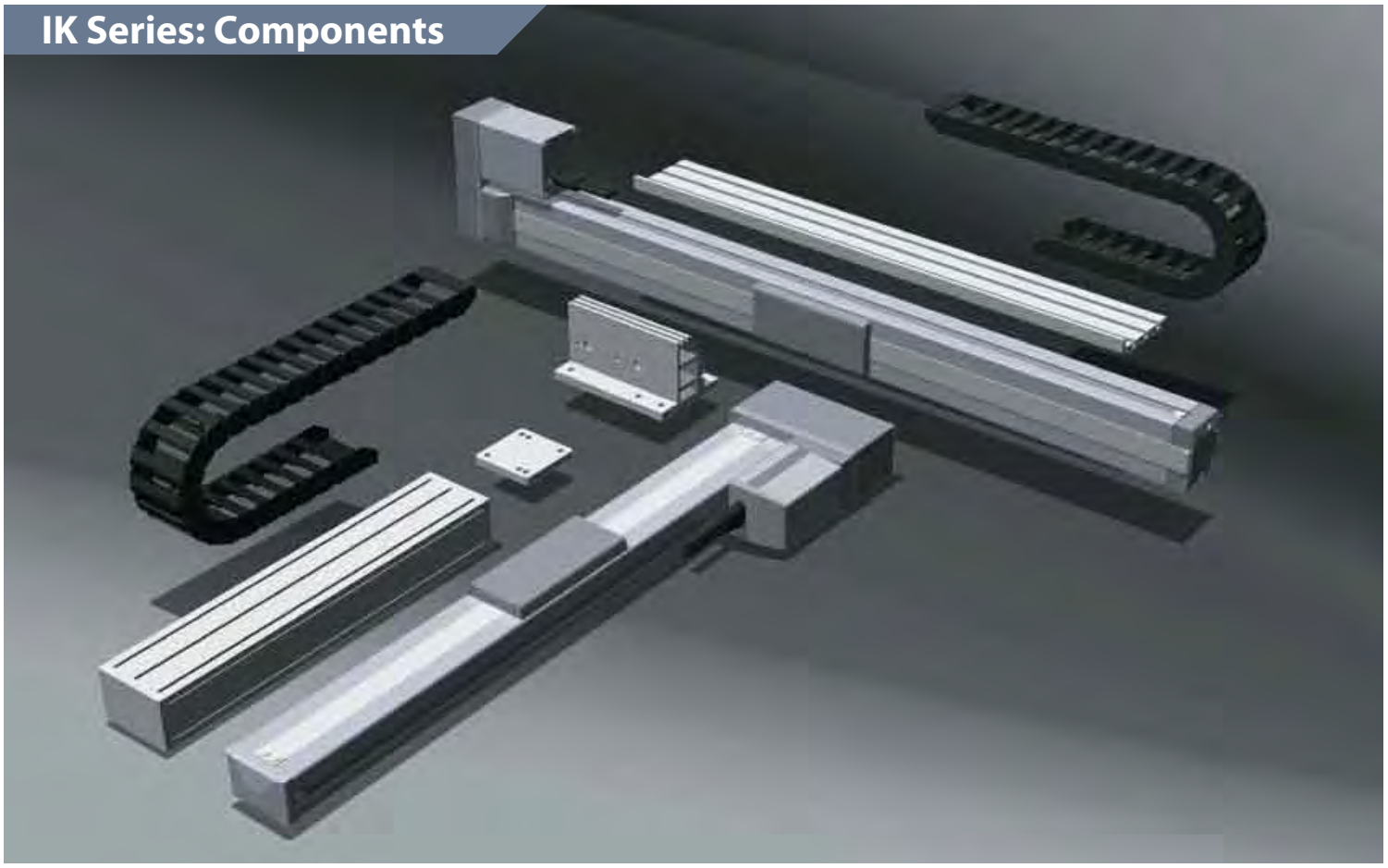
IAI
Quality and Innovation

ROBO CYLINDER

ROBO Cylinder
IK Series Catalog

ROBO Cylinder IK Series

IK Series: Components



1. Wide Variation

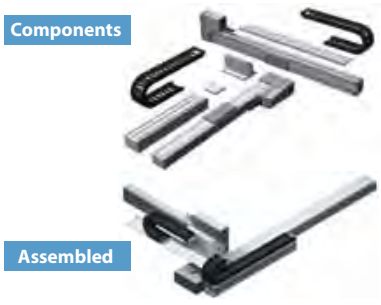
The engineers at IAI have worked extensively to produce the highest quality products at affordable prices. The new IK Series lineup offers many variations and can be easily integrated and prepared to your specific needs.

2. Motor Options

The IK Series is offered in both pulse and servo motors. Choose the pulse motor for applications requiring high thrust at low speeds. Choose the servo motor for applications requiring constant thrust regardless of the operating speed.

3. Easy Assembly

The ROBO Cylinder IK Series multi-axes kit includes everything needed for fast and easy assembly.



Multi-Axes Systems

IK Series: Assembled

4. High Functionality

Combined with the PCON/PSEL/SCON/SSEL/XSEL controllers, complex programming is made easy.

5. Quality and Innovation

We at IAI are always working to offer high quality and innovative solutions tailored for your specific application. Whenever you need support, IAI's experienced teams of technical support engineers are available to help you diagnose and troubleshoot IAI products. When you require innovative and high quality robots, excellent service and support for your unique needs, demand IAI!

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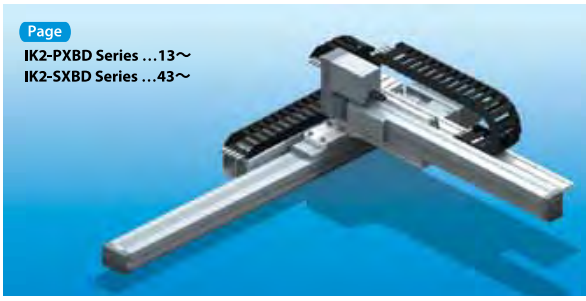
Wide-ranging Lineup
Lineup of IK Series

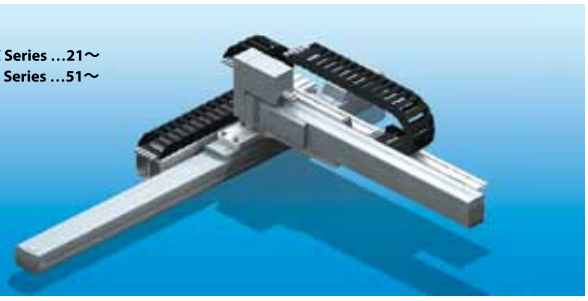
Combinations

XYB (XY, base mount)

Page
IK2-PXBD Series ...13〜
IK2-SXBD Series ...43〜



Page
IK2-PXBC Series ...21〜
IK2-SXBC Series ...51〜



• IK2-PXBD Series • IK2-SXBD Series

		Maximum X-axis stroke	Maximum Y-axis stroke	Load capacity at maximum Y-axis stroke
Single-slider	Y high-speed type	600mm	200mm	2.5kg
	Y medium-speed type	600mm	200mm	5.0kg
Double-slider	Y high-speed type	450mm	400mm	2.0kg
	Y medium-speed type	450mm	400mm	4.0kg

• IK2-PXBC Series • IK2-SXBC Series

		Maximum X-axis stroke	Maximum Y-axis stroke	Load capacity at maximum Y-axis stroke
Single-slider	Y high-speed type	600mm	200mm	3.0kg
	Y medium-speed type	600mm	200mm	6.0kg
Double-slider	Y high-speed type	450mm	400mm	3.0kg
	Y medium-speed type	450mm	400mm	6.0kg

XZ (Upright type)

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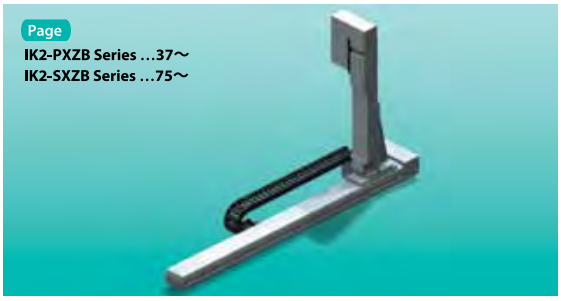
IK2-PXZB Series ...37〜
IK2-SXZB Series ...75〜



• IK2-PXZB Series • IK2-SXZB Series

		Maximum X-axis stroke	Maximum Z-axis stroke	Load capacity at maximum Y-axis stroke
Single-slider	X high-speed/Z high-speed type	1,000mm	250mm	1.5kg
	X high-speed/Z medium-speed type	1,000mm	250mm	2.5kg
	X high-speed/Z low-speed type	1,000mm	250mm	3.0kg
Double-slider	X high-speed/Z high-speed type	800mm	300mm	1.5kg
	X high-speed/Z medium-speed type	800mm	300mm	3.0kg
	X high-speed/Z low-speed type	800mm	300mm	5.5kg

YZB (Cross type, base mount)

Page
IK2-PYBB Series ...41〜
IK2-SYBB Series ...79〜

• IK2-PYBB Series • IK2-SYBB Series

		Maximum X-axis stroke	Maximum Z-axis stroke	Load capacity at maximum Y-axis stroke
Single-slider	X high-speed/Z high-speed type	1,000mm	300mm	1.5kg
	X high-speed/Z medium-speed type	1,000mm	300mm	3.0kg
	X high-speed/Z low-speed type	1,000mm	300mm	5.5kg

IK2-P Series / IK3-P Series	ROBO Cylinder RCP2 combinations based on pulse motor
IK2-S Series / IK3-S Series	ROBO Cylinder RCS2 combinations based on servo motor

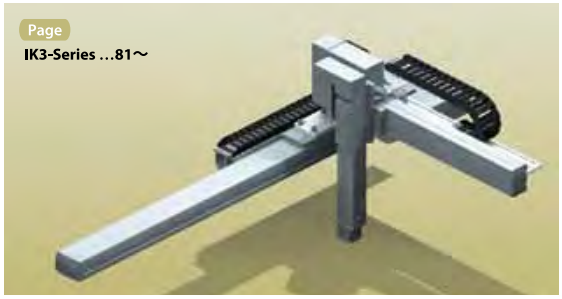
• IK2-PXBB Series • IK2-SXBB Series

		Maximum X-axis stroke	Maximum Y-axis stroke	Load capacity at maximum Y-axis stroke
Single-slider	High-speed type	1,000mm	300mm	6.0kg
	Medium-speed type	1,000mm	300mm	8.0kg
Double-slider	High-speed type	800mm	400mm	5.5kg
	Medium-speed type	800mm	400mm	10.5kg

• IK2-SXBA Series

		Maximum X-axis stroke	Maximum Y-axis stroke	Load capacity at maximum Y-axis stroke
Single-slider	High-speed type	1,000mm	350mm	7.0kg
	Medium-speed type	1,000mm	200mm	12.5kg
Double-slider	High-speed type	800mm	400mm	10.0kg
	Medium-speed type	800mm	400mm	11.5kg

3-axis type (XYB+Z, base mount)



• IK3 Series

		Maximum X-axis stroke	Maximum Y-axis stroke	Maximum Z-axis stroke	Load capacity at maximum Y-axis stroke
Single-slider	X high-speed/Y high-speed/Z high-speed type	1,000mm	300mm	200mm	1.0kg
	X high-speed/Y high-speed/Z medium-speed type	1,000mm	300mm	200mm	2.0kg
	X high-speed/Y high-speed/Z low-speed type	1,000mm	300mm	200mm	4.0kg
Double-slider	X high-speed/Y high-speed/Z high-speed type	800mm	400mm	200mm	1.0kg
	X high-speed/Y high-speed/Z medium-speed type	800mm	400mm	200mm	2.0kg
	X high-speed/Y high-speed/Z low-speed type	800mm	400mm	200mm	4.0kg

2-axis combination – Axis configurations

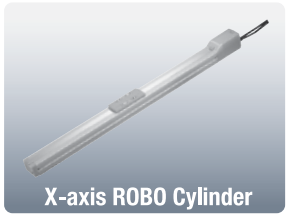
	Axis 1	Axis 2
IK2-PXBD IK2-SXBD	RCP2-SS7☐ RCS2-SS7☐	RCP2-SA5R RCS2-SA5R
IK2-PXBC IK2-SXBC	RCP2-SS7☐ RCS2-SS7☐	RCP2-SA6R RCS2-SA6R
IK2-PXBB IK2-SXBB	RCP2-SS8☐ RCS2-SS8☐ (100W)	RCP2-SA7R RCS2-SA7R
IK2-SXBA	RCS2-SS8☐ (150W)	RCS2-SS8R (100W)
IK2-PXZB IK2-SXZB	RCP2-SS8☐ RCS2-SS8☐ (100W)	RCP2-SA7R RCS2-SA7R
IK2-PYBB IK2-SYBB	RCP2-SS8☐ RCS2-SS8☐ (100W)	RCP2-SA7R RCS2-SA7R

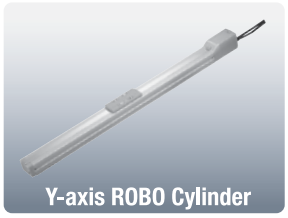
3-axis combination – Axis configurations

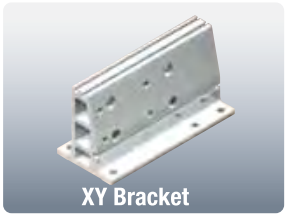
	X axis	Y axis	Z axis
IK3	RCP2-SS8☐ RCS2-SS8☐ (100W)	RCP2-SA7R RCS2-SA7R	RCP2-SA6R RCS2-SA6R

IK Series

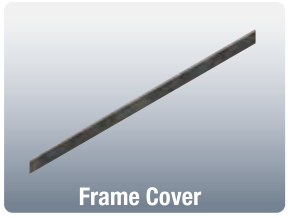
The IK Series is a set that includes the following components needed to assemble the cartesian robot.


X-axis ROBO Cylinder

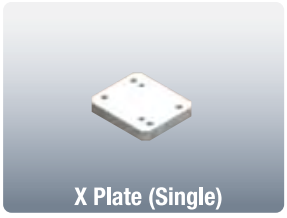

Y-axis ROBO Cylinder

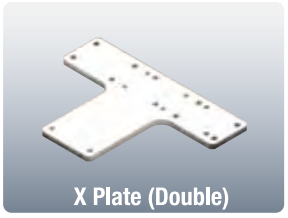

XY Bracket


X Guide Rail

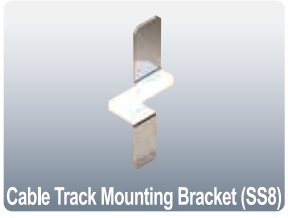

Frame Cover

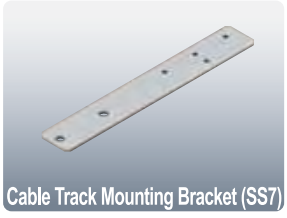

Y Guide Rail

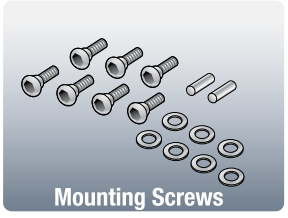

X Plate (Single)


X Plate (Double)

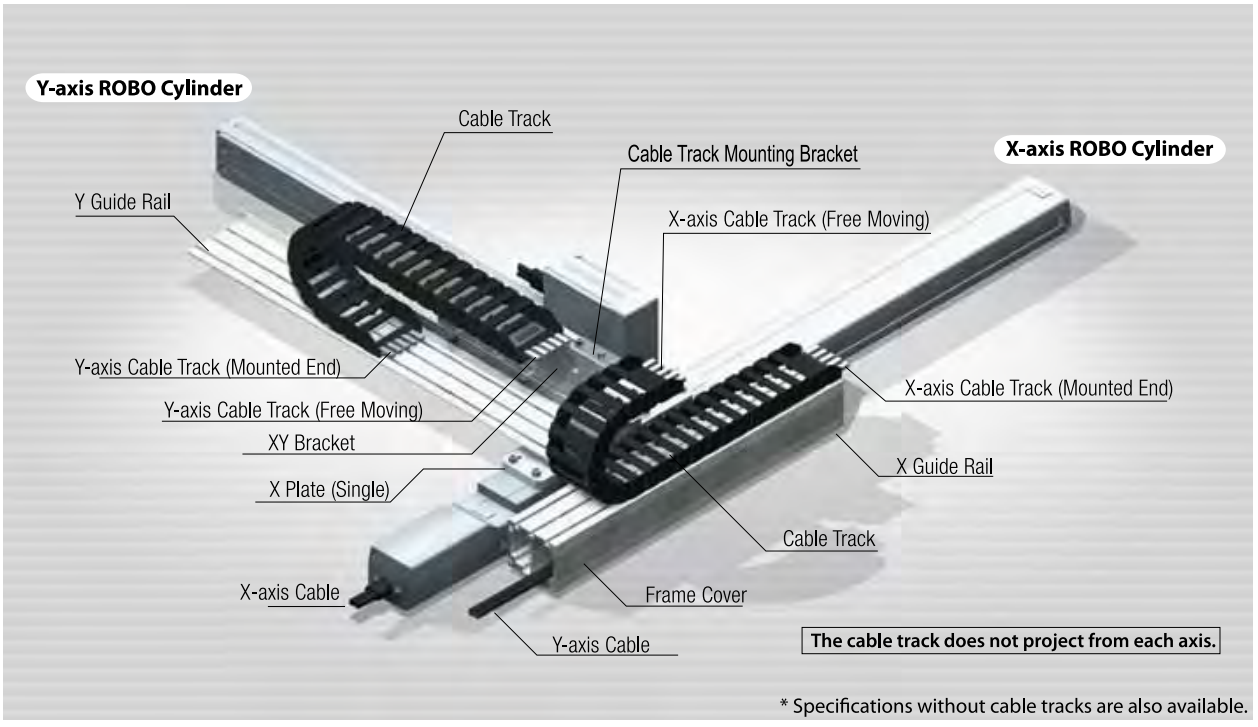

Cable Track


Cable Track Mounting Bracket (SS8)


Cable Track Mounting Bracket (SS7)


Mounting Screws

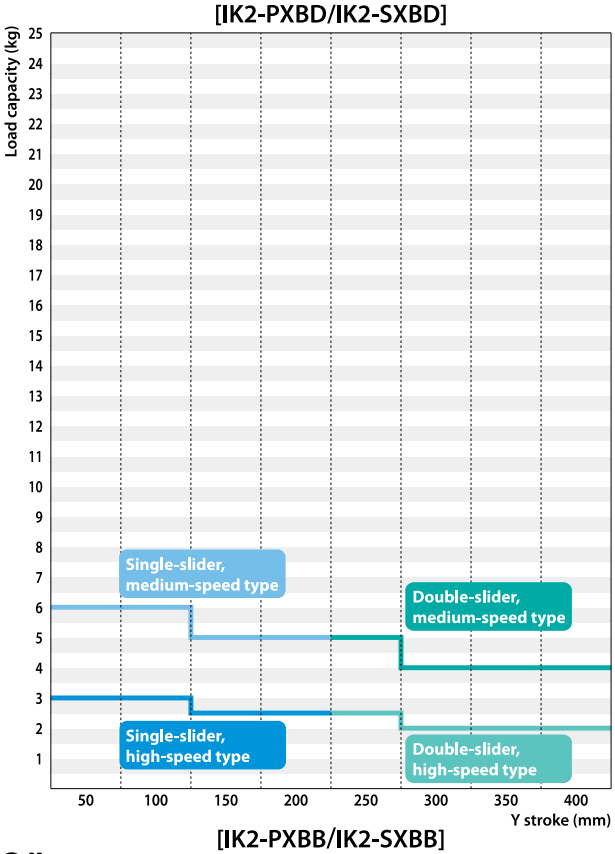
Note: The above images are provided for reference purposes only.
The actual components may vary depending on the combination type, direction, etc.



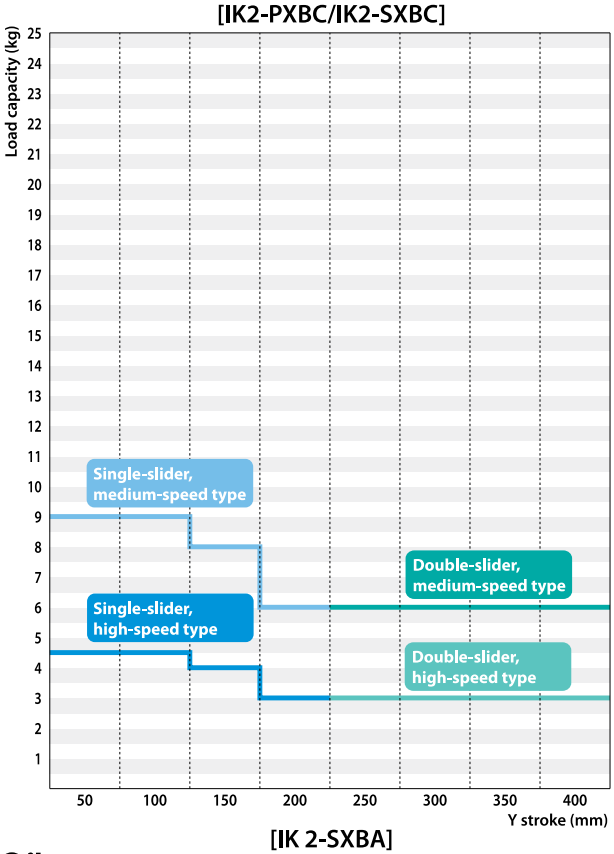
* Specifications without cable tracks are also available.

Load Capacity Graphs for XYB Combinations

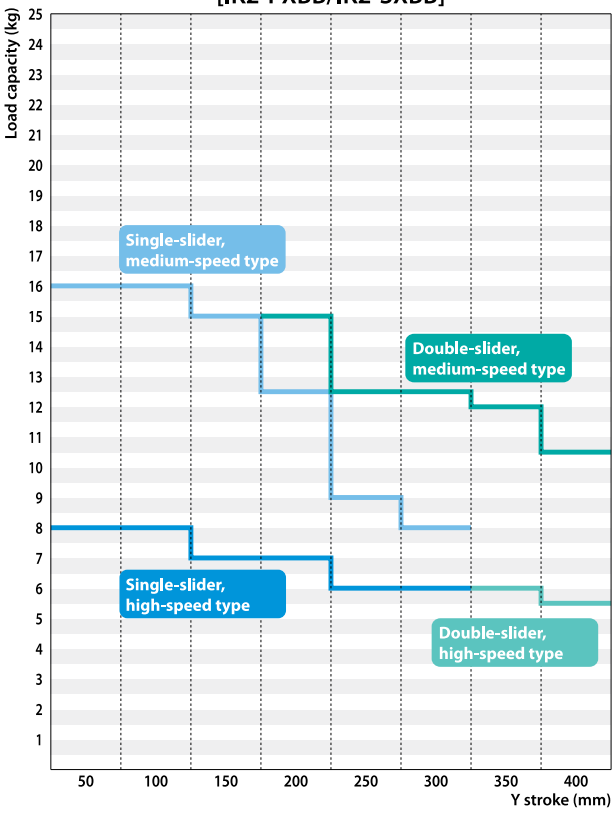
[IK2-PXBD/IK2-SXBD]



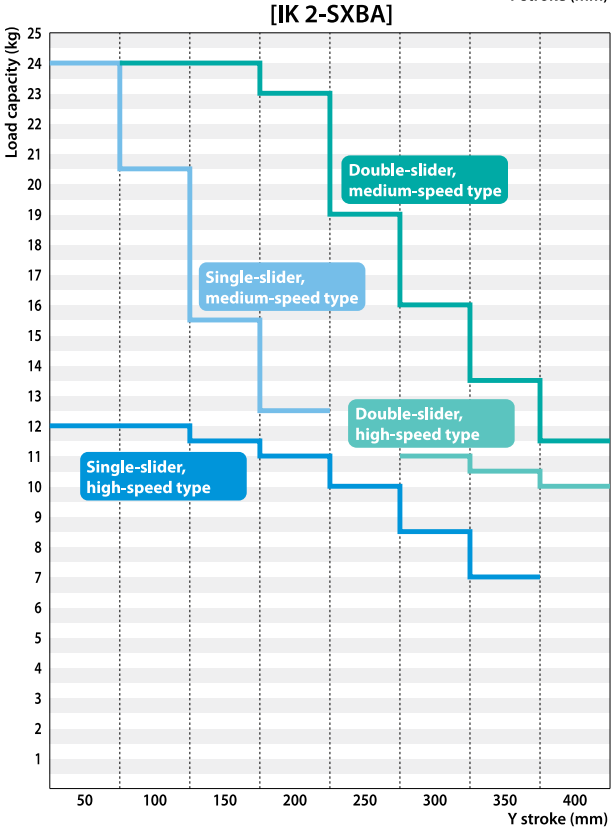
[IK2-PXBC/IK2-SXBC]



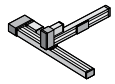
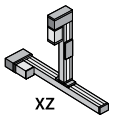
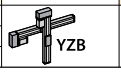
[IK2-PXBB/IK2-SXBB]



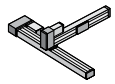
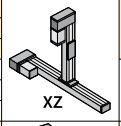
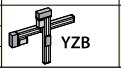
[IK 2-SXBA]



RCP2 Combination Unit List for 2-axis Configuration (XYB) (☐ in the model names indicates a value from 1 to 4 specifying the combination direction. For the combination directions, refer to P. 10.)

Page	Combination model	Combined shape	Axis 1 Type	Axis 1 Motor size	Axis 1 Lead (mm)	Axis 1 Maximum speed (mm/sec)	Axis 1 Stroke (mm)	Axis 2 Type
13	IK2-PXBD1☐HHS	 XYB	SS7R Reversed	42☐	12	400	50–600	SA5R Reversed
	IK2-PXBD1☐HMS				12	350		
15	IK2-PXBD1☐HHD		SS7R Reversed, double-slider		12	400	50–450	
	IK2-PXBD1☐HMD				12	350		
17	IK2-PXBD2☐HHS		SS7C Straight		12	400	50–600	
	IK2-PXBD2☐HMS				12	350		
19	IK2-PXBD2☐HHD		SS7C Straight, double-slider		12	400	50–450	
	IK2-PXBD2☐HMD				12	350		
21	IK2-PXBC1☐HHS		SS7R Reversed		12	400	50–600	SA6R Reversed
	IK2-PXBC1☐HMS				12	250		
23	IK2-PXBC1☐HHD		SS7R Reversed, double-slider		12	400	50–450	
	IK2-PXBC1☐HMD				12	250		
25	IK2-PXBC2☐HHS		SS7C Straight		12	400	50–600	
	IK2-PXBC2☐HMS				12	250		
27	IK2-PXBC2☐HHD		SS7C Straight, double-slider		12	400	50–450	
	IK2-PXBC2☐HMD				12	250		
29	IK2-PXBB1☐HHS		SS8R Reversed	56☐	20	250	50–1000	SA7R Reversed
	IK2-PXBB1☐MMS				10	125		
31	IK2-PXBB1☐HHD		SS8R Reversed, double-slider		20	250	50–800	
	IK2-PXBB1☐MMD				10	125		
33	IK2-PXBB2☐HHS		SS8C Straight		20	250	50–1000	
	IK2-PXBB2☐MMS				10	125		
35	IK2-PXBB2☐HHD		SS8C Straight, double-slider		20	250	50–800	
	IK2-PXBB2☐MMD				10	125		
37	IK2-PXZB1☐HHS	 XZ	SS8R Reversed	56☐	20	250	50–1000	SA7R Reversed
	IK2-PXZB1☐HMS							
	IK2-PXZB1☐HLS							
39	IK2-PXZB1☐HHD		SS8R Reversed, double-slider				50–800	
	IK2-PXZB1☐HMD							
	IK2-PXZB1☐HLD							
41	IK2-PYBB1☐HHS	 YZB	SS8R Reversed				50–1000	
	IK2-PYBB1☐HMS							
	IK2-PYBB1☐HLS							

RCS2 Combination Unit List for 2-axis Configuration (XYB) (☐ in the model names indicates a value from 1 to 4 specifying the combination direction. For the combination directions, refer to P. 10.)

Page	Combination model	Combined shape	Axis 1 Type	Axis 1 Motor output (W)	Axis 1 Lead (mm)	Axis 1 Maximum speed (mm/sec)	Axis 1 Stroke (mm)	Axis 2 Type
43	IK2-SXBD1☐HHS	 XYB	SS7R Reversed	60	12	600	50–600	SA5R Reversed
	IK2-SXBD1☐HMS				12	600		
45	IK2-SXBD1☐HHD		SS7R Reversed, double-slider		12	600	50–450	
	IK2-SXBD1☐HMD				12	600		
47	IK2-SXBD2☐HHS		SS7C Straight		12	600	50–600	
	IK2-SXBD2☐HMS				12	600		
49	IK2-SXBD2☐HHD		SS7C Straight, double-slider		12	600	50–450	
	IK2-SXBD2☐HMD				12	600		
51	IK2-SXBC1☐HHS		SS7R Reversed		12	600	50–600	SA6R Reversed
	IK2-SXBC1☐MMS				6	300		
53	IK2-SXBC1☐HHD		SS7R Reversed, double-slider		12	600	50–450	
	IK2-SXBC1☐MMD				6	300		
55	IK2-SXBC2☐HHS		SS7C Straight		12	600	50–600	
	IK2-SXBC2☐MMS				6	300		
57	IK2-SXBC2☐HHD		SS7C Straight, double-slider		12	600	50–450	
	IK2-SXBC2☐MMD				6	300		
59	IK2-SXBB1☐HHS		SS8R (100W) Reversed	100	20	1000	50–1000	SA7R Reversed
	IK2-SXBB1☐MMS				10	500		
61	IK2-SXBB1☐HHD		SS8R (100W) Reversed, double-slider		20	1000	50–800	
	IK2-SXBB1☐MMD				10	500		
63	IK2-SXBB2☐HHS		SS8C (100W) Straight		20	1000	50–1000	
	IK2-SXBB2☐MMS				10	500		
65	IK2-SXBB2☐HHD		SS8C (100W) Straight, double-slider		20	1000	50–800	
	IK2-SXBB2☐MMD				10	500		
67	IK2-SXBA1☐HHS		SS8R (150W) Reversed	150	20	1000	50–1000	SS8R (100W) Reversed
	IK2-SXBA1☐MMS				10	500		
69	IK2-SXBA1☐HHD		SS8R (150W) Reversed, double-slider		20	1000	50–800	
	IK2-SXBA1☐MMD				10	500		
71	IK2-SXBA2☐HHS		SS8C (150W) Straight		20	1000	50–1000	
	IK2-SXBA2☐MMS				10	500		
73	IK2-SXBA2☐HHD		SS8C (150W) Straight, double-slider		20	1000	50–800	
	IK2-SXBA2☐MMD				10	500		
75	IK2-SXZB1☐HHS	 XZ	SS8R (100W) Reversed	100	20	1000	50–1000	SA7R Reversed
	IK2-SXZB1☐HMS							
	IK2-SXZB1☐HLS							
77	IK2-SXZB1☐HHD		SS8R (100W) Reversed, double-slider				50–800	
	IK2-SXZB1☐HMD							
	IK2-SXZB1☐HLD							
79	IK2-SYBB1☐HHS	 YZB	SS8R (100W) Reversed				50–1000	
	IK2-SYBB1☐HMS							
	IK2-SYBB1☐HLS							

Axis 2					Load capacity by axis 2 stroke							
	Motor size	Lead (mm)	Maximum speed (mm/sec)	Stroke (mm)	50	100	150	200	250	300	350	400
		12	600	50–200	3.0	3.0	2.5	2.5				
		6	300	50–200	6.0	6.0	5.0	5.0				
		12	600	250–400					2.5	2.0	2.0	2.0
		6	300	250–400					5.0	4.0	4.0	4.0
	42□	12	600	50–200	3.0	3.0	2.5	2.5				
		6	300	50–200	6.0	6.0	5.0	5.0				
		12	600	250–400					2.5	2.0	2.0	2.0
		6	300	250–400					5.0	4.0	4.0	4.0
		12	600	50–200	4.5	4.5	4.0	3.0				
		6	300	50–200	9.0	9.0	8.0	6.0				
		12	600	250–400					3.0	3.0	3.0	3.0
		6	300	250–400					6.0	6.0	6.0	6.0
	42□	12	600	50–200	4.5	4.5	4.0	3.0				
		6	300	50–200	9.0	9.0	8.0	6.0				
		12	600	250–400					3.0	3.0	3.0	3.0
		6	300	250–400					6.0	6.0	6.0	6.0
		16	450	50–300	8.0	8.0	7.0	7.0	6.0	6.0		
		8	220	50–300	16.0	16.0	15.0	12.5	9.0	8.0		
		16	450	350–400							6.0	5.5
	56□	8	220	200–400				15.0	12.5	12.5	12.0	10.5
		16	450	50–300	8.0	8.0	7.0	7.0	6.0	6.0		
		8	220	50–300	16.0	16.0	15.0	12.5	9.0	8.0		
		16	450	350–400							6.0	5.5
		8	220	200–400				15.0	12.5	12.5	12.0	10.5
		16	360	50–250	2.0	2.0	2.0	2.0	1.5			
		8	180	50–250	4.0	4.0	3.5	3.5	2.5			
		4	90	50–250	8.0	7.0	5.0	4.0	3.0			
		16	400	300						1.5		
	56□	8	200	300						3.0		
		4	100	150–300			7.0	7.0	5.5	5.5		
		16	360	50–300	2.0	2.0	2.0	2.0	1.5	1.5		
		8	180	50–300	4.0	4.0	3.5	3.5	3.0	3.0		
		4	90	50–300	8.0	8.0	7.0	7.0	6.0	5.5		

Axis 2					Load capacity by axis 2 stroke							
	Motor output (W)	Lead (mm)	Maximum speed (mm/sec)	Stroke (mm)	50	100	150	200	250	300	350	400
		12	800	50–200	3.0	3.0	2.5	2.5				
		6	400		6.0	6.0	5.0	5.0				
		12	800	250–400					2.5	2.0	2.0	2.0
	20	6	400						5.0	4.0	4.0	4.0
		12	800	50–200	3.0	3.0	2.5	2.5				
		6	400		6.0	6.0	5.0	5.0				
		12	800	250–400					2.5	2.0	2.0	2.0
		6	400						5.0	4.0	4.0	4.0
		12	800	50–200	4.5	4.5	4.0	3.0				
		6	400		9.0	9.0	8.0	6.0				
		12	800	250–400					3.0	3.0	3.0	3.0
	30	6	400						6.0	6.0	6.0	6.0
		12	800	50–200	4.5	4.5	4.0	3.0				
		6	400		9.0	9.0	8.0	6.0				
		12	800	250–400					3.0	3.0	3.0	3.0
		6	400						6.0	6.0	6.0	6.0
		16	800	50–300	8.0	8.0	7.0	7.0	6.0	6.0		
		8	400		16.0	16.0	15.0	12.5	9.0	8.0		
		16	800	350–400							6.0	5.5
	60	8	400	200–400				15.0	12.5	12.5	12.0	10.5
		16	800	50–300	8.0	8.0	7.0	7.0	6.0	6.0		
		8	400		16.0	16.0	15.0	12.5	9.0	8.0		
		16	800	350–400							6.0	5.5
		8	400	200–400				15.0	12.5	12.5	12.0	10.5
		20	1000	50–350	12.0	12.0	11.5	11.0	10.0	8.5	7.0	
		10	500		24.0	20.5	15.5	12.5				
		20	1000	300–400						11.0	10.5	10.0
	100	10	500	100–400		24.0	24.0	23.0	19.0	16.0	13.5	11.5
		20	1000	50–350	12.0	12.0	11.5	11.0	10.0	8.5	7.0	
		10	500		24.0	20.5	15.5	12.5				
		20	1000	300–400						11.0	10.5	10.0
		10	500	100–400		24.0	24.0	23.0	19.0	16.0	13.5	11.5
		16	800	50–250	2.0	2.0	2.0	2.0	1.5			
		8	400		4.0	4.0	3.5	3.5	2.5			
		4	200		8.0	7.0	5.0	4.0	3.0			
		16	800	300						1.5		
	60	8	400							3.0		
		4	200	150–300			7.0	7.0	5.5	5.5		
		16	800	50–300	2.0	2.0	2.0	2.0	1.5	1.5		
		8	400		4.0	4.0	3.5	3.5	3.0	3.0		
		4	200		8.0	8.0	7.0	7.0	6.0	5.5		

RCP2 Combination Unit List for 3-axis Configuration (XYB+Z-axes, base mount) (☐ in the model names indicates a value from 1 to 4 specifying the combination direction. For the combination directions, refer to P. 10.)

Page	Combination model	Combined shape	X axis					Y axis
			Type	Motor size	Lead (mm)	Maximum speed (mm/sec)	Stroke (mm)	Type
81	IK3-PBBG1☐HHHS	XYB+Z, base mount	SS8R Reversed, single-slider	56☐	20	220	50–1000	SA7R Reversed
	IK3-PBBG1☐HHMS							
	IK3-PBBG1☐HHLS							
83	IK3-PBBG1☐HHHD		SS8R Reversed, double-slider				50–800	
	IK3-PBBG1☐HHMD							
	IK3-PBBG1☐HHLD							

RCS2 Combination Unit List for 3-axis Configuration (XYB+Z-axes, base mount) (☐ in the model names indicates a value from 1 to 4 specifying the combination direction. For the combination directions, refer to P. 10.)

Page	Combination model	Combined shape	X axis					Y axis
			Type	Motor output (W)	Lead (mm)	Maximum speed (mm/sec)	Stroke (mm)	Type
85	IK3-SBBG1☐HHHS	XYB+Z, base mount	SS8R (100W) Reversed, single-slider	100	20	1000	50–1000	SA7R Reversed
	IK3-SBBG1☐HHMS							
	IK3-SBBG1☐HHLS							
88	IK3-SBBG1☐HHHD		SS8R (100W) Reversed, double-slider				50–800	
	IK3-SBBG1☐HHMD							
	IK3-SBBG1☐HHLD							

Tips on Selection

1. Differences between RCP2 and RCS2

Features of RCP2

[1] Adopting a pulse motor.

[2] Characterized by high thrust at low speed.

[3] Less expensive than the RCS2.

Features of RCS2

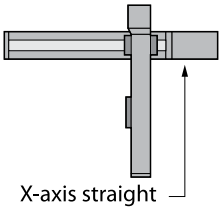
[1] Adopting a servo motor.

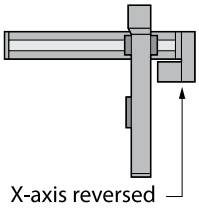
[2] Able to operate at a constant thrust regardless of the speed.

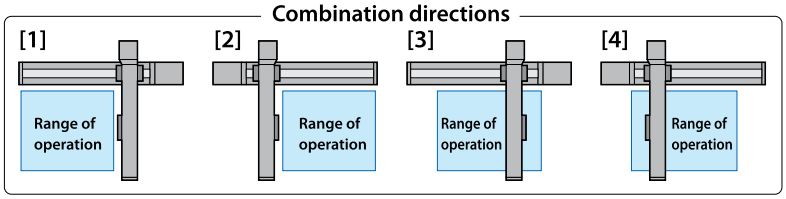
[3] Able to move at higher speeds than the RCP2.

2. Differences between X-axis Straight and Reversed Types

The X-axis reversed type can have a shorter dimension in the X-axis direction. When the 150-watt RCS2-SS8C (straight) and 150-watt SS8R (reversed) are compared, for example, the SS8R is shorter by 130 mm. Note, however, that the reversed type does not support configurations based on combination directions [3] and [4].

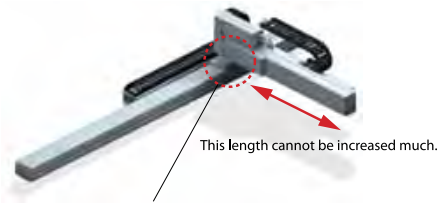


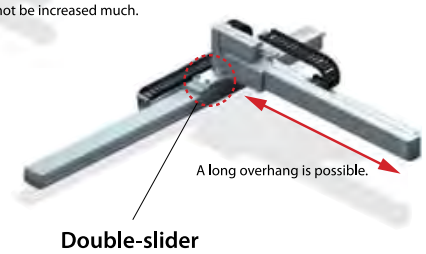




3. Differences between Single-slider and Double-slider Types

A double-slider consists of two sliders connected to each other and has a greater permissible load moment compared to a single-slider type. Accordingly, double-slider units are used as the X-axis in XY configurations with a long overhang.
Note, however, that because the double-slider structure naturally has a longer slider section, a double-slider unit has a shorter stroke than a single-slider unit of the same total length.





Y axis				Z axis					Load capacity by Y-axis stroke							
Motor size	Lead (mm)	Maximum speed (mm/sec)	Stroke (mm)	Type	Motor size	Lead (mm)	Maximum speed (mm/sec)	Stroke (mm)	50	100	150	200	250	300	350	400
56□	16	420	50–300	SA6R Reversed	42□	12	500	50–200	1.0							
						6	250		2.0							
						3	125		4.0							
			350–400			12	500								1.0	
						6	250								2.0	
						3	125								4.0	

Y axis				Z axis					Load capacity by Y-axis stroke							
Motor output (W)	Lead (mm)	Maximum speed (mm/sec)	Stroke (mm)	Type	Motor output (W)	Lead (mm)	Maximum speed (mm/sec)	Stroke (mm)	50	100	150	200	250	300	350	400
60	16	800	50–300	SA6R Reversed	30	12	800	50–200	1.0							
						6	400		2.0							
						3	200		4.0							
			350–400			12	800								1.0	
						6	400								2.0	
						3	200								4.0	

Explanation of Items Comprising Model Name

[IK Series, 2-axis combination unit]

IK2–□□□□□□–□–□□–□□–□□–□–□–□–□

[1] [2] [3] [4] [5] [6] [7] [8] [9] [10] [11] [14] [15] [16] [17] [18]

[IK Series, 3-axis combination unit]

IK3–□□□□□□–□–□□–□□–□□–□□–□–□–□–□

[1] [2] [3] [4] [5] [6] [7] [8] [9] [10] [11] [12] [13] [14] [15] [16] [17] [18]

[1]Axis configuration

Code	Model
P	RCP2
S	RCS2

[2]Combined shape

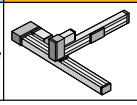
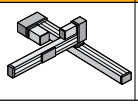
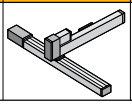
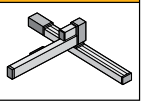
Code	Combined shape	Name
XB	XYB	XY, base mount
XZ	XZ	Upright type
YB	YZB	Cross type, base mount
BB	XYB+ZB	XYB+Z, base mount

[3]Configuration type

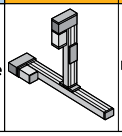
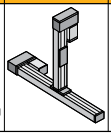
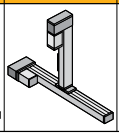
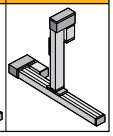
Code	Axis 1	Axis 2	Axis 3
A1	SS8R (150W)	SS8R (100W)	
A2	SS8C (150W)	SS8R (100W)	
B1	SS8R (100W)	SA7R	
B2	SS8C (100W)	SA7R	
C1	SS7R	SA6R	
C2	SS7C	SA6R	
D1	SS7R	SA5R	
D2	SS7C	SA5R	
G1	SS8R (100W)	SA7R	SA6R

[4]Combination directions

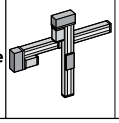
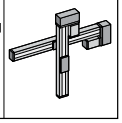
XYB (XY, base mount) *Only 1 and 2 are supported if the X-axis is of reversed type.

Code	1	2	3	4
Shape				

XZ (Upright type)

Code	1	2	3	4
Shape				

YZB (Cross type, base mount)

Code	1	2
Shape		

The combination directions supported by the 3-axis configuration (XYB+Z-axes, base mount) are the same as those of the XYB configuration shown above.

[5]Speed type

Code	Type		
HH	High-speed	High-speed	
HM	High-speed	Medium-speed	
HL	High-speed	Low-speed	
MM	Medium-speed	Medium-speed	
HHH	High-speed	High-speed	High-speed
HHM	High-speed	High-speed	Medium-speed
HHL	High-speed	High-speed	Low-speed

[6]X-Axis Slider Type

Code	Type
S	Single
D	Double

[7]Encoder Type

Code	Type
I	Incremental
A	Absolute

[8]Axis 1 stroke (cm)

5:50mm–100:1000mm
(Can be set in 50-mm increments)

[10]Axis 2 stroke (cm)

5:50mm–40:400mm
(Can be set in 50-mm increments)

[12]Axis 3 stroke (cm)

5:50mm–20:200mm
(Can be set in 50-mm increments)

[9]Axis 1 options

Code	Description
NM	Reversed-home specification
SR	Slider roller specification

[11]Axis 2 options

Code	Description
B	Brake
NM	Reversed-home specification
SR	Slider roller specification

[13]Axis 3 options

Code	Description
B	Brake
NM	Reversed-home specification
SR	Slider roller specification

Axis 1: Mount axis
Axis 2: Axis installed on axis 1
Axis 3: Axis 3: Axis installed on axis 2
Cable wiring 1: Wiring for axis 2
Cable wiring 2: Wiring for axis 3

[14]Applicable controller

Code	Model
T1	XSEL-J/K
T2	SSEL, XSEL-P/Q
P1	PSEL, ROBONET

[15]Cable length

Code	Description
1L	1m
3L	3m
5L	5m
□L	□m

[16]Cable wiring 1

Code	Description
N	Cable only
CT	With cable track

[17]Cable wiring 2

Code	Description
N	Cable only
CT	With cable track

[18]Shipping configuration

Code	Description
K	Individual components (kit)

Controller List

The IA kit supports the following controllers. For details on each controller, refer to the reference page describing the applicable controller.

	Exterior view	Features	Maximum number of positioning points	Input power supply	Reference page
PCON		A positioning controller for the RCP2 series. Pulse-train control and serial communication types are also available.	512	DC24V	Refer to the ROBO Cylinder General Catalog
PSEL		A program controller for the RCP2 series. Can be programmed using SEL language. 1-axis and 2-axis types are available.	1500	DC24V	P. 93
SCON		A positioning controller for the RCS2 series. Field networks are supported.	512	100 VAC Single-phase 200 VAC	Refer to the ROBO Cylinder General Catalog
SSEL		A program controller for the RCS2 series. Can be programmed using SEL language. 1-axis and 2-axis types are available.	1500	100 VAC Single-phase 200 VAC	P. 93
ROBONET		Able to operate 1 to 16 ROBO Cylinder axes via a field network. Less hassle of wiring and installation.	768	DC24V	P. 93
XSEL-J/K		For the RCS2 series. 3-axis and 4-axis configurations are supported. Two sets of 2-axis combination systems can be controlled. J type: Small size K type: Provides greater expandability because I/Os can be used.	3000	100 VAC Single-phase 200 VAC	P. 93
XSEL-P/Q		For the RCS2 series. 5-axis and 6-axis configurations are supported.	4000	Three-phase 200 VAC	P. 93

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IAI has been certified for ISO 9001:2000 and JIS Q9001:2000 by an independent auditor to be in conformance with ISO 9001:2000 and JIS 9001:2000. We at IAI are continually improving our methods to produce quality products and services that surpass customer expectations.

RoHS Compliant
IAI is RoHS compliant and recognizes the responsibility in reducing hazardous substances to better serve our customers and our environment.

RoHS

IK2-PXBD1□□S

RCP2 2-axis Combinations X axis: SS7R (Reversed, Single-slider)
Y axis: SA5R (Reversed)

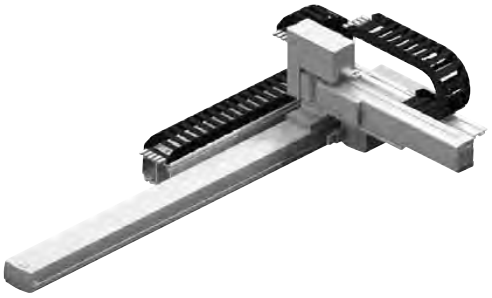
■Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllers — Cable — Shipping configuration

IK2 — PXBD1□□S — □ — □ □ — □ □ — P1 — □ — □ — □ — □

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; HM: X high-speed, Y medium-speed
- Encoder type: I: Incremental
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; Wiring 2: CT: With cable track
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

■Maximum Stroke

X axis 600 mm　Y axis 200 mm

■Maximum Speed (High-speed type)

X axis 400 mm/s　Y axis 600 mm/s

■Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X high-speed, Y medium-speed
50mm	3.0kg	6.0kg
100mm	3.0kg	6.0kg
150mm	2.5kg	5.0kg
200mm	2.5kg	5.0kg

List of Options

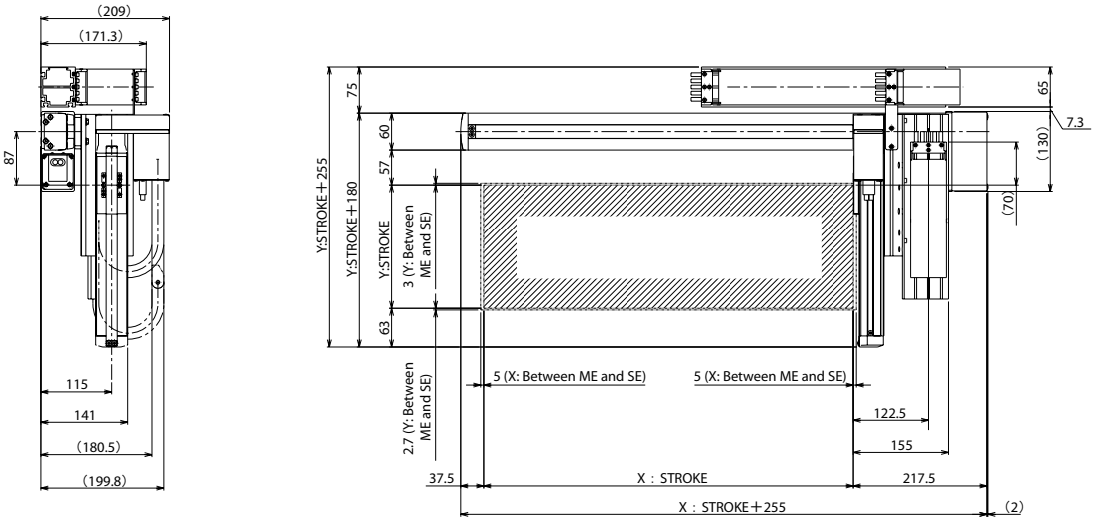
Name	Option code
Opposite-home specification	NM
Slider roller specification	SR

Specifications

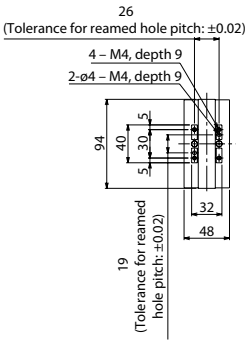
Item	X axis	Y axis
Axis model	RCP2-SS7R	RCP2-SA5R
Stroke (Can be set in 50-mm increments)	50-600mm	50-200mm
Max speed	HH type: 400mm/s HM type: 350mm/s	High-speed type: 600mm/s Medium-speed type: 300mm/s
Motor size	42-square pulse motor	
Ball screw lead	High-speed type: 12mm	High-speed type: 12mm Medium-speed type: 6mm
Drive method	Ball screw, ø10 mm, rolled, C10	
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

Dimensions

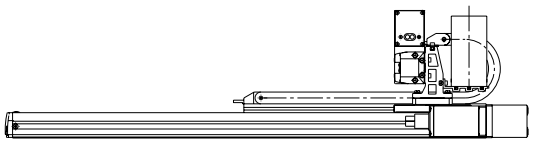
Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.



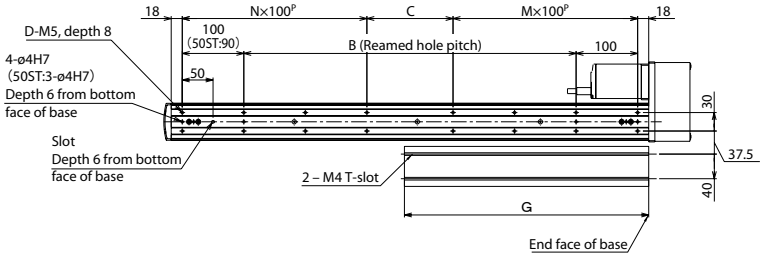
ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider



Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Model	50	100	150	200	250	300	350	400	450	500	550	600
B	0	40	90	140	190	240	290	340	390	440	490	540
C	90	40	90	140	190	40	90	140	190	40	90	140
D	6	8	8	8	8	12	12	12	12	16	16	16
M	1	1	1	1	1	2	2	2	2	3	3	3
N	0	1	1	1	1	2	2	2	2	3	3	3
G	122	147	172	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-PXBD1□□D

RCP2 2-axis Combinations X axis: SS7R (Reversed, Double-slider)
Y axis: SA5R (Reversed)

■Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllers — Cable — Shipping configuration

IK2 — PXBD1□□D — □ — □ □ — □ □ — P1 — □ — □ — □ — □

Combination directions
1-2

Differences between Single-slider and Double-slider Types
HH: X high-speed, Y high-speed
HM: X high-speed, Y medium-speed

Encoder type
I: Incremental

Stroke (mm)
5: 50mm
≀
(Can be set in 50-mm increments)

Options
NM: Opposite-home specification
SR: Slider roller specification

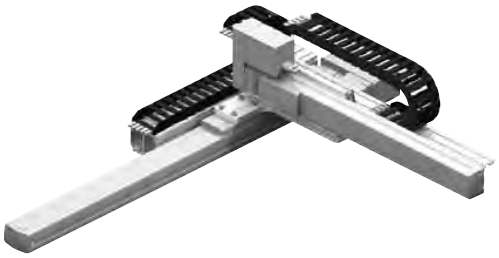
Cable length
1L: 1m
3L: 3m
5L: 5m
□L: □m

Wiring 1
N: Cable only

Wiring 2
CT: With cable track

Shipping configuration
K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

■Maximum Stroke

X axis 450 mm　Y axis 400 mm

■Maximum Speed (High-speed type)

X axis 400 mm/s　Y axis 600 mm/s

■Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X high-speed, Y medium-speed
250mm	2.5kg	5.0kg
300mm	2.0kg	4.0kg
350mm	2.0kg	4.0kg
400mm	2.0kg	4.0kg

List by Stroke

		Incremental			
	Y-axis stroke	250	300	350	400
X-axis stroke	50	–	–	–	–
	100	–	–	–	–
	150	–	–	–	–
	200	–	–	–	–
	250	–	–	–	–
	300	–	–	–	–
	350	–	–	–	–
	400	–	–	–	–
	450	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-450
		-	-
Wiring 2 (Next to Y-axis)	Y-axis stroke	250-400	–
		-	–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

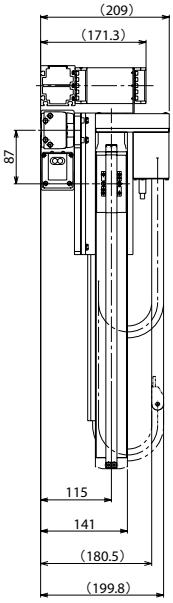
Name	Option code	-
Opposite-home specification	NM	-
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

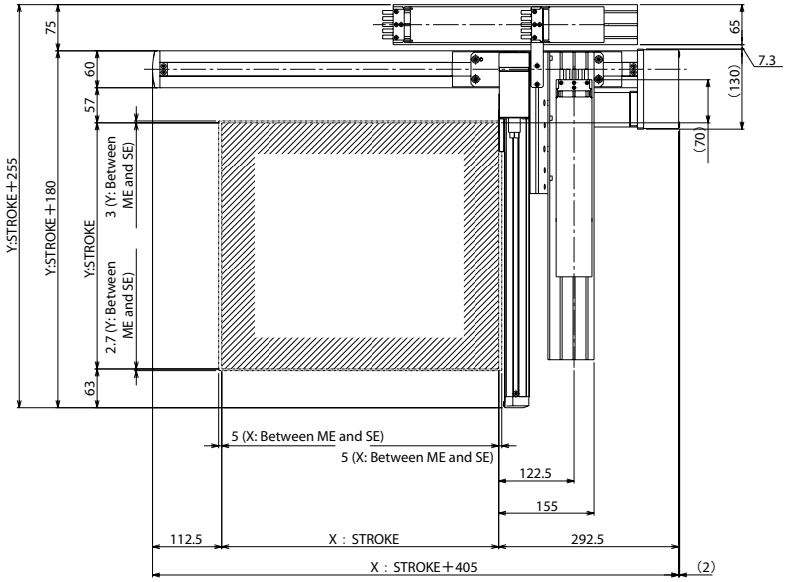
Specifications

Item	X axis	Y axis
Axis model	RCP2-SS7R	RCP2-SA5R
Stroke (Can be set in 50-mm increments)	50-450mm	250-400mm
Max speed	HH type: 400mm/s HM type: 350mm/s	High-speed type: 600mm/s Medium-speed type: 300mm/s
Motor size	42-square pulse motor	
Ball screw lead	High-speed type: 12mm	High-speed type: 12mm Medium-speed type: 6mm
Drive method	Ball screw, ø10 mm, rolled, C10	
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

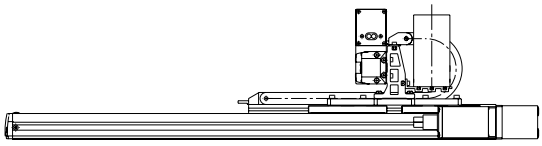
Dimensions

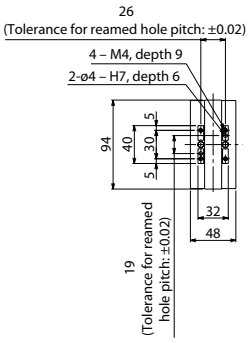
Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.





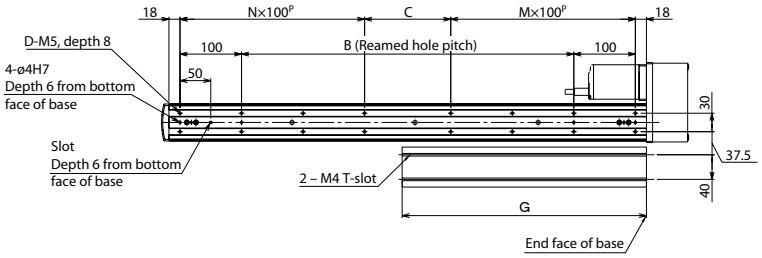
ME: Mechanical end
SE: Stroke end





Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	200	250	300	350	400	450	500	550	600
X: Effective stroke	50	100	150	200	250	300	350	400	450
B	140	190	240	290	340	390	440	490	540
C	140	190	40	90	140	190	40	90	140
D	8	8	12	12	12	12	16	16	16
M	1	1	2	2	2	2	3	3	3
N	1	1	2	2	2	2	3	3	3
G	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-PXBD2□□S

RCP2 2-axis Combinations X axis: SS7C (Straight, Single-slider)
Y axis: SA5R (Reversed)

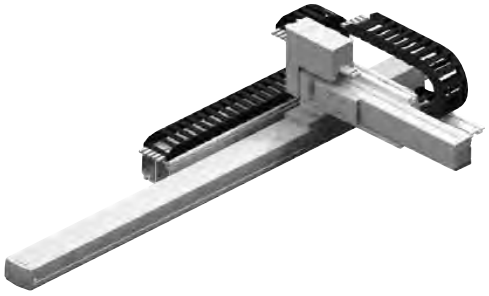
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllers — Cable — Shipping configuration

IK2 — PXBD2□□S — □ — □ □ — □ □ — P1 — □ — □ — □ — □

- **Combination directions** 1-4
- **Differences between Single-slider and Double-slider Types** HH: X high-speed, Y high-speed; HM: X high-speed, Y medium-speed
- **Encoder type** I: Incremental
- **Stroke (mm)** 5: 50mm ~ (Can be set in 50-mm increments)
- **Options** NM: Opposite-home specification; SR: Slider roller specification
- **Controllers** P1
- **Cable length** 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- **Wiring 1** N: Cable only; **Wiring 2** CT: With cable track
- **Shipping configuration** K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 600 mm — Y axis 200 mm

Maximum Speed (High-speed type)

X axis 400 mm/s — Y axis 600 mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X high-speed, Y medium-speed
50mm	3.0kg	6.0kg
100mm	3.0kg	6.0kg
150mm	2.5kg	5.0kg
200mm	2.5kg	5.0kg

List by Stroke

		Incremental			
	Y-axis stroke	50	100	150	200
X-axis stroke	50	–	–	–	–
	100	–	–	–	–
	150	–	–	–	–
	200	–	–	–	–
	250	–	–	–	–
	300	–	–	–	–
	350	–	–	–	–
	400	–	–	–	–
	450	–	–	–	–
	500	–	–	–	–
	550	–	–	–	–
	600	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600
		-	-
Wiring 2 (Next to Y-axis)	Y-axis stroke	50-200	–
		-	–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

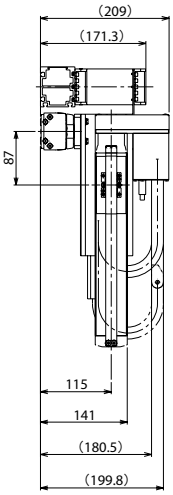
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

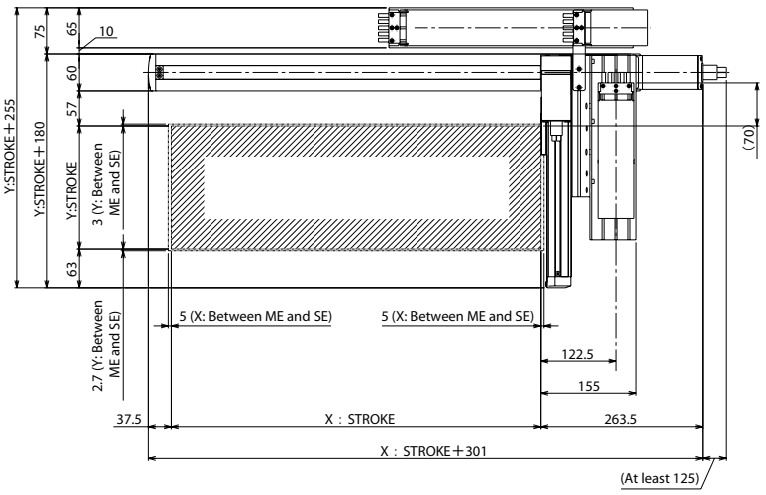
Specifications

Item	X axis	Y axis
Axis model	RCP2-SS7C	RCP2-SA5R
Stroke (Can be set in 50-mm increments)	50-600mm	50-200mm
Max speed	HH type: 400mm/s HM type: 350mm/s	High-speed type: 600mm/s Medium-speed type: 300mm/s
Motor size	42-square pulse motor	
Ball screw lead	High-speed type: 12mm	High-speed type: 12mm Medium-speed type: 6mm
Drive method	Ball screw, ø10 mm, rolled, C10	
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

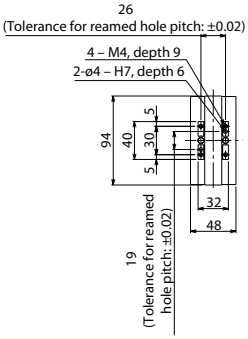
Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

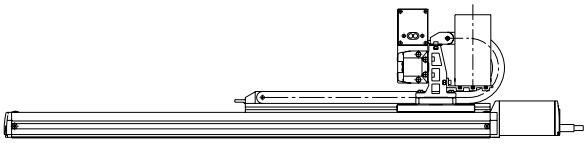




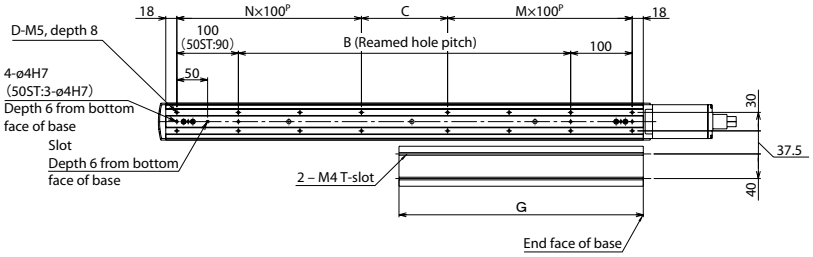
ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider



Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

■Dimensions by Stroke

X: Model	50	100	150	200	250	300	350	400	450	500	550	600
B	0	40	90	140	190	240	290	340	390	440	490	540
C	90	40	90	140	190	40	90	140	190	40	90	140
D	6	8	8	8	8	12	12	12	12	16	16	16
M	1	1	1	1	1	2	2	2	2	3	3	3
N	0	1	1	1	1	2	2	2	2	3	3	3
G	122	147	172	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-PXBD2□□D

RCP2 2-axis Combinations X axis: SS7C (Straight, Double-slider)
Y axis: SA5R (Reversed)

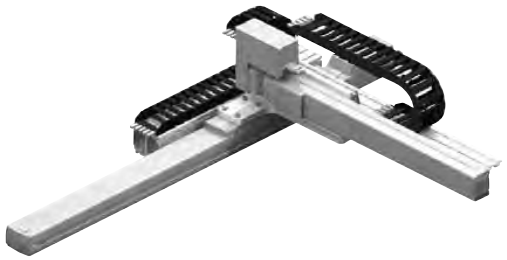
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllers — Cable — Shipping configuration

IK2 — PXBD2□□D — □ — □ □ — □ □ — P1 — □ — □ — □ — □

- **Combination directions** 1-4
- **Differences between Single-slider and Double-slider Types** HH: X high-speed, Y high-speed; HM: X high-speed, Y medium-speed
- **Encoder type** I: Incremental
- **Stroke (mm)** 5: 50mm ~ (Can be set in 50-mm increments)
- **Options** NM: Opposite-home specification; SR: Slider roller specification
- **Cable length** 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- **Wiring 1** N: Cable only
- **Wiring 2** CT: With cable track
- **Shipping configuration** K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 450 mm — Y axis 400 mm

Maximum Speed (High-speed type)

X axis 400 mm/s — Y axis 600 mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X high-speed, Y medium-speed
250mm	2.5kg	5.0kg
300mm	2.0kg	4.0kg
350mm	2.0kg	4.0kg
400mm	2.0kg	4.0kg

List by Stroke

X-axis stroke \ Y-axis stroke	Incremental 250	300	350	400
50	–	–	–	–
100	–	–	–	–
150	–	–	–	–
200	–	–	–	–
250	–	–	–	–
300	–	–	–	–
350	–	–	–	–
400	–	–	–	–
450	—	–	–	–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-450
		-	-
Wiring 2 (Next to Y-axis)	Y-axis stroke	250-400	–
		-	–

List of Options

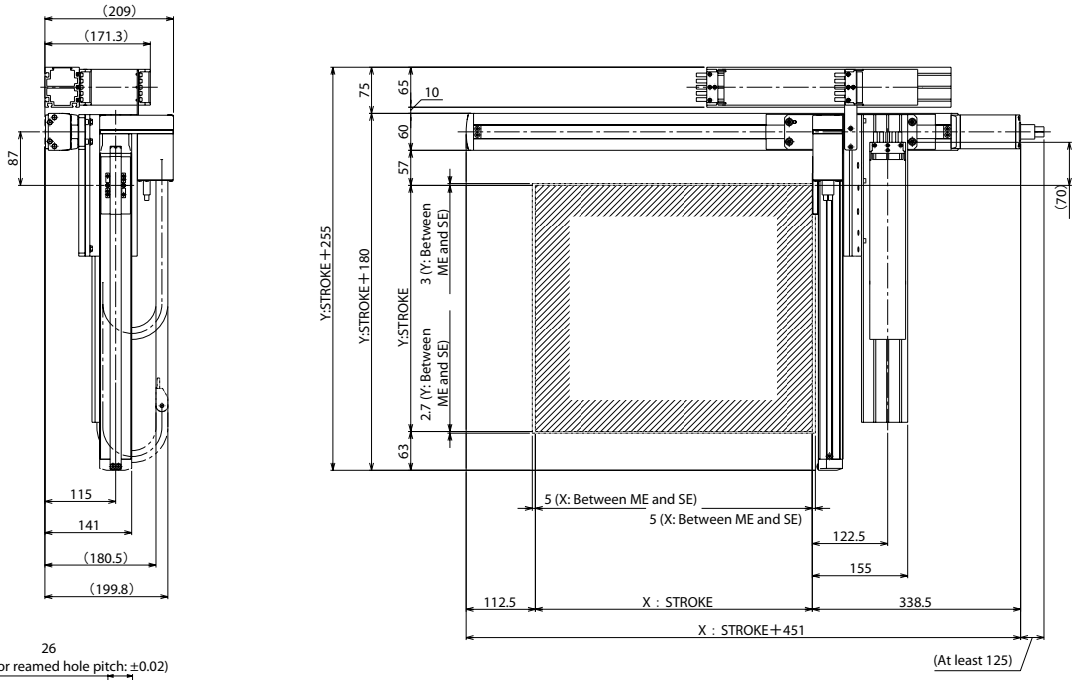
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

Specifications

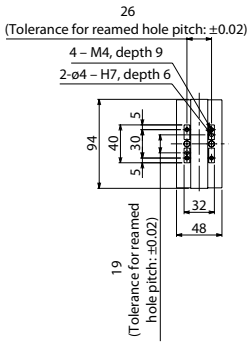
Item	X axis	Y axis
Axis model	RCP2-SS7C	RCP2-SA5R
Stroke (Can be set in 50-mm increments)	50-450mm	250-400mm
Max speed	HH type: 400mm/s HM type: 350mm/s	High-speed type: 600mm/s Medium-speed type: 300mm/s
Motor size	42-square pulse motor	
Ball screw lead	High-speed type: 12mm	High-speed type: 12mm Medium-speed type: 6mm
Drive method	Ball screw, ø10 mm, rolled, C10	
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

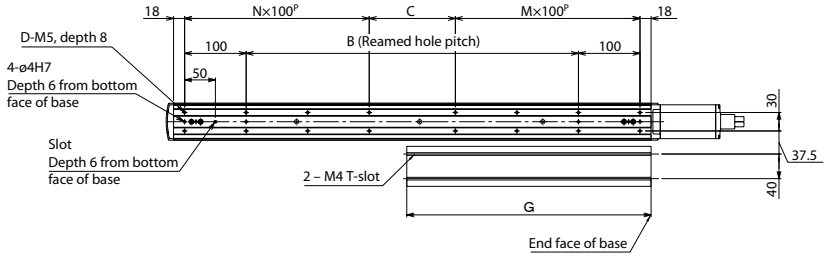


ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	200	250	300	350	400	450	500	550	600
X: Effective stroke	50	100	150	200	250	300	350	400	450
B	140	190	240	290	340	390	440	490	540
C	140	190	40	90	140	190	40	90	140
D	8	8	12	12	12	12	16	16	16
M	1	1	2	2	2	2	3	3	3
N	1	1	2	2	2	2	3	3	3
G	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-PXBC1□□S

RCP2 2-axis Combinations X axis: SS7R (Reversed, Single-slider)
Y axis: SA5R (Reversed)

Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllers — Cable — Shipping configuration

IK2 — PXBC1□□S — □ — □ □ — □ □ — P1 — □ — □ — □ — □

Combination directions
1-2

Differences between Single-slider and Double-slider Types
HH: X high-speed, Y high-speed
HM: X high-speed, Y medium-speed

Encoder type
I: Incremental

Stroke (mm)
5: 50mm
↓
(Can be set in 50-mm increments)

Options
NM: Opposite-home specification
SR: Slider roller specification

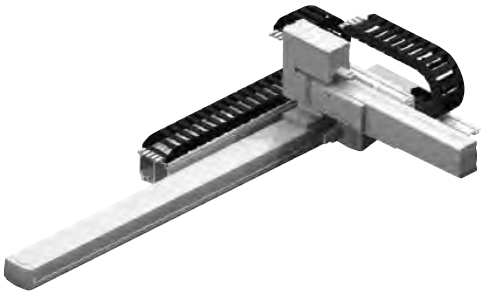
Cable length
1L: 1m
3L: 3m
5L: 5m
□L: □m

Wiring 1
N: Cable only
CT: With cable track

Wiring 2

Shipping configuration
K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 600 mm Y axis 200 mm

Maximum Speed (High-speed type)

X axis 400 mm/s Y axis 600 mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X high-speed, Y medium-speed
50mm	4.5kg	9.0kg
100mm	4.5kg	9.0kg
150mm	4.0kg	8.0kg
200mm	3.0kg	6.0kg

List by Stroke

		Incremental			
	Y-axis stroke	50	100	150	200
X-axis stroke	50	–	–	–	–
	100	–	–	–	–
	150	–	–	–	–
	200	–	–	–	–
	250	–	–	–	–
	300	–	–	–	–
	350	–	–	–	–
	400	–	–	–	–
	450	–	–	–	–
	500	–	–	–	–
	550	–	–	–	–
	600	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600
			-
Wiring 2 (Next to Y-axis)	Y-axis stroke	50-200	–
			–

List of by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

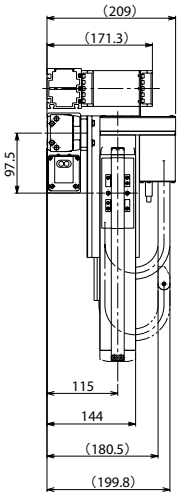
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

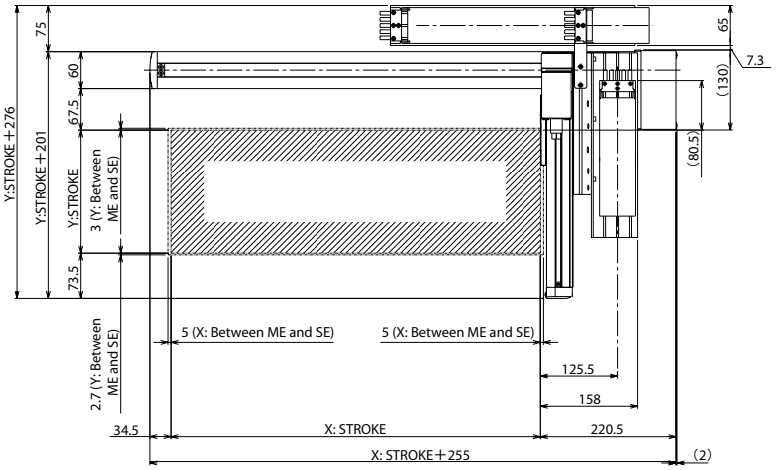
Specifications

Item	X axis	Y axis
Axis model	RCP2-SS7R	RCP2-SA6R
Stroke (Can be set in 50-mm increments)	50-600mm	50-200mm
Max speed	HH type: 400mm/s HM type: 250mm/s	High-speed type: 600mm/s Medium-speed type: 300mm/s
Motor size	42-square pulse motor	
Ball screw lead	High-speed type: 12mm	High-speed type: 12mm Medium-speed type: 6mm
Drive method	Ball screw, ø10 mm, rolled, C10	
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

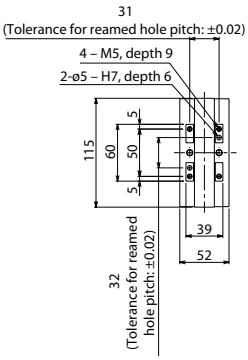
Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

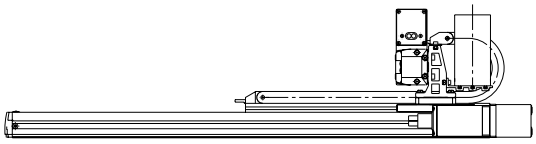




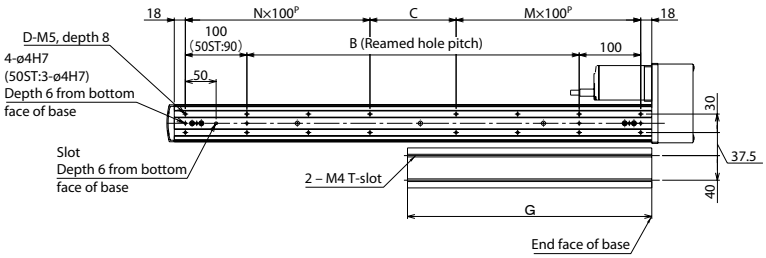
ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider



Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Model	50	100	150	200	250	300	350	400	450	500	550	600
B	0	40	90	140	190	240	290	340	390	440	490	540
C	90	40	90	140	190	40	90	140	190	40	90	140
D	6	8	8	8	8	12	12	12	12	16	16	16
M	1	1	1	1	1	2	2	2	2	3	3	3
N	0	1	1	1	1	2	2	2	2	3	3	3
G	122	147	172	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-PXBC1□□D

RCP2 2-axis Combinations X axis: SS7R (Reversed, Double-slider)
Y axis: SA5R (Reversed)

■Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllers — Cable — Shipping configuration

IK2 — PXBC1□□D — □ — □ □ — □ □ — P1 — □ — □ — □ — □

Combination directions
1-2

Differences between Single-slider and Double-slider Types
HH: X high-speed, Y high-speed
HM: X high-speed, Y medium-speed

Encoder type
I: Incremental

Stroke (mm)
5: 50mm
≀
(Can be set in 50-mm increments)

Options
NM: Opposite-home specification
SR: Slider roller specification

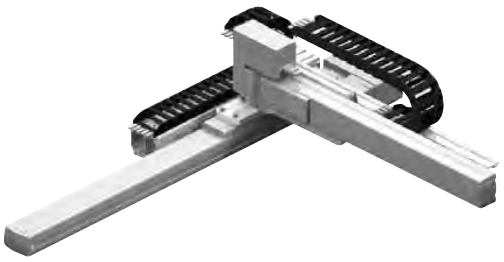
Cable length
1L: 1m
3L: 3m
5L: 5m
□L: □m

Wiring 1
N: Cable only
CT: With cable track

Wiring 2

Shipping configuration
K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

■Maximum Stroke

X axis 450 mm　Y axis 400 mm

■Maximum Speed (High-speed type)

X axis 400 mm/s　Y axis 600 mm/s

■Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X high-speed, Y medium-speed
250mm	3.0kg	6.0kg
300mm	3.0kg	6.0kg
350mm	3.0kg	6.0kg
400mm	3.0kg	6.0kg

List by Stroke

		Incremental			
	Y-axis stroke	250	300	350	400
X-axis stroke	50	–	–	–	–
	100	–	–	–	–
	150	–	–	–	–
	200	–	–	–	–
	250	–	–	–	–
	300	–	–	–	–
	350	–	–	–	–
	400	–	–	–	–
	450	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-450
			-
Wiring 2 (Next to Y-axis)	Y-axis stroke	250-400	–
			–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

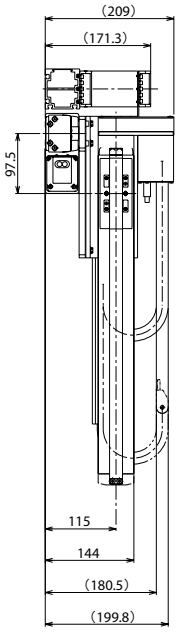
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

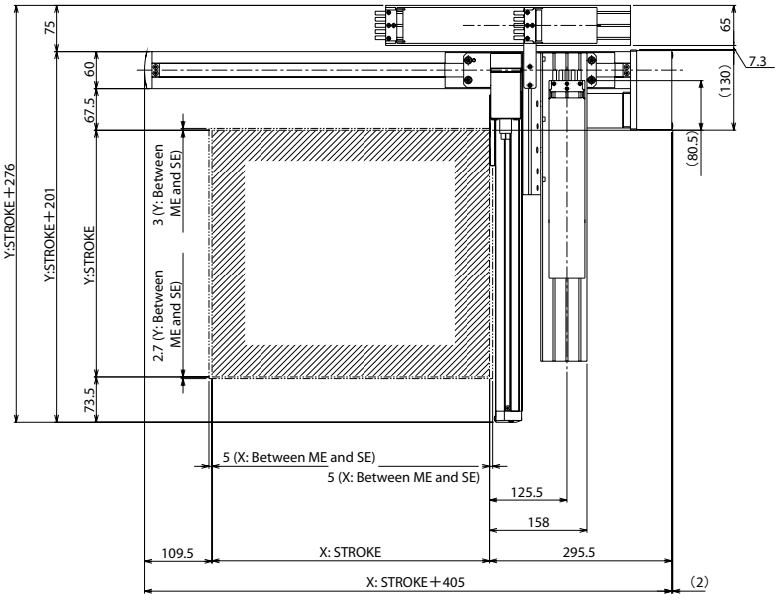
Specifications

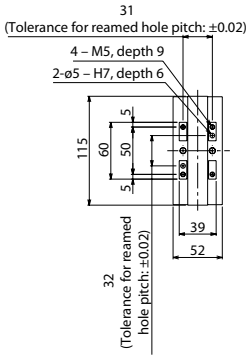
Item	X axis	Y axis
Axis model	RCP2-SS7R	RCP2-SA6R
Stroke (Can be set in 50-mm increments)	50-450mm	250-400mm
Max speed	HH type: 400mm/s HM type: 250mm/s	High-speed type: 600mm/s Medium-speed type: 300mm/s
Motor size	42-square pulse motor	
Ball screw lead	High-speed type: 12mm	High-speed type: 12mm Medium-speed type: 6mm
Drive method	Ball screw, ø10 mm, rolled, C10	
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.



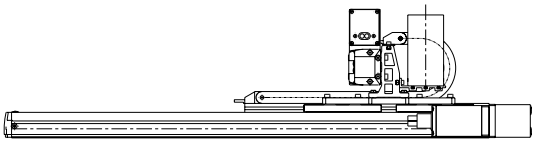


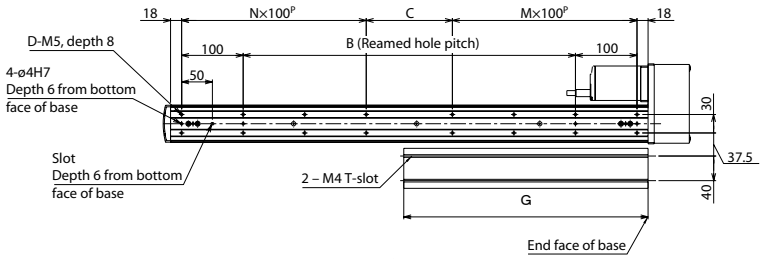


Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base

ME: Mechanical end
SE: Stroke end





Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	200	250	300	350	400	450	500	550	600
X: Effective stroke	50	100	150	200	250	300	350	400	450
B	140	190	240	290	340	390	440	490	540
C	140	190	40	90	140	190	40	90	140
D	8	8	12	12	12	12	16	16	16
M	1	1	2	2	2	2	3	3	3
N	1	1	2	2	2	2	3	3	3
G	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-PXBC2□□S

RCP2 2-axis Combinations X axis: SS7C (Straight, Single-slider)
Y axis: SA6R (Reversed)

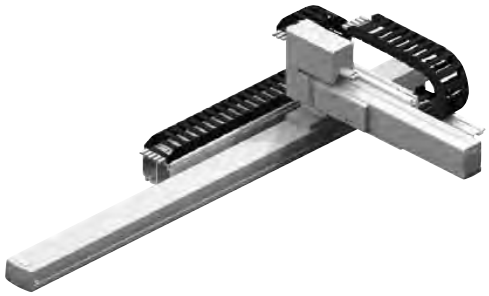
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllers — Cable — Shipping configuration

IK2 — PXBC2□□S — □ — □ □ — □ □ — P1 — □ — □ — □ — □

- **Combination directions** 1-4
- **Differences between Single-slider and Double-slider Types** HH: X high-speed, Y high-speed; HM: X high-speed, Y medium-speed
- **Encoder type** I: Incremental
- **Stroke (mm)** 5: 50mm ~ (Can be set in 50-mm increments)
- **Options** NM: Opposite-home specification; SR: Slider roller specification
- **Controllers** P1
- **Cable length** 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- **Wiring 1** N: Cable only; CT: With cable track
- **Wiring 2**
- **Shipping configuration** K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 600 mm — Y axis 200 mm

Maximum Speed (High-speed type)

X axis 400 mm/s — Y axis 600 mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X high-speed, Y medium-speed
50mm	4.5kg	9.0kg
100mm	4.5kg	9.0kg
150mm	4.0kg	8.0kg
200mm	3.0kg	6.0kg

List by Stroke

		Incremental			
	Y-axis stroke	50	100	150	200
X-axis stroke	50	–	–	–	–
	100	–	–	–	–
	150	–	–	–	–
	200	–	–	–	–
	250	–	–	–	–
	300	–	–	–	–
	350	–	–	–	–
	400	–	–	–	–
	450	–	–	–	–
	500	–	–	–	–
	550	–	–	–	–
	600	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600
			-
Wiring 2 (Next to Y-axis)	Y-axis stroke	50-200	–
			–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

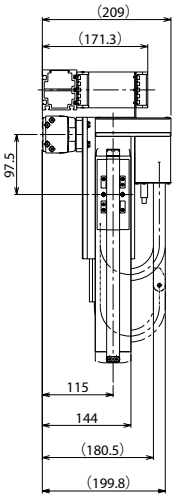
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

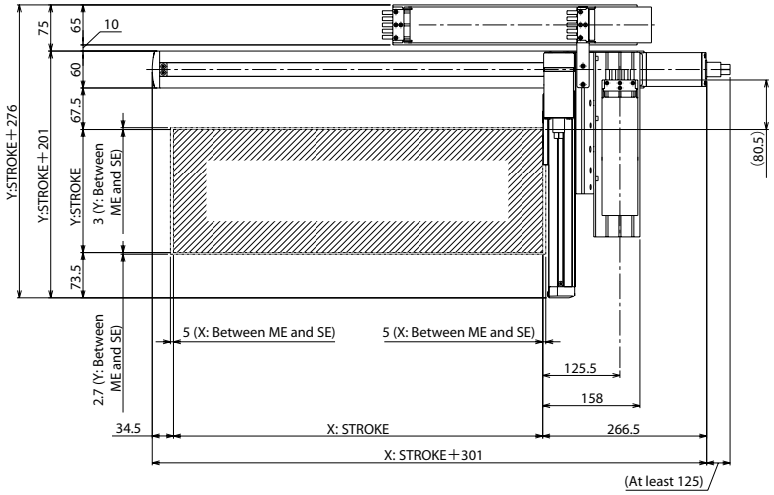
Specifications

Item	X axis	Y axis
Axis model	RCP2-SS7C	RCP2-SA6R
Stroke (Can be set in 50-mm increments)	50-600mm	50-200mm
Max speed	HH type: 400mm/s HM type: 250mm/s	High-speed type: 600mm/s Medium-speed type: 300mm/s
Motor size	42-square pulse motor	
Ball screw lead	High-speed type: 12mm	High-speed type: 12mm Medium-speed type: 6mm
Drive method	Ball screw, ø10 mm, rolled, C10	
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

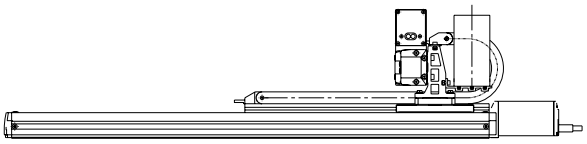
Dimensions

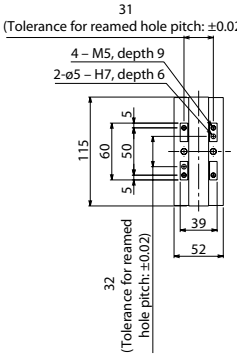
Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.





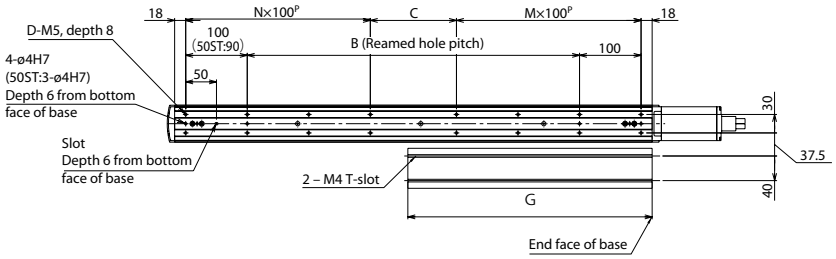
ME: Mechanical end
SE: Stroke end





Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Model	50	100	150	200	250	300	350	400	450	500	550	600
B	0	40	90	140	190	240	290	340	390	440	490	540
C	90	40	90	140	190	40	90	140	190	40	90	140
D	6	8	8	8	8	12	12	12	12	16	16	16
M	1	1	1	1	1	2	2	2	2	3	3	3
N	0	1	1	1	1	2	2	2	2	3	3	3
G	122	147	172	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-PXBC2□□D

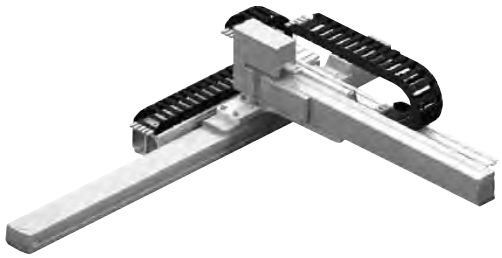
RCP2 2-axis Combinations X axis: SS7C (Straight, Double-slider)
Y axis: SA6R (Reversed)

Model Details

Series	Type	Encoder type	Axis 1 (X axis)	Axis 2 (Y axis)	Controllers	Cable	Shipping configuration
IK2	PXBC2□□D	□	□	□	P1	□	□

- **Combination directions** 1-4
- **Differences between Single-slider and Double-slider Types** HH: X high-speed, Y high-speed; HM: X high-speed, Y medium-speed
- **Encoder type** I: Incremental
- **Stroke (mm)** 5: 50mm ~ (Can be set in 50-mm increments)
- **Options** NM: Opposite-home specification; SR: Slider roller specification
- **Cable length** 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- **Wiring 1** N: Cable only
- **Wiring 2** CT: With cable track
- **Shipping configuration** K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 450 mm　Y axis 400 mm

Maximum Speed (High-speed type)

X axis 400 mm/s　Y axis 600 mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X high-speed, Y medium-speed
250mm	3.0kg	6.0kg
300mm	3.0kg	6.0kg
350mm	3.0kg	6.0kg
400mm	3.0kg	6.0kg

List by Stroke

		Incremental			
	Y-axis stroke	250	300	350	400
X-axis stroke	50	–	–	–	–
	100	–	–	–	–
	150	–	–	–	–
	200	–	–	–	–
	250	–	–	–	–
	300	–	–	–	–
	350	–	–	–	–
	400	–	–	–	–
	450	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-450
			-
Wiring 2 (Next to Y-axis)	Y-axis stroke	250-400	–
			–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

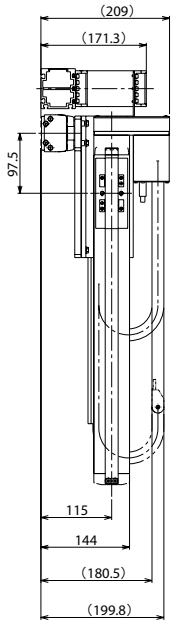
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

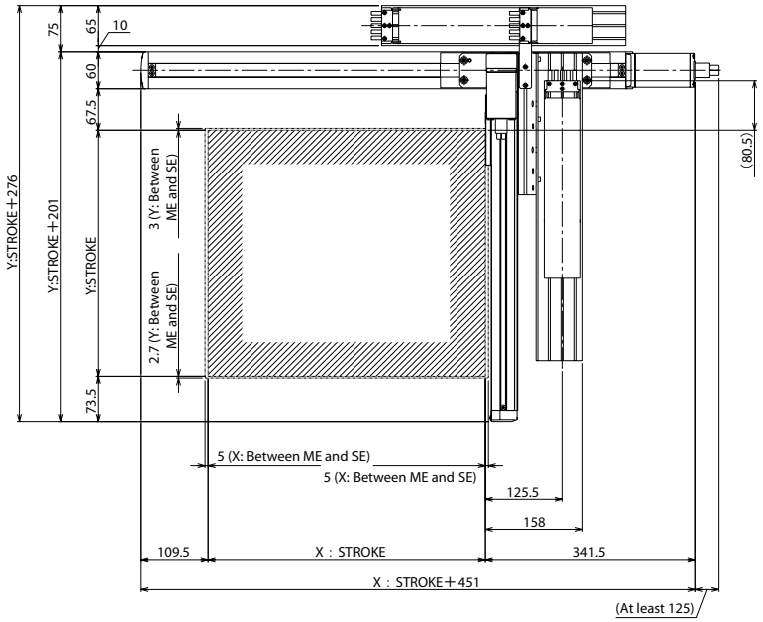
Specifications

Item	X axis	Y axis
Axis model	RCP2-SS7C	RCP2-SA6R
Stroke (Can be set in 50-mm increments)	50-450mm	250-400mm
Max speed	HH type: 400mm/s HM type: 250mm/s	High-speed type: 600mm/s Medium-speed type: 300mm/s
Motor size	42-square pulse motor	
Ball screw lead	High-speed type: 12mm	High-speed type: 12mm Medium-speed type: 6mm
Drive method	Ball screw, ø10 mm, rolled, C10	
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

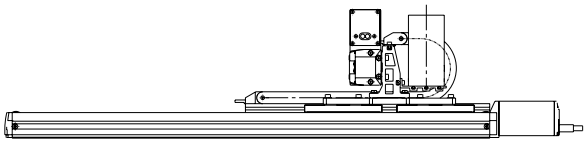
Dimensions

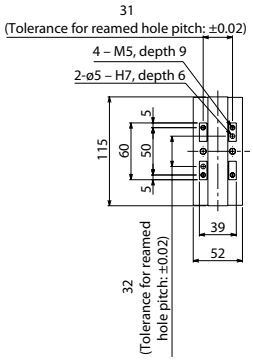
Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.





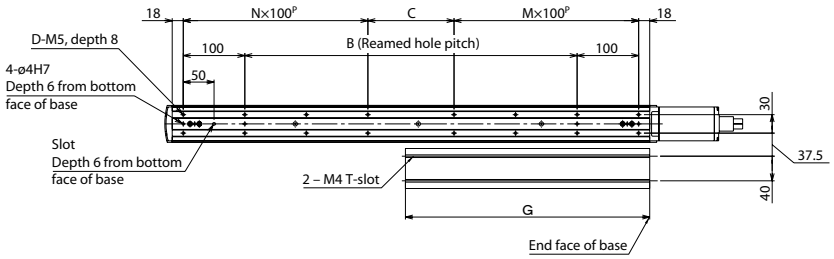
ME: Mechanical end
SE: Stroke end





Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	200	250	300	350	400	450	500	550	600
X: Effective stroke	50	100	150	200	250	300	350	400	450
B	140	190	240	290	340	390	440	490	540
C	140	190	40	90	140	190	40	90	140
D	8	8	12	12	12	12	16	16	16
M	1	1	2	2	2	2	3	3	3
N	1	1	2	2	2	2	3	3	3
G	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-PXBB1□□S

RCP2 2-axis Combinations X axis: SS8R (Reversed, Single-slider)
Y axis: SA7R (Reversed)

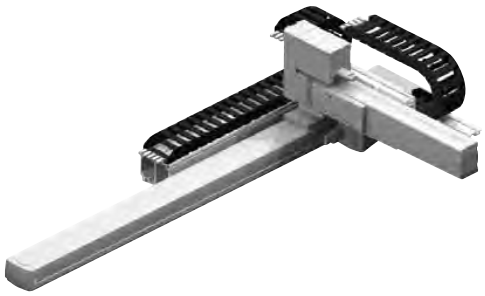
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllers — Cable — Shipping configuration

IK2 – PXBB1□□S – □ – □ □ – □ □ – P1 – □ – □ – □ – □

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- Encoder type: I: Incremental
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 1000 mm — Y axis 300 mm

Maximum Speed (High-speed type)

X axis 250 mm/s — Y axis 450 mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
50mm	8.0kg	16kg
100mm	8.0kg	16kg
150mm	7.0kg	15kg
200mm	7.0kg	12.5kg
250mm	6.0kg	9.0kg
300mm	6.0kg	8.0kg

List by Stroke

		Incremental					
	Y-axis stroke	50	100	150	200	250	300
X-axis stroke	50	–	–	–	–	–	–
	100	–	–	–	–	–	–
	150	–	–	–	–	–	–
	200	–	–	–	–	–	–
	250	–	–	–	–	–	–
	300	–	–	–	–	–	–
	350	–	–	–	–	–	–
	400	–	–	–	–	–	–
	450	–	–	–	–	–	–
	500	–	–	–	–	–	–
	550	–	–	–	–	–	–
	600	–	–	–	–	–	–
	650	–	–	–	–	–	–
	700	–	–	–	–	–	–
	750	–	–	–	–	–	–
	800	–	–	–	–	–	–
	850	–	–	–	–	–	–
	900	–	–	–	–	–	–
	950	–	–	–	–	–	–
	1000	–	–	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600	650-900	950-1000
Wiring 2 (Next to Y-axis)	Y-axis stroke	50-200	250-300	–	–
				–	–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

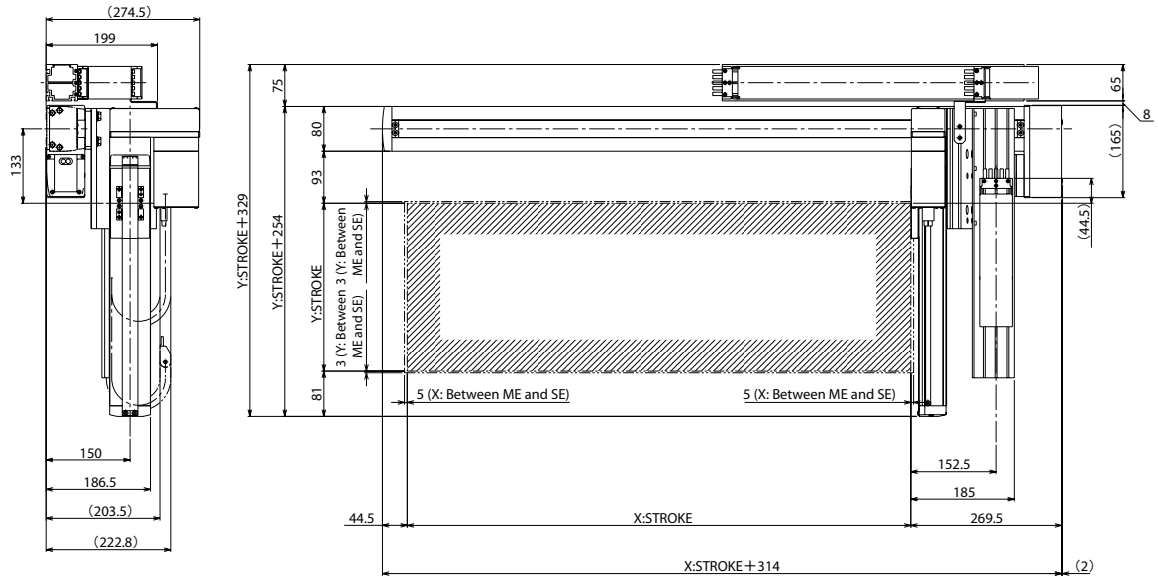
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

Specifications

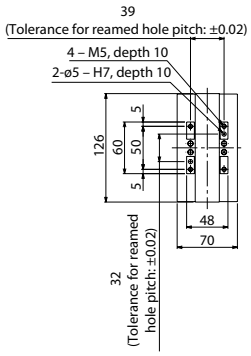
Item	X axis	Y axis
Axis model	RCP2-SS8R	RCP2-SA7R
Stroke (Can be set in 50-mm increments)	50-1000mm	50-300mm
Max speed	High-speed type: 250mm/s Medium-speed type: 125mm/s	High-speed type: 450mm/s Medium-speed type: 220mm/s
Motor size	56-square pulse motor	
Ball screw lead	High-speed type: 20mm Medium-speed type: 10mm	High-speed type: 16mm Medium-speed type: 8mm
Drive method	Ball screw, ø16mm, rolled, C10	Ball screw, ø12mm, rolled, C10
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

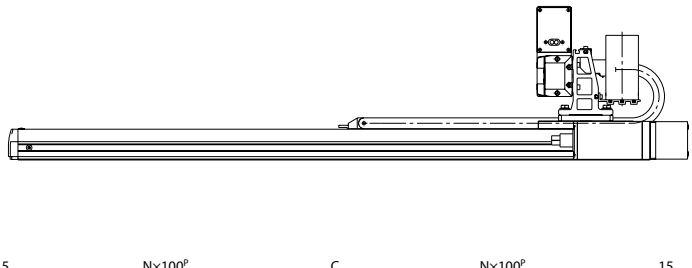


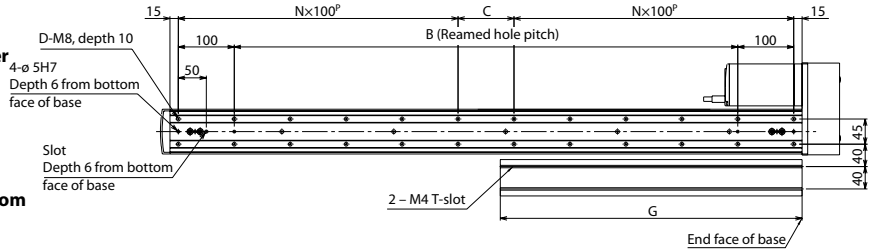
ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base





Detail view of X-axis installation

Dimensions by Stroke

X: Model	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
B	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	8	8	8	10	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	114.5	139.5	164.5	189.5	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-PXBB1□□D

RCP2 2-axis Combinations X axis: SS8R (Reversed, Double-slider)
Y axis: SA7R (Reversed)

Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllers — Cable — Shipping configuration

IK2 – PXBB1□□D – □ – □ □ – □ □ – P1 – □ – □ – □ – □

Combination directions
1-2

Differences between Single-slider and Double-slider Types
HH: X high-speed, Y high-speed
MM: X medium-speed, Y medium-speed

Encoder type
I: Incremental

Stroke (mm)
5: 50mm
↓
(Can be set in 50-mm increments)

Options
NM: Opposite-home specification
SR: Slider roller specification

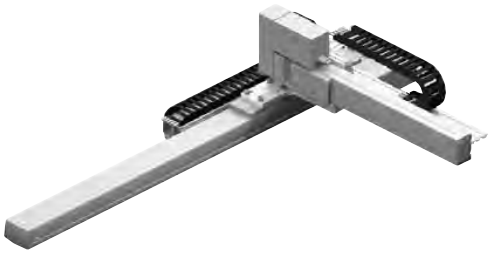
Cable length
1L: 1m
3L: 3m
5L: 5m
□L: □m

Wiring 1
N: Cable only
CT: With cable track

Wiring 2

Shipping configuration
K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 800 mm　Y axis 400 mm

Maximum Speed (High-speed type)

X axis 250 mm/s　Y axis 450 mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
200mm	–	15kg
250mm	–	12.5kg
300mm	–	12.5kg
350mm	6.0kg	12kg
400mm	5.5kg	10.5kg

List by Stroke

		Incremental				
	Y-axis stroke	200	250	300	350	400
X-axis stroke	50	–	–	–	–	–
	100	–	–	–	–	–
	150	–	–	–	–	–
	200	–	–	–	–	–
	250	–	–	–	–	–
	300	–	–	–	–	–
	350	–	–	–	–	–
	400	–	–	–	–	–
	450	–	–	–	–	–
	500	–	–	–	–	–
	550	–	–	–	–	–
	600	–	–	–	–	–
	650	–	–	–	–	–
	700	–	–	–	–	–
	750	–	–	–	–	–
	800	–	–	–	–	–

Note: For the X high-speed/Y high-speed type, the Y-axis stroke must be 350 mm or more.

List by Cable Length

Type	Cable code	Length
Standard type	**1L**	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600	650-800
Wiring 2 (Next to Y-axis)	Y-axis stroke	200	250-400	–
				–

List of Options

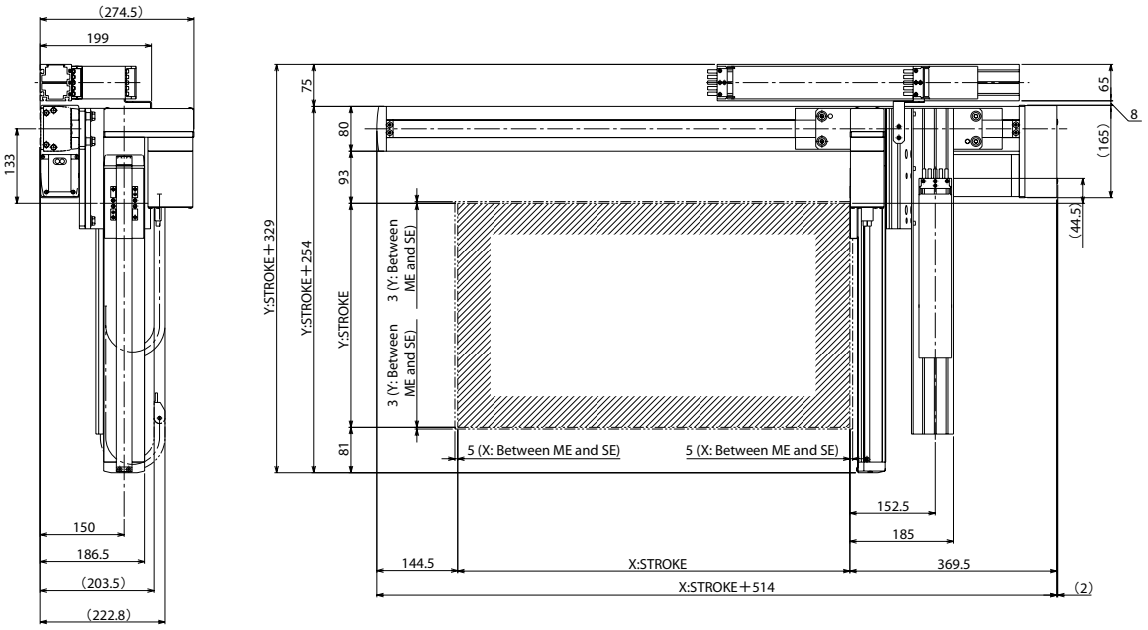
Name	Option code	
Opposite-home specification	**NM**	
Slider roller specification	**SR**	Axis 1 (X-axis) Axis 2 (Y-axis)

Specifications

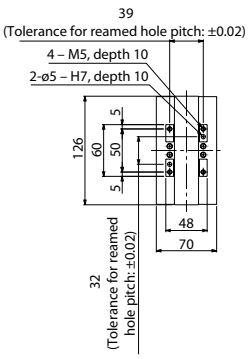
Item	X axis	Y axis
Axis model	RCP2-SS8R	RCP2-SA7R
Stroke (Can be set in 50-mm increments)	50-800mm	High-speed type: 350-400mm Medium-speed type: 200-400mm
Max speed	High-speed type: 250mm/s Medium-speed type: 125mm/s	High-speed type: 450mm/s Medium-speed type: 220mm/s
Motor size	56-square pulse motor	
Ball screw lead	High-speed type: 20mm Medium-speed type: 10mm	High-speed type: 16mm Medium-speed type: 8mm
Drive method	Ball screw, ø16mm, rolled, C10	Ball screw, ø12mm, rolled, C10
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.



ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider

Detail view of X-axis installation

Detail view of slot in bottom face of X-axis base

Dimensions by Stroke

X: Nominal stroke	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
X: Effective stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
B	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-PXBB2□□S

RCP2 2-axis Combinations X axis: SS8C (Straight, Single-slider)
Y axis: SA7R (Reversed)

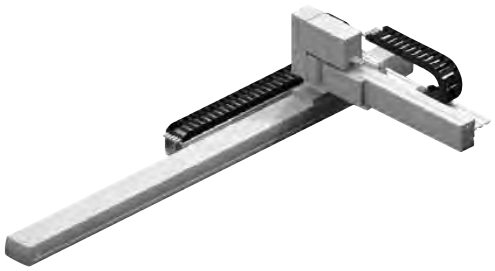
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllers — Cable — Shipping configuration

IK2 – PXBB2□□S – □ – □ □ – □ □ – P1 – □ – □ – □ – □

- **Combination directions** 1-4
- **Differences between Single-slider and Double-slider Types** HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- **Encoder type** I: Incremental
- **Stroke (mm)** 5: 50mm ~ (Can be set in 50-mm increments)
- **Options** NM: Opposite-home specification; SR: Slider roller specification
- **Cable length** 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- **Wiring 1** N: Cable only; CT: With cable track
- **Wiring 2**
- **Shipping configuration** K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 1000 mm Y axis 300 mm

Maximum Speed (High-speed type)

X axis 250 mm/s Y axis 450 mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
50mm	8.0kg	16kg
100mm	8.0kg	16kg
150mm	7.0kg	15kg
200mm	7.0kg	12.5kg
250mm	6.0kg	9.0kg
300mm	6.0kg	8.0kg

List by Stroke

		Incremental					
	Y-axis stroke	50	100	150	200	250	300
X-axis stroke	50	–	–	–	–	–	–
	100	–	–	–	–	–	–
	150	–	–	–	–	–	–
	200	–	–	–	–	–	–
	250	–	–	–	–	–	–
	300	–	–	–	–	–	–
	350	–	–	–	–	–	–
	400	–	–	–	–	–	–
	450	–	–	–	–	–	–
	500	–	–	–	–	–	–
	550	–	–	–	–	–	–
	600	–	–	–	–	–	–
	650	–	–	–	–	–	–
	700	–	–	–	–	–	–
	750	–	–	–	–	–	–
	800	–	–	–	–	–	–
	850	–	–	–	–	–	–
	900	–	–	–	–	–	–
	950	–	–	–	–	–	–
	1000	–	–	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600	650-900	950-1000
Wiring 2 (Next to Y-axis)	Y-axis stroke	50-200	250-300	–	–
				–	–

List by Cable Length

Type	Cable code	Length
Standard type	**1L**	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

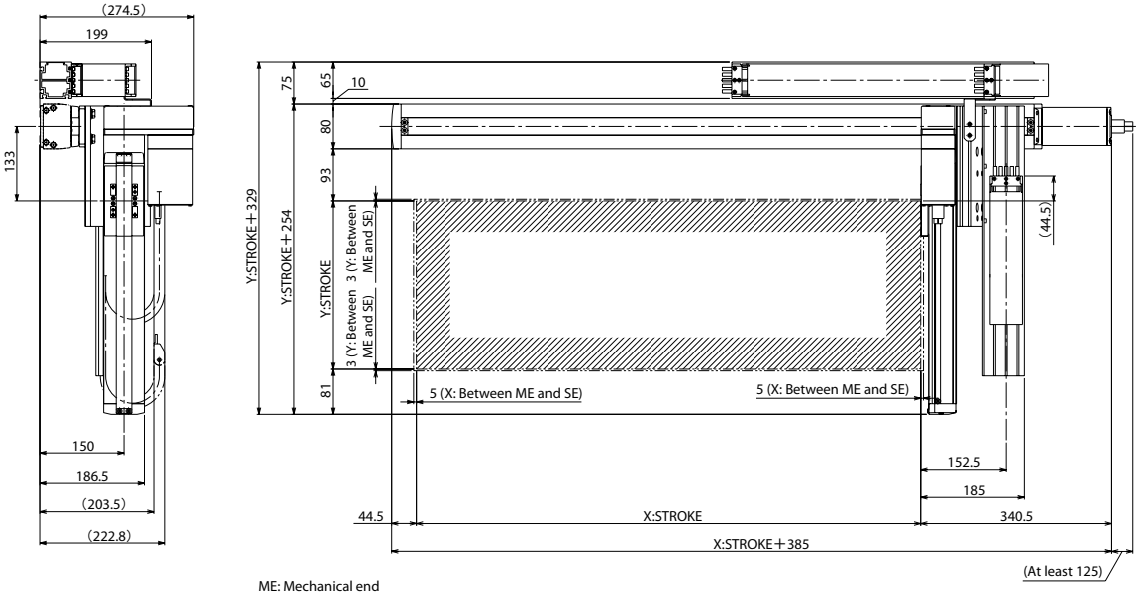
Name	Option code	
Opposite-home specification	**NM**	
Slider roller specification	**SR**	Axis 1 (X-axis) Axis 2 (Y-axis)

Specifications

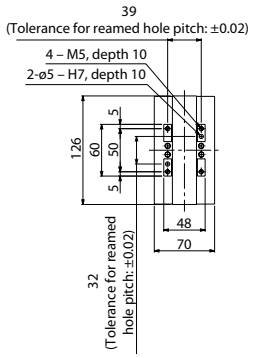
Item	X axis	Y axis
Axis model	RCP2-SS8C	RCP2-SA7R
Stroke (Can be set in 50-mm increments)	50-1000mm	50-300mm
Max speed	High-speed type: 250mm/s Medium-speed type: 125mm/s	High-speed type: 450mm/s Medium-speed type: 220mm/s
Motor size	56-square pulse motor	
Ball screw lead	High-speed type: 20mm Medium-speed type: 10mm	High-speed type: 16mm Medium-speed type: 8mm
Drive method	Ball screw, ø16mm, rolled, C10	Ball screw, ø12mm, rolled, C10
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

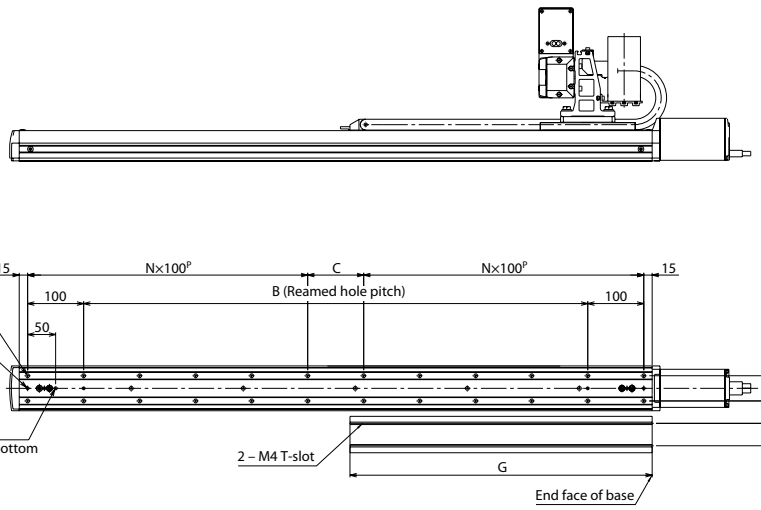


ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Model	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
B	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	8	8	8	10	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	114.5	139.5	164.5	189.5	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-PXBB2□□D

RCP2 2-axis Combinations X axis: SS8C (Straight, Double-slider)
Y axis: SA7R (Reversed)

Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllers — Cable — Shipping configuration

IK2 — **PXBB2□□D** — □ — □ □ — □ □ — **P1** — □ — □ — □ — □

- **Combination directions** 1-4
- **Differences between Single-slider and Double-slider Types** HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- **Encoder type** I: Incremental
- **Stroke (mm)** 5: 50mm ~ (Can be set in 50-mm increments)
- **Options** NM: Opposite-home specification; SR: Slider roller specification
- **Cable length** 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- **Wiring 1** N: Cable only; CT: With cable track
- **Wiring 2**
- **Shipping configuration** K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.

Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 800 mm — Y axis 400 mm

Maximum Speed (High-speed type)

X axis 250 mm/s — Y axis 450 mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
200mm	–	15kg
250mm	–	12.5kg
300mm	–	12.5kg
350mm	6.0kg	12kg
400mm	5.5kg	10.5kg

List by Stroke

		Incremental				
	Y-axis stroke	200	250	300	350	400
X-axis stroke	50	–	–	–	–	–
	100	–	–	–	–	–
	150	–	–	–	–	–
	200	–	–	–	–	–
	250	–	–	–	–	–
	300	–	–	–	–	–
	350	–	–	–	–	–
	400	–	–	–	–	–
	450	–	–	–	–	–
	500	–	–	–	–	–
	550	–	–	–	–	–
	600	–	–	–	–	–
	650	–	–	–	–	–
	700	–	–	–	–	–
	750	–	–	–	–	–
	800	–	–	–	–	–

Note: For the X high-speed/Y high-speed type, the Y-axis stroke must be 350 mm or more.

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600	650-800
Wiring 2 (Next to Y-axis)	Y-axis stroke	200	250-400	–
				–

List by Cable Length

Type	Cable code	Length
Standard type	**1L**	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

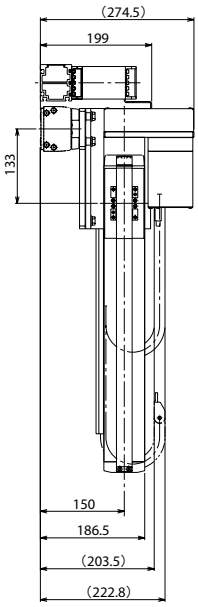
Name	Option code	
Opposite-home specification	**NM**	
Slider roller specification	**SR**	Axis 1 (X-axis) Axis 2 (Y-axis)

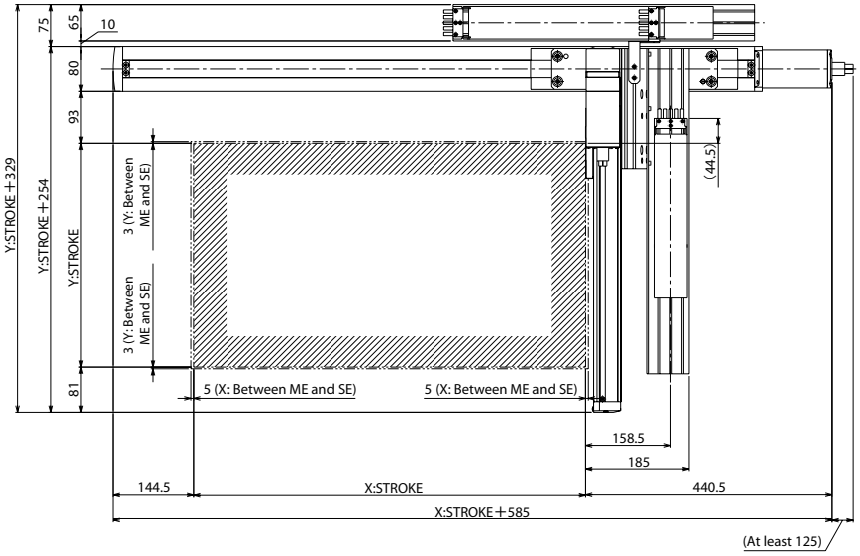
Specifications

Item	X axis	Y axis
Axis model	RCP2-SS8C	RCP2-SA7R
Stroke (Can be set in 50-mm increments)	50-800mm	High-speed type: 350-400mm Medium-speed type: 200-400mm
Max speed	High-speed type: 250mm/s Medium-speed type: 125mm/s	High-speed type: 450mm/s Medium-speed type: 220mm/s
Motor size	56-square pulse motor	
Ball screw lead	High-speed type: 20mm Medium-speed type: 10mm	High-speed type: 16mm Medium-speed type: 8mm
Drive method	Ball screw, ø16mm, rolled, C10	Ball screw, ø12mm, rolled, C10
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

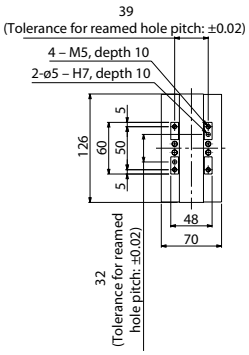
Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.



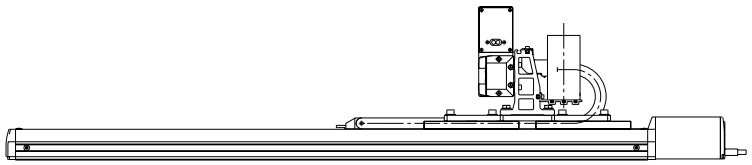


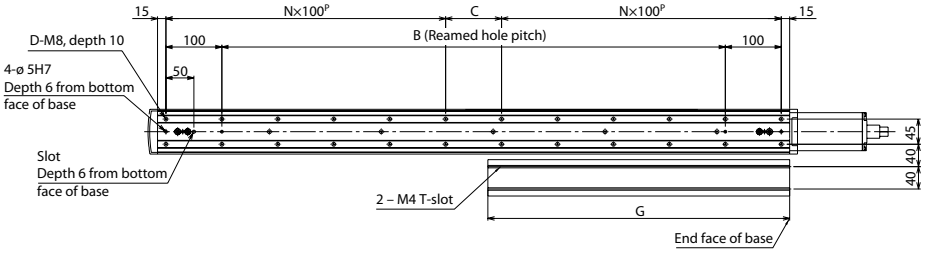
ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base





Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
X: Effective stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
B	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-PXZB1□□S

RCP2 2-axis Combinations X axis: SS8R (Reversed, Single-slider)
Z axis: SA7R (Reversed)

Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Z axis) — Controllers — Cable — Shipping configuration

IK2 – PXZB1□□S – □ – □ □ – □ □ – P1 – □ – □ – □ – □

- **Combination directions** 1-4
- **Differences between Single-slider and Double-slider Types** HH: X high-speed, Z high-speed; HM: X high-speed, Z medium-speed; HL: X high-speed, Z low-speed
- **Encoder type** I: Incremental
- **Stroke (mm)** 5: 50mm ~ (Can be set in 50-mm increments)
- **Options** B: Brake; NM: Opposite-home specification; SR: Slider roller specification
- **Cable length** 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- **Wiring 1** N: Cable only; CT: With cable track
- **Wiring 2**
- **Shipping configuration** K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.

Wiring 1 with cable track

Maximum Stroke

X axis 1000 mm — Z axis 250 mm

Maximum Speed (High-speed type)

X axis 250 mm/s — Z axis 360 mm/s

Maximum Load Capacity

Z-axis stroke	Z high-speed, lead 16	Z medium-speed, lead 8	Z low-speed, lead 4
50mm	2.0kg	4.0kg	8.0kg
100mm	2.0kg	4.0kg	7.0kg
150mm	2.0kg	3.5kg	5.0kg
200mm	2.0kg	3.5kg	4.0kg
250mm	1.5kg	2.5kg	3.0kg

List by Stroke

		Incremental				
	Z -axis stroke	50	100	150	200	250
X-axis stroke	50	–	–	–	–	–
	100	–	–	–	–	–
	150	–	–	–	–	–
	200	–	–	–	–	–
	250	–	–	–	–	–
	300	–	–	–	–	–
	350	–	–	–	–	–
	400	–	–	–	–	–
	450	–	–	–	–	–
	500	–	–	–	–	–
	550	–	–	–	–	–
	600	–	–	–	–	–
	650	–	–	–	–	–
	700	–	–	–	–	–
	750	–	–	–	–	–
	800	–	–	–	–	–
	850	–	–	–	–	–
	900	–	–	–	–	–
	950	–	–	–	–	–
	1000	–	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	150-300	350-600	650-900	950-1000

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

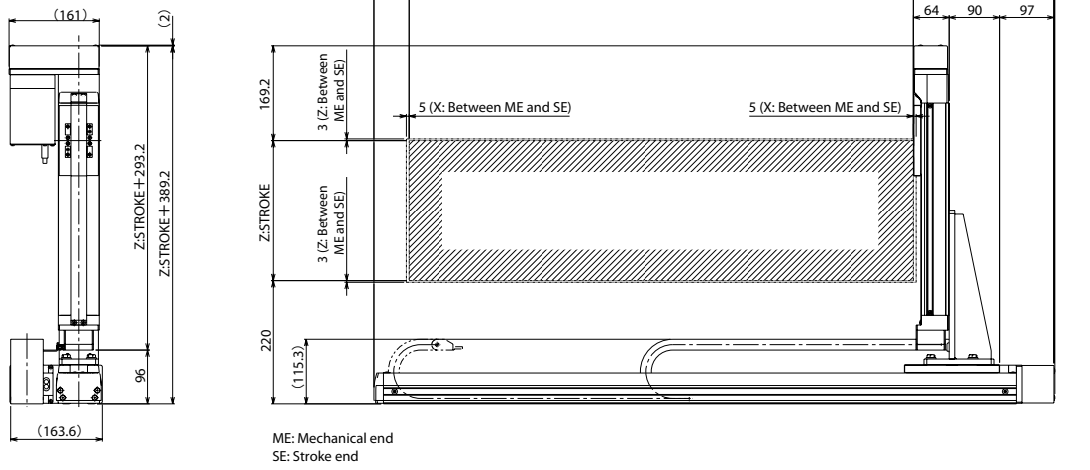
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Z-axis)

Specifications

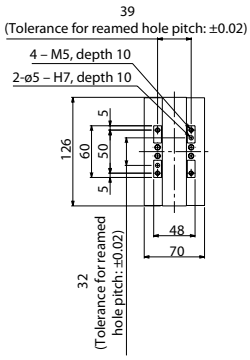
Item	X axis	Z axis
Axis model	RCP2-SS8R	RCP2-SA7R
Stroke (Can be set in 50-mm increments)	50-1000mm	50-250mm
Max speed	High-speed type: 250mm/s	High-speed type: 360mm/s Medium-speed type: 180mm/s Low-speed type: 90mm/s
Motor size	56-square pulse motor	
Ball screw lead	High-speed type: 20mm	High-speed type: 16mm Medium-speed type: 8mm Low-speed type: 4mm
Drive method	Ball screw, ø16mm, rolled, C10	Ball screw, ø12mm, rolled, C10
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

Dimensions

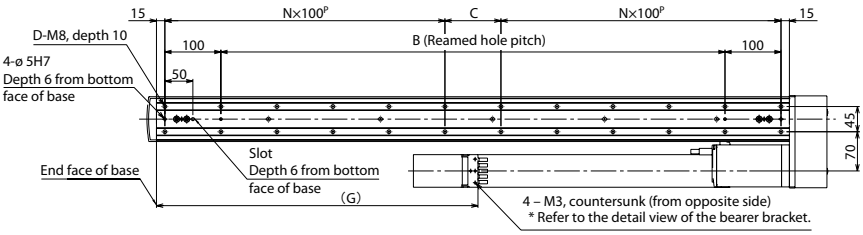
Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.



ME: Mechanical end
SE: Stroke end



Detail view of Z-axis slider



Detail view of X-axis installation

Detail view of slot in bottom face of X-axis base

Dimensions by Stroke

X: Model	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
B	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	8	8	8	10	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	–	–	199	224	249	274	299	324	349	374	399	424	449	474	499	524	549	574	599	624

* A bearer is not set when the X stroke is 50 or 100.

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-PXZB1□□D

RCP2 2-axis Combinations X axis: SS8R (Reversed, Double-slider)
Z axis: SA7R (Reversed)

Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Z axis) — Controllers — Cable — Shipping configuration

IK2 – PXZB1□□D – □ – □ □ – □ □ – P1 – □ – □ – □ – □

- **Combination directions** 1-4
- **Differences between Single-slider and Double-slider Types** HH: X high-speed, Z high-speed; HM: X high-speed, Z medium-speed; HL: X high-speed, Z low-speed
- **Encoder type** I: Incremental
- **Stroke (mm)** 5: 50mm ~ (Can be set in 50-mm increments)
- **Options** B: Brake; NM: Opposite-home specification; SR: Slider roller specification
- **Cable length** 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- **Wiring 1** N: Cable only; CT: With cable track
- **Wiring 2**
- **Shipping configuration** K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.

Wiring 1 with cable track

Maximum Stroke

X axis 800 mm Z axis 300 mm

Maximum Speed (High-speed type)

X axis 250 mm/s Z axis 400 mm/s

Maximum Load Capacity

Z-axis stroke	Z high-speed, lead 16	Z medium-speed, lead 8	Z low-speed, lead 4
150mm	–	–	7.0kg
200mm	–	–	7.0kg
250mm	–	–	5.5kg
300mm	1.5kg	3.0kg	5.5kg

List by Stroke

		Incremental			
	Z-axis stroke	150	200	250	300
X-axis stroke	50	–	–	–	–
	100	–	–	–	–
	150	–	–	–	–
	200	–	–	–	–
	250	–	–	–	–
	300	–	–	–	–
	350	–	–	–	–
	400	–	–	–	–
	450	–	–	–	–
	500	–	–	–	–
	550	–	–	–	–
	600	–	–	–	–
	650	–	–	–	–
	700	–	–	–	–
	750	–	–	–	–
	800	–	–	–	–

Note: For the Z high-speed type and Z medium-speed type, The Z-axis stroke is limited to 300 mm.

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	150-300	350-600	650-800

List by Cable Length

Type	Cable code	Length
Standard type	**1L**	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

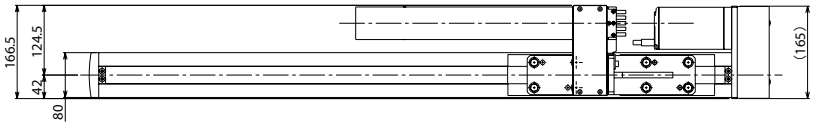
Name	Option code	
Opposite-home specification	**NM**	
Slider roller specification	**SR**	Axis 1 (X-axis) Axis 2 (Z-axis)

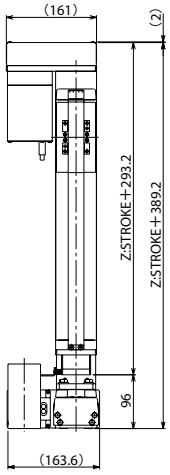
Specifications

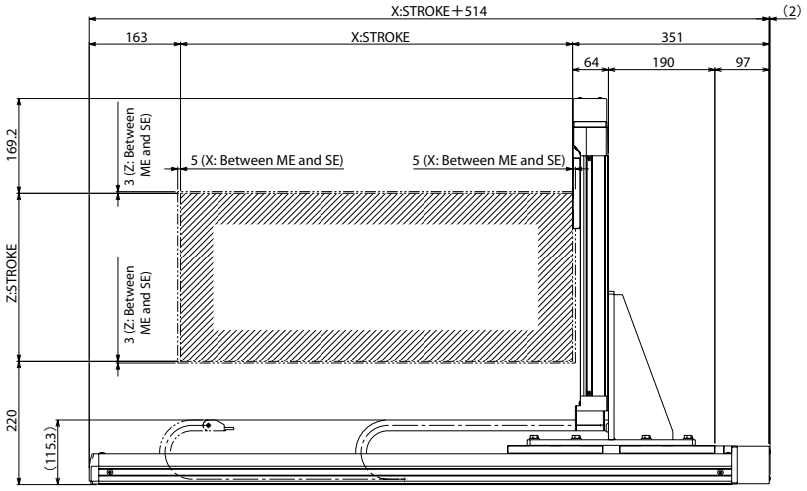
Item	X axis	Z axis
Axis model	RCP2-SS8R	RCP2-SA7R
Stroke (Can be set in 50-mm increments)	50-800mm	High-speed type: 300mm Medium-speed type: 300mm Low-speed type: 150-300mm
Max speed	High-speed type: 250mm/s	High-speed type: 400mm/s Medium-speed type: 200mm/s Low-speed type: 100mm/s
Motor size	56-square pulse motor	
Ball screw lead	High-speed type: 20mm	High-speed type: 16mm Medium-speed type: 8mm Low-speed type: 4mm
Drive method	Ball screw, ø16mm, rolled, C10	Ball screw, ø12mm, rolled, C10
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

Dimensions

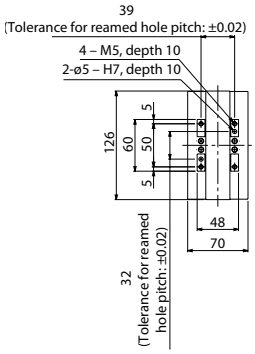
Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.



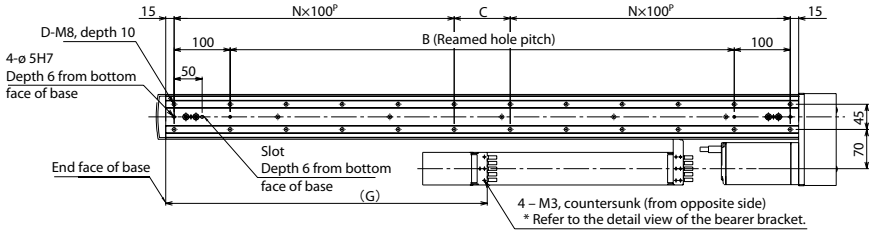




ME: Mechanical end
SE: Stroke end



Detail view of Z-axis slider



Detail view of X-axis installation

Detail view of slot in bottom face of X-axis base

Dimensions by Stroke

X: Nominal stroke	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
X: Effective stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
B	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	–	–	299	324	349	374	399	424	449	474	499	524	549	574	599	624

* A bearer is not set when the X stroke is 50 or 100.

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-PYBB1□□S

RCP2 2-axis Combinations Y axis: SS8R (Reversed, Double-slider)
Z axis: SA7R (Reversed)

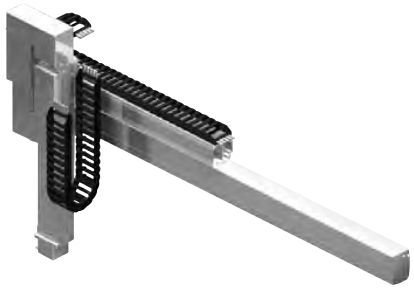
■Model Details

Series — Type — Encoder type — Axis 1 (Y axis) — Axis 2 (Z axis) — Controllers — Cable — Shipping configuration

IK2 – PYBB1□□S – □ – □ □ – □ □ – P1 – □ – □ – □ – □

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HH: Y high-speed, Z high-speed; HM: Y high-speed, Z medium-speed; HL: Y high-speed, Z low-speed
- Encoder type: I: Incremental
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: B: Brake; NM: Opposite-home specification; SR: Slider roller specification
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

■Maximum Stroke

Y axis 1000 mm　Z axis 300 mm

■Maximum Speed (High-speed type)

Y axis 250 mm/s　Z axis 360 mm/s

■Maximum Load Capacity

Z-axis stroke	Z high-speed, lead 16	Z medium-speed, lead 8	Z low-speed, lead 4
50mm	2.0kg	4.0kg	8.0kg
100mm	2.0kg	4.0kg	8.0kg
150mm	2.0kg	3.5kg	7.0kg
200mm	2.0kg	3.5kg	7.0kg
250mm	1.5kg	3.0kg	6.0kg
300mm	1.5kg	3.0kg	5.5kg

List by Stroke

Y-axis stroke \ Z-axis stroke	Incremental 50	100	150	200	250	300
50	–	–	–	–	–	–
100	–	–	–	–	–	–
150	–	–	–	–	–	–
200	–	–	–	–	–	–
250	–	–	–	–	–	–
300	–	–	–	–	–	–
350	–	–	–	–	–	–
400	–	–	–	–	–	–
450	–	–	–	–	–	–
500	–	–	–	–	–	–
550	–	–	–	–	–	–
600	–	–	–	–	–	–
650	–	–	–	–	–	–
700	–	–	–	–	–	–
750	–	–	–	–	–	–
800	–	–	–	–	–	–
850	–	–	–	–	–	–
900	–	–	–	–	–	–
950	–	–	–	–	–	–
1000	–	–	–	–	–	–

Cable track

Wiring 1 (Next to Y-axis)	Y-axis stroke	50-300	350-600	650-900	950-1000
Wiring 2 (Next to Z-axis)	Z-axis stroke	50-200	250-300	–	–
				–	–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

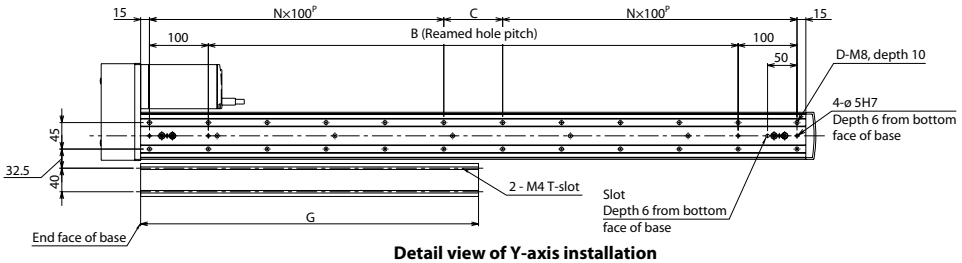
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (Y-axis) Axis 2 (Z-axis)

Specifications

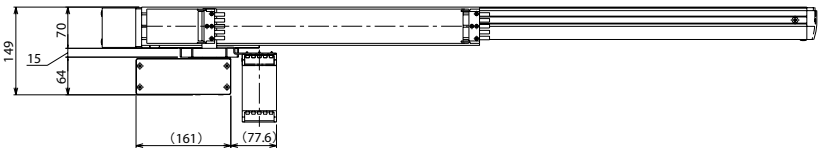
Item	Y axis	Z axis
Axis model	RCP2-SS8R	RCP2-SA7R
Stroke (Can be set in 50-mm increments)	50-1000mm	50-300mm
Max speed	High-speed type: 250mm/s	High-speed type: 360mm/s Medium-speed type: 180mm/s Low-speed type: 90mm/s
Motor size	56-square pulse motor	
Ball screw lead	High-speed type: 20mm	High-speed type: 16mm Medium-speed type: 8mm Low-speed type: 4mm
Drive method	Ball screw, ø16mm, rolled, C10	Ball screw, ø12mm, rolled, C10
Positioning repeatability	±0.02mm	
Base material	Dedicated alloy steel	Aluminum
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)	

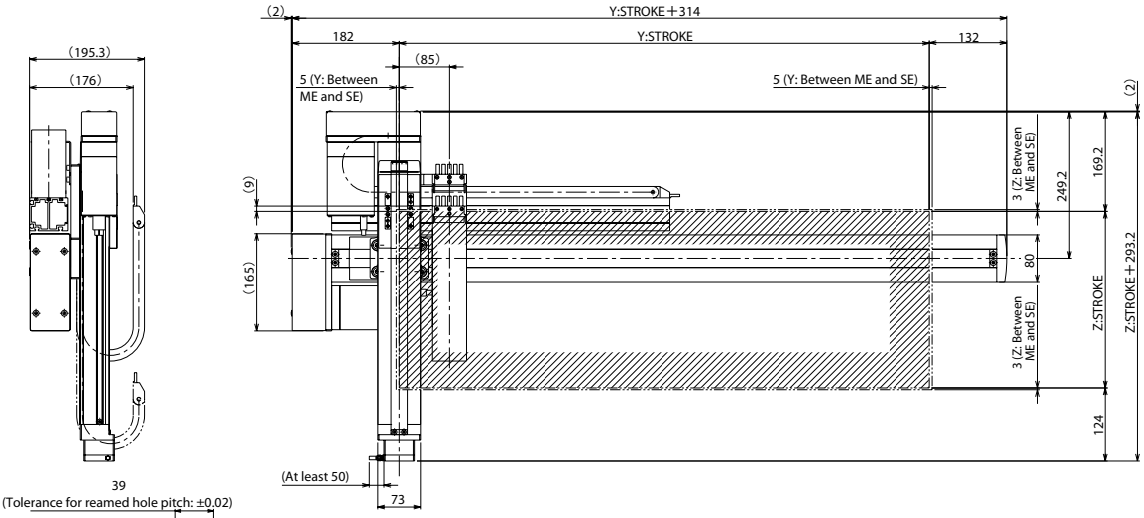
Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

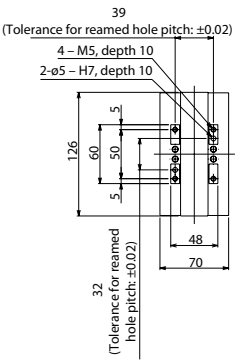


Detail view of Y-axis installation





ME: Mechanical end
SE: Stroke end



Detail view of Z-axis slider

Detail view of slot in bottom face of Y-axis base

Dimensions by Stroke

Y: Model	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
B	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	8	8	8	10	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	149	174	199	224	249	274	299	324	349	374	399	424	449	474	499	524	549	574	599	624

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBD1□□S

RCS2 2-axis Combinations X axis: SS7R (Reversed, Single-slider)
Y axis: SA5R (Reversed)

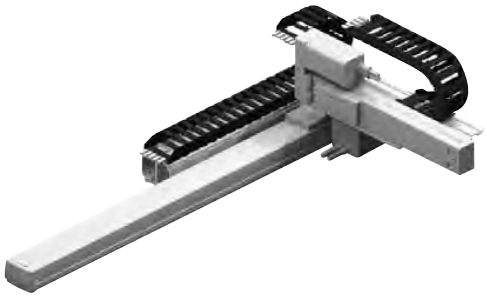
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

IK2 – SXBD1□□S – □ – □ □ – □ □ – □ – □ – □ – □

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; HM: X high-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 600 mm Y axis 200 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	600mm/s	–
Y axis	800mm/s	400mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X high-speed, Y medium-speed
50mm	3.0kg	6.0kg
100mm	3.0kg	6.0kg
150mm	2.5kg	5.0kg
200mm	2.5kg	5.0kg

List by Stroke

		Incremental				Absolute			
	Y-axis stroke	50	100	150	200	50	100	150	200
X-axis stroke	50	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600
		-	-
Wiring 2 (Next to Y-axis)	Y-axis stroke	50-200	–
		-	–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

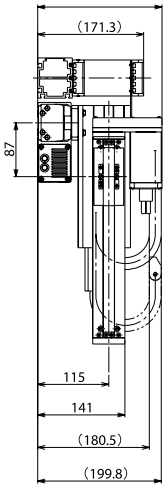
Name	Option code
Opposite-home specification	NM
Slider roller specification	SR

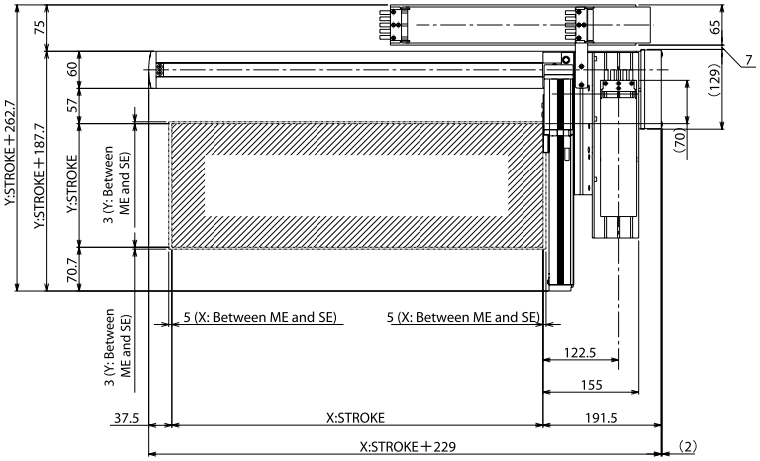
Specifications

Item		X axis		Y axis
Axis model		RCS2-SS7R		RCS2-SA5R
Stroke (Can be set in 50-mm increments)		50-600mm		50-200mm
Max speed	Stroke	50-500mm	550-600mm	50-200mm
	High speed	600mm/s	470mm/s	800mm/s
	Medium speed	-	-	400mm/s
Motor output (W)		60W		20W
Ball screw lead		High-speed type: 12mm		High-speed type: 12mm Medium-speed type: 6mm
Drive method		Ball screw, ø10 mm, rolled, C10		
Positioning repeatability		±0.02mm		
Base material		Dedicated alloy steel		Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)		

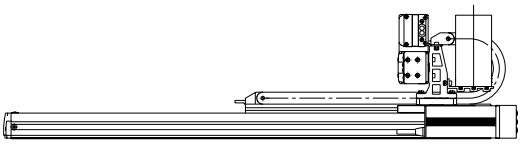
Dimensions

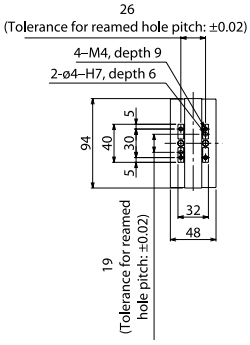
Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.





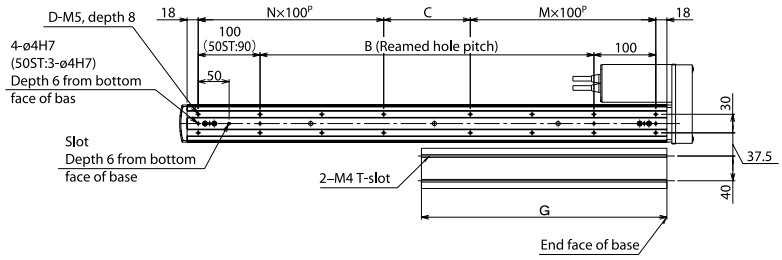
ME: Mechanical end
SE: Stroke end





Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	50	100	150	200	250	300	350	400	450	500	550	600
B	0	40	90	140	190	240	290	340	390	440	490	540
C	90	40	90	140	190	40	90	140	190	40	90	140
D	6	8	8	8	8	12	12	12	12	16	16	16
M	1	1	1	1	1	2	2	2	2	3	3	3
N	0	1	1	1	1	2	2	2	2	3	3	3
G	122	147	172	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBD1□□D

RCS2 2-axis Combinations X axis: SS7R (Reversed, Double-slider)
Y axis: SA5R (Reversed)

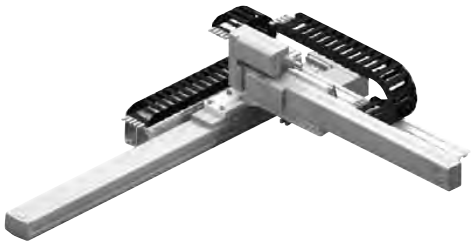
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

IK2 — SXBD1 □□ D — □ — □ □ — □ □ — □ — □ — □ — □ — □

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; HM: X high-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 450 mm Y axis 400 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	600mm/s	–
Y axis	800mm/s	400mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X high-speed, Y medium-speed
250mm	2.5kg	5.0kg
300mm	2.0kg	4.0kg
350mm	2.0kg	4.0kg
400mm	2.0kg	4.0kg

List by Stroke

		Incremental				Absolute			
	Y-axis stroke	250	300	350	400	250	300	350	400
X-axis stroke	50	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-450
		-	-
Wiring 2 (Next to Y-axis)	Y-axis stroke	250-400	–
		-	–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

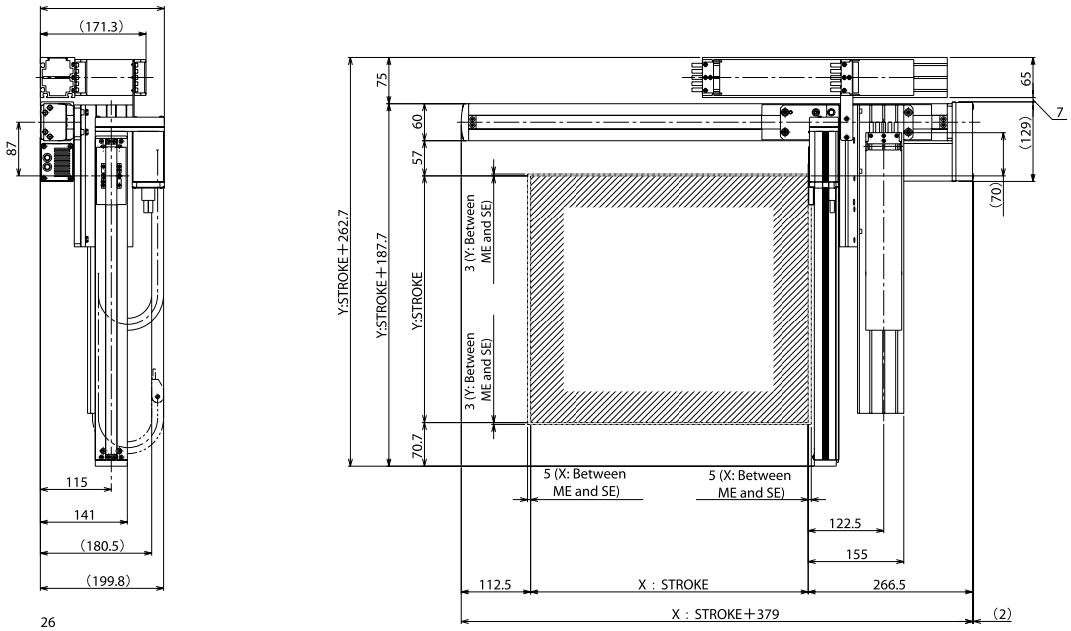
Name	Option code
Opposite-home specification	NM
Slider roller specification	SR

Specifications

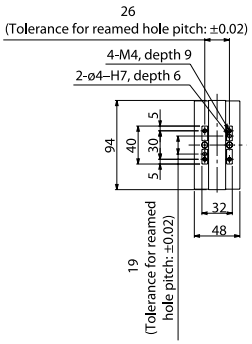
Item		X axis		Y axis
Axis model		RCS2-SS7R		RCS2-SA5R
Stroke (Can be set in 50-mm increments)		50-450mm		250-400mm
Max speed	Stroke	50-350mm	400-450mm	250-400mm
	High speed	600mm/s	470mm/s	800mm/s
	Medium speed	-	-	400mm/s
Motor output (W)		60W		20W
Ball screw lead		High-speed type: 12mm		High-speed type: 12mm Medium-speed type: 6mm
Drive method		Ball screw, ø10 mm, rolled, C10		
Positioning repeatability		±0.02mm		
Base material		Dedicated alloy steel		Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)		

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

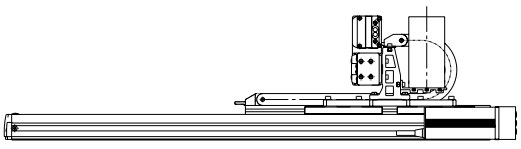


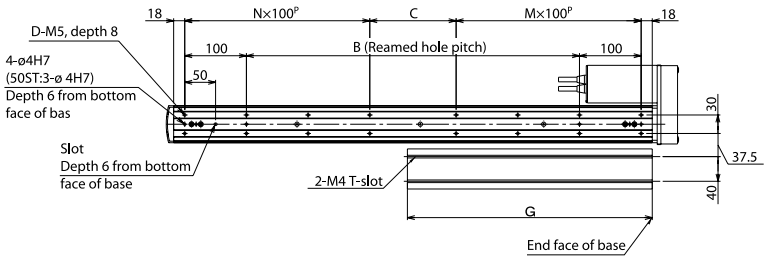
ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base





Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	200	250	300	350	400	450	500	550	600
X: Effective stroke	50	100	150	200	250	300	350	400	450
B	140	190	240	290	340	390	440	490	540
C	140	190	40	90	140	190	40	90	140
D	8	8	12	12	12	12	16	16	16
M	1	1	2	2	2	2	3	3	3
N	1	1	2	2	2	2	3	3	3
G	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBD2□□S

RCS2 2-axis Combinations X axis: SS7C (Reversed, Single-slider)
Y axis: SA5R (Reversed)

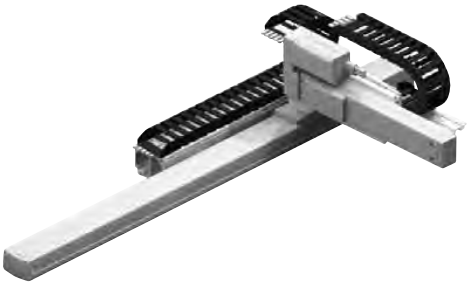
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

IK2 – SXBD2□□S – □ – □ □ – □ □ – □ – □ – □ – □ – □

- Combination directions: 1-4
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; HM: X high-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm … (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 600 mm Y axis 200 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	600mm/s	–
Y axis	800mm/s	400mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X high-speed, Y medium-speed
50mm	3.0kg	6.0kg
100mm	3.0kg	6.0kg
150mm	2.5kg	5.0kg
200mm	2.5kg	5.0kg

List by Stroke

		Incremental				Absolute			
	Y-axis stroke	50	100	150	200	50	100	150	200
X-axis stroke	50	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600
		-	-
Wiring 2 (Next to Y-axis)	Y-axis stroke	50-200	–
		-	–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

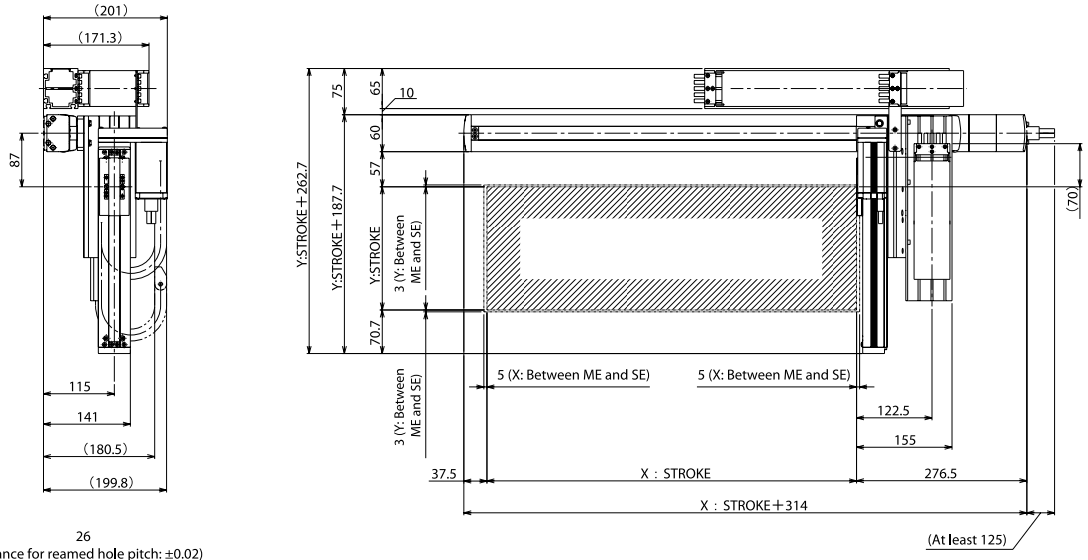
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

Specifications

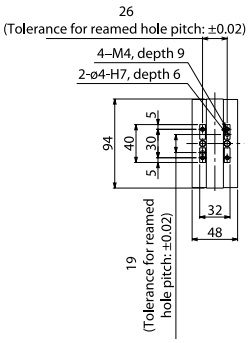
Item		X axis		Y axis
Axis model		RCS2-SS7C		RCS2-SA5R
Stroke (Can be set in 50-mm increments)		50-600mm		50-200mm
Max speed	Stroke	50-500mm	550-600mm	50-200mm
	High speed	600mm/s	470mm/s	800mm/s
	Medium speed	-	-	400mm/s
Motor output (W)		60W		20W
Ball screw lead		High-speed type: 12mm		High-speed type: 12mm Medium-speed type: 6mm
Drive method		Ball screw, ø10 mm, rolled, C10		
Positioning repeatability		±0.02mm		
Base material		Dedicated alloy steel		Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)		

Dimensions

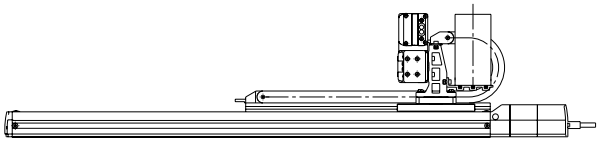
Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.



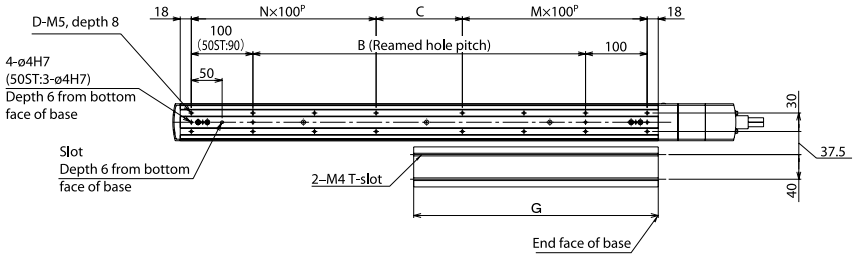
ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider



Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	50	100	150	200	250	300	350	400	450	500	550	600
B	0	40	90	140	190	240	290	340	390	440	490	540
C	90	40	90	140	190	40	90	140	190	40	90	140
D	6	8	8	8	8	12	12	12	12	16	16	16
M	1	1	1	1	1	2	2	2	2	3	3	3
N	0	1	1	1	1	2	2	2	2	3	3	3
G	122	147	172	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBD2□□D

RCS2 2-axis Combinations X axis: SS7C (Straight, Double-slider)
Y axis: SA5R (Reversed)

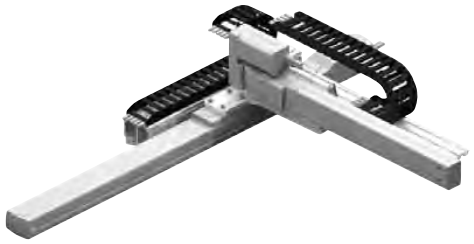
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

IK2 — SXBD2 □□ D — □ — □ □ — □ □ — □ — □ — □ — □ — □

- Combination directions: 1-4
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; HM: X high-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 450 mm Y axis 400 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	600mm/s	–
Y axis	800mm/s	400mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X high-speed, Y medium-speed
250mm	2.5kg	5.0kg
300mm	2.0kg	4.0kg
350mm	2.0kg	4.0kg
400mm	2.0kg	4.0kg

List by Stroke

		Incremental				Absolute			
	Y-axis stroke	250	300	350	400	250	300	350	400
X-axis stroke	50	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-450
		-	-
Wiring 2 (Next to Y-axis)	Y-axis stroke	250-400	–
		-	–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

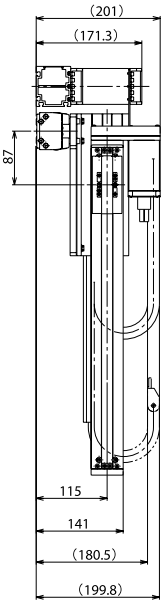
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

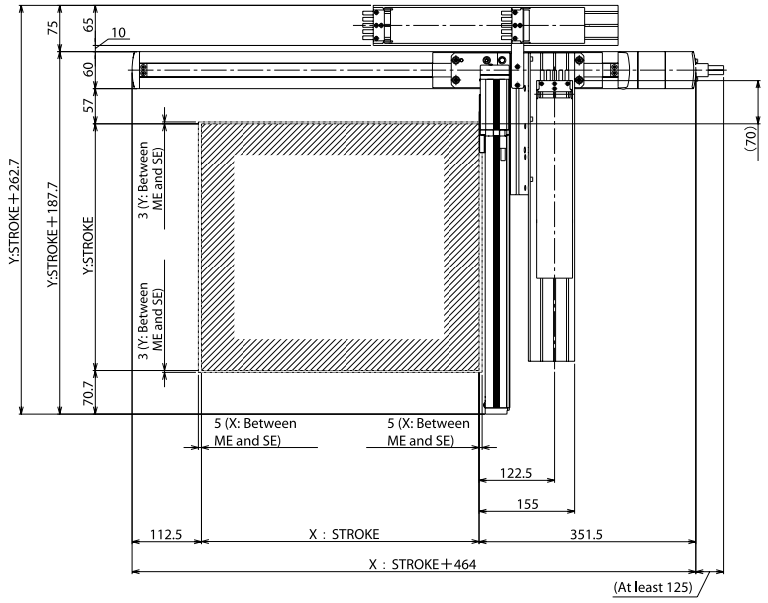
Specifications

Item		X axis		Y axis
Axis model		RCS2-SS7C		RCS2-SA5R
Stroke (Can be set in 50-mm increments)		50-450mm		250-400mm
Max speed	Stroke	50-350mm	400-450mm	250-400mm
	High speed	600mm/s	470mm/s	800mm/s
	Medium speed	-	-	400mm/s
Motor output (W)		60W		20W
Ball screw lead		High-speed type: 12mm		High-speed type: 12mm Medium-speed type: 6mm
Drive method		Ball screw, ø10 mm, rolled, C10		
Positioning repeatability		±0.02mm		
Base material		Dedicated alloy steel		Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)		

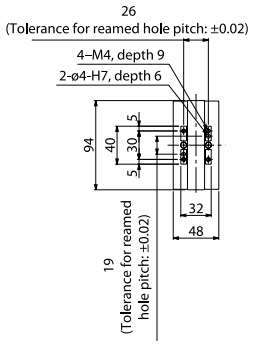
Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.



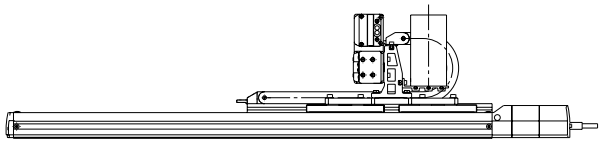


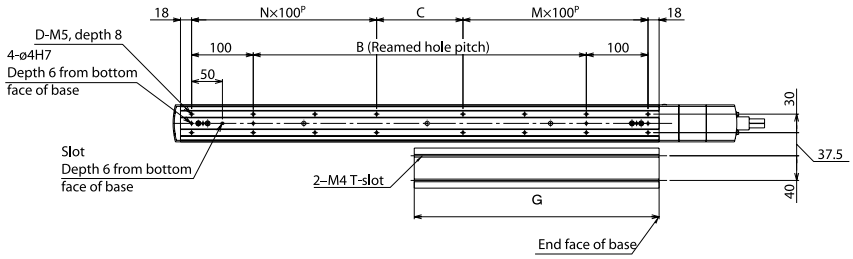
ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base





Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	200	250	300	350	400	450	500	550	600
X: Effective stroke	50	100	150	200	250	300	350	400	450
B	140	190	240	290	340	390	440	490	540
C	140	190	40	90	140	190	40	90	140
D	8	8	12	12	12	12	16	16	16
M	1	1	2	2	2	2	3	3	3
N	1	1	2	2	2	2	3	3	3
G	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBC1□□S

RCS2 2-axis Combinations X axis: SS7R (Reversed, Single-slider)
Y axis: SA6R (Reversed)

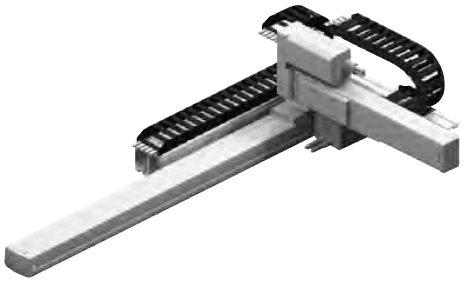
■Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

IK2 – SXBC1 □□S – □ – □ □ – □ □ – □ – □ – □ – □

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

■Maximum Stroke

X axis 600 mm　　Y axis 200 mm

■Maximum Speed

	High-speed type	Medium-speed type
X axis	600mm/s	300mm/s
Y axis	800mm/s	400mm/s

■Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
50mm	4.5kg	9.0kg
100mm	4.5kg	9.0kg
150mm	4.0kg	8.0kg
200mm	3.0kg	6.0kg

List by Stroke

		Incremental				Absolute			
	Y-axis stroke	50	100	150	200	50	100	150	200
X-axis stroke	50	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600
			-
Wiring 2 (Next to Y-axis)	Y-axis stroke	50-200	–
			–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

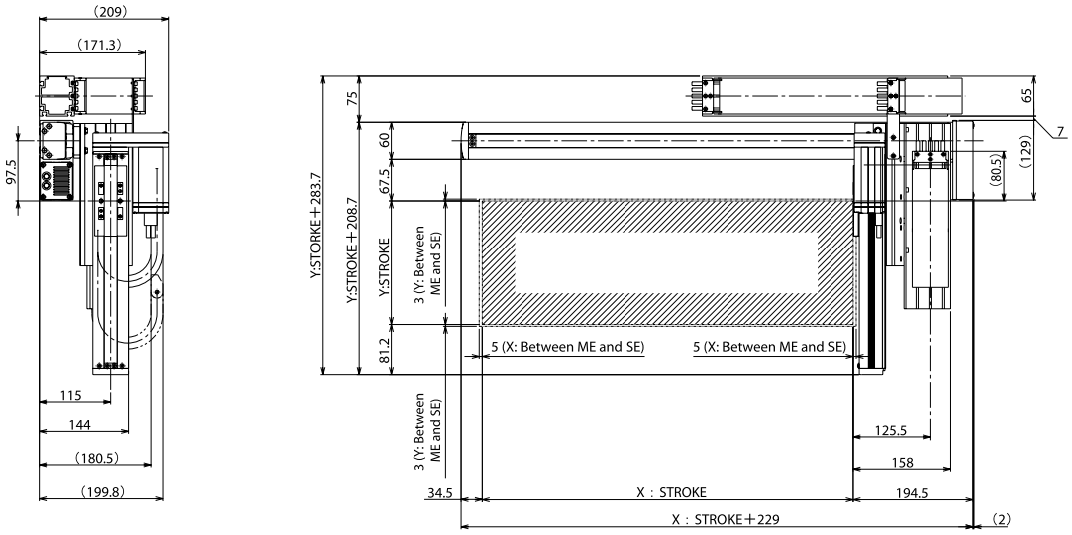
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

Specifications

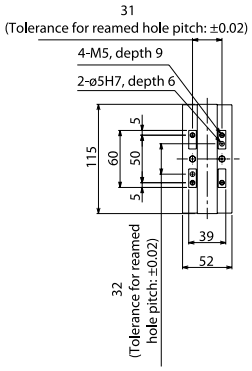
Item		X axis		Y axis
Axis model		RCS2-SS7R		RCS2-SA6R
Stroke (Can be set in 50-mm increments)		50-600mm		50-200mm
Max speed	Stroke	50-500mm	550-600mm	50-200mm
	High speed	600mm/s	470mm/s	800mm/s
	Medium speed	300mm/s	230mm/s	400mm/s
Motor output (W)		60W		30W
Ball screw lead		High-speed type: 12mm Medium-speed type: 6mm		
Drive method		Ball screw, ø10 mm, rolled, C10		
Positioning repeatability		±0.02mm		
Base material		Dedicated alloy steel		Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)		

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

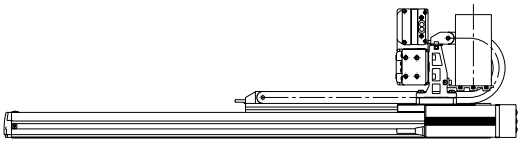


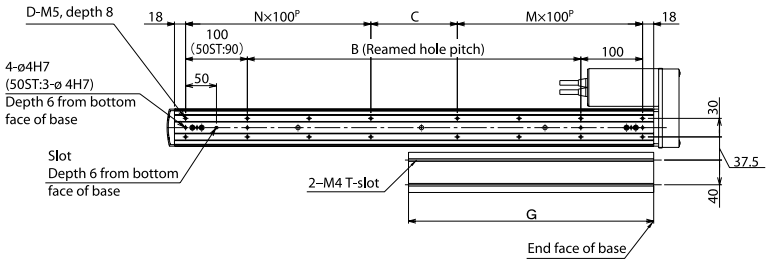
ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base





Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	50	100	150	200	250	300	350	400	450	500	550	600
B	0	40	90	140	190	240	290	340	390	440	490	540
C	90	40	90	140	190	40	90	140	190	40	90	140
D	6	8	8	8	8	12	12	12	12	16	16	16
M	1	1	1	1	1	2	2	2	2	3	3	3
N	0	1	1	1	1	2	2	2	2	3	3	3
G	122	147	172	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBC1□□D

RCS2 2-axis Combinations X axis: SS7R (Reversed, Double-slider)
Y axis: SA6R (Reversed)

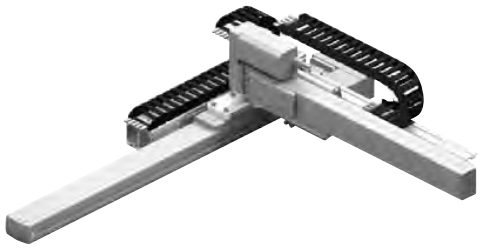
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

IK2 — SXBC1 □□D — □ — □ □ — □ □ — □ — □ — □ — □

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 450 mm　　Y axis 400 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	600mm/s	300mm/s
Y axis	800mm/s	400mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
250mm	3.0kg	6.0kg
300mm	3.0kg	6.0kg
350mm	3.0kg	6.0kg
400mm	3.0kg	6.0kg

List by Stroke

X-axis stroke \ Y-axis stroke	Incremental 250	300	350	400	Absolute 250	300	350	400
50	–	–	–	–	–	–	–	–
100	–	–	–	–	–	–	–	–
150	–	–	–	–	–	–	–	–
200	–	–	–	–	–	–	–	–
250	–	–	–	–	–	–	–	–
300	–	–	–	–	–	–	–	–
350	–	–	–	–	–	–	–	–
400	–	–	–	–	–	–	–	–
450	–	–	–	–	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-450
			-
Wiring 2 (Next to Y-axis)	Y-axis stroke	250-400	–
			–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

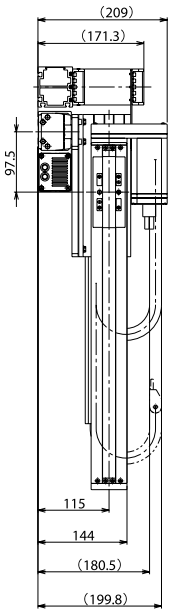
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

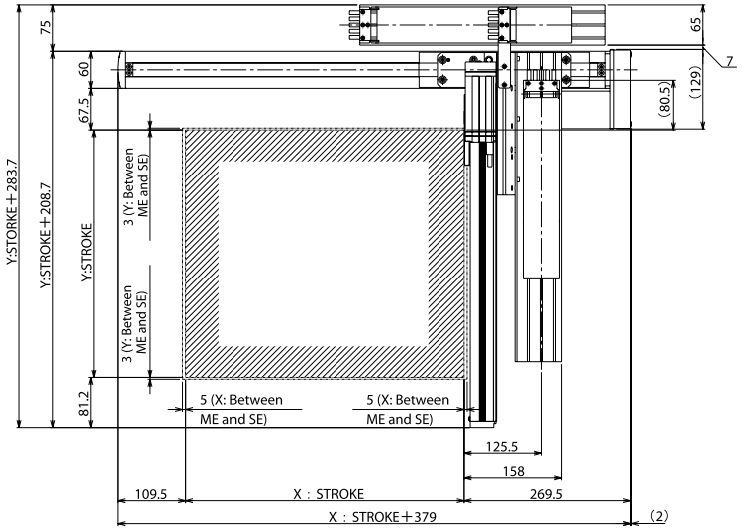
Specifications

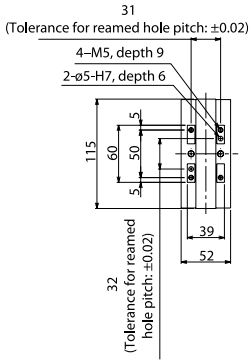
Item		X axis		Y axis
Axis model		RCS2-SS7R		RCS2-SA6R
Stroke (Can be set in 50-mm increments)		50-450mm		250-400mm
Max speed	Stroke	50-350mm	400-450mm	250-400mm
	High speed	600mm/s	470mm/s	800mm/s
	Medium speed	300mm/s	230mm/s	400mm/s
Motor output (W)		60W		30W
Ball screw lead		High-speed type: 12mm Medium-speed type: 6mm		
Drive method		Ball screw, ø10 mm, rolled, C10		
Positioning repeatability		±0.02mm		
Base material		Dedicated alloy steel		Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)		

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.



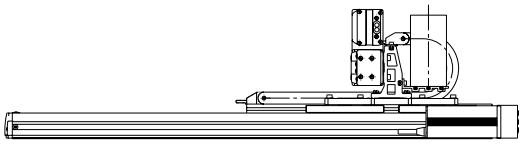


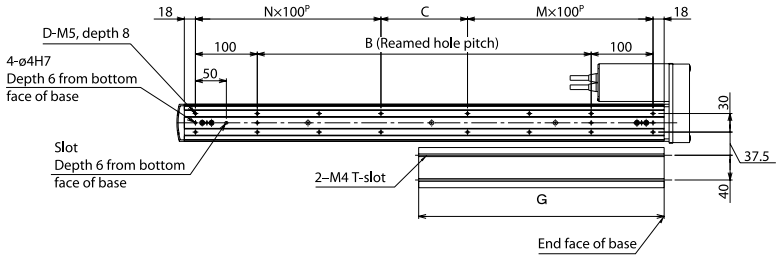


Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base

ME: Mechanical end
SE: Stroke end





Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	200	250	300	350	400	450	500	550	600
X: Effective stroke	50	100	150	200	250	300	350	400	450
B	140	190	240	290	340	390	440	490	540
C	140	190	40	90	140	190	40	90	140
D	8	8	12	12	12	12	16	16	16
M	1	1	2	2	2	2	3	3	3
N	1	1	2	2	2	2	3	3	3
G	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBC2□□S

RCS2 2-axis Combinations X axis: SS7C (Straight, Single-slider)
Y axis: SA6R (Reversed)

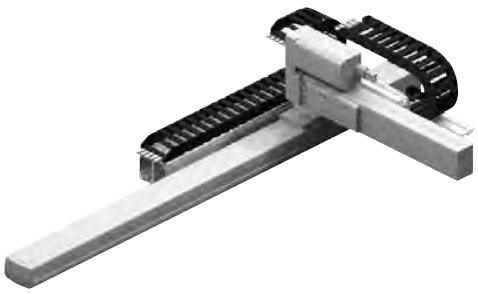
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

IK2 — SXBC2 □□ S — □ — □ □ — □ □ — □ — □ — □ — □ — □

- Combination directions: 1-4
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 600 mm Y axis 200 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	600mm/s	300mm/s
Y axis	800mm/s	400mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
50mm	4.5kg	9.0kg
100mm	4.5kg	9.0kg
150mm	4.0kg	8.0kg
200mm	3.0kg	6.0kg

List by Stroke

		Incremental				Absolute			
	Y-axis stroke	50	100	150	200	50	100	150	200
X-axis stroke	50	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600
			-
Wiring 2 (Next to Y-axis)	Y-axis stroke	50-200	–
			–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

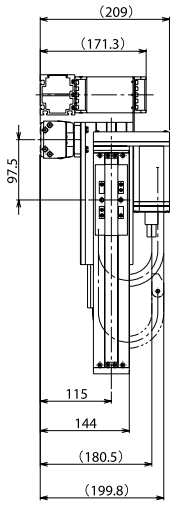
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

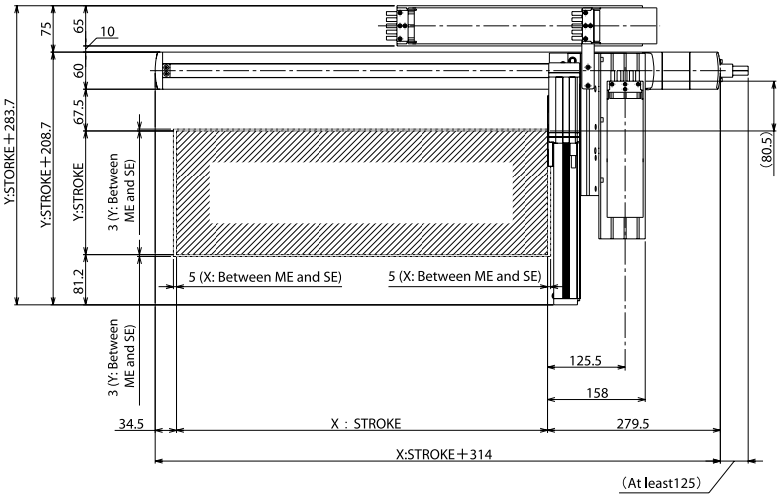
Specifications

Item		X axis		Y axis
Axis model		RCS2-SS7C		RCS2-SA6R
Stroke (Can be set in 50-mm increments)		50-600mm		50-200mm
Max speed	Stroke	50-500mm	550-600mm	50-200mm
	High speed	600mm/s	470mm/s	800mm/s
	Medium speed	300mm/s	230mm/s	400mm/s
Motor output (W)		60W		30W
Ball screw lead		High-speed type: 12mm Medium-speed type: 6mm		
Drive method		Ball screw, ø10 mm, rolled, C10		
Positioning repeatability		±0.02mm		
Base material		Dedicated alloy steel		Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)		

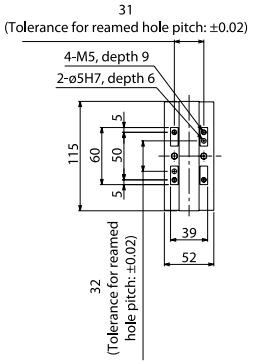
Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

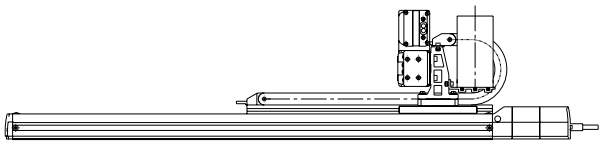




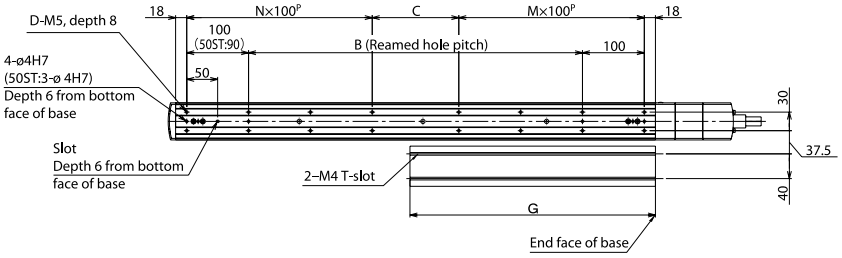
ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider



Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	50	100	150	200	250	300	350	400	450	500	550	600
B	0	40	90	140	190	240	290	340	390	440	490	540
C	90	40	90	140	190	40	90	140	190	40	90	140
D	6	8	8	8	8	12	12	12	12	16	16	16
M	1	1	1	1	1	2	2	2	2	3	3	3
N	0	1	1	1	1	2	2	2	2	3	3	3
G	122	147	172	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBC2□□D

RCS2 2-axis Combinations X axis: SS7C (Straight, Double-slider)
Y axis: SA6R (Reversed)

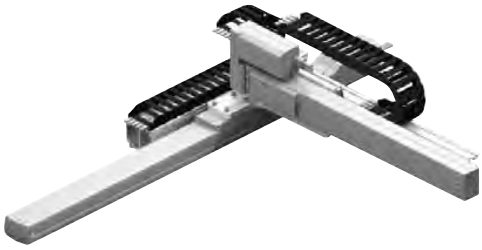
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

IK2 — SXBC2 □□D — □ — □ □ — □ □ — □ — □ — □ — □

- Combination directions: 1-4
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K, SSEL, XSEL-P/Q; T2: XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 450 mm

Y axis 400 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	600mm/s	300mm/s
Y axis	800mm/s	400mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
250mm	3.0kg	6.0kg
300mm	3.0kg	6.0kg
350mm	3.0kg	6.0kg
400mm	3.0kg	6.0kg

List by Stroke

		Incremental				Absolute			
	Y-axis stroke	250	300	350	400	250	300	350	400
X-axis stroke	50	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-450
			-
Wiring 2 (Next to Y-axis)	Y-axis stroke	250-400	–
			–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

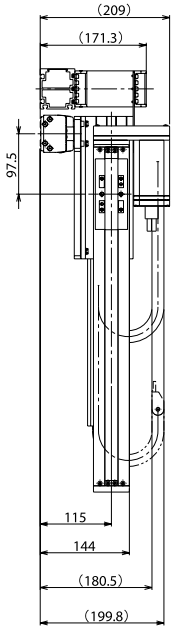
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

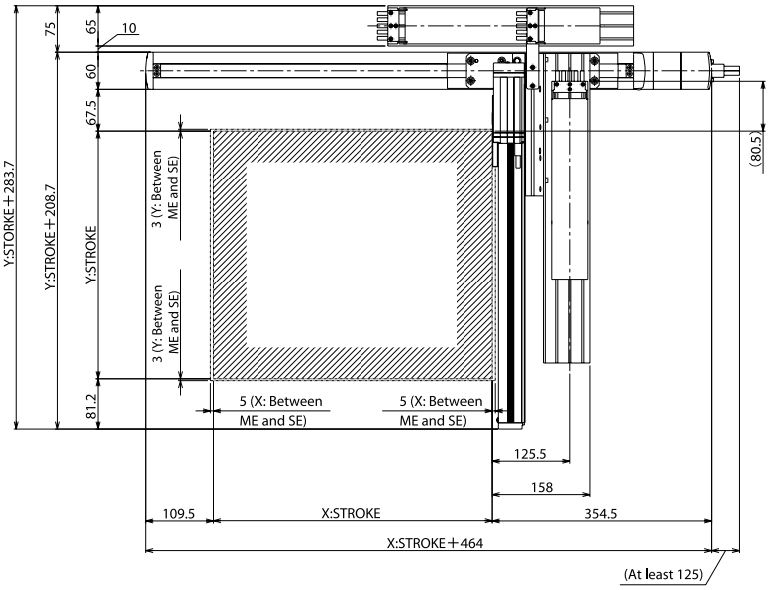
Specifications

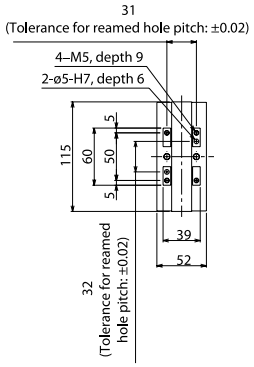
Item		X axis		Y axis
Axis model		RCS2-SS7C		RCS2-SA6R
Stroke (Can be set in 50-mm increments)		50-450mm		250-400mm
Max speed	Stroke	50-350mm	400-450mm	250-400mm
	High speed	600mm/s	470mm/s	800mm/s
	Medium speed	300mm/s	230mm/s	400mm/s
Motor output (W)		60W		30W
Ball screw lead		High-speed type: 12mm Medium-speed type: 6mm		
Drive method		Ball screw, ø10 mm, rolled, C10		
Positioning repeatability		±0.02mm		
Base material		Dedicated alloy steel		Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)		

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.



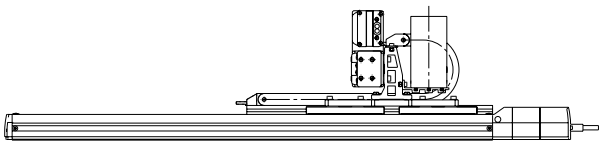


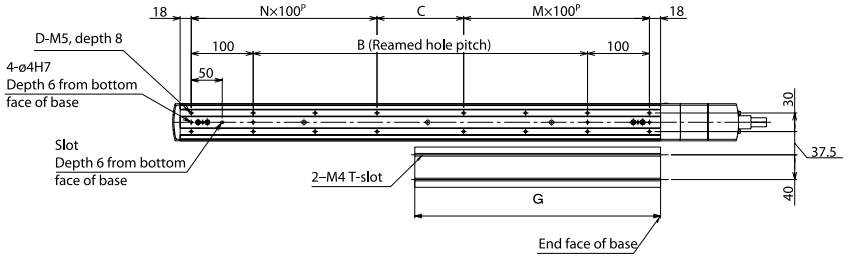


Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base

ME: Mechanical end
SE: Stroke end





Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	200	250	300	350	400	450	500	550	600
X: Effective stroke	50	100	150	200	250	300	350	400	450
B	140	190	240	290	340	390	440	490	540
C	140	190	40	90	140	190	40	90	140
D	8	8	12	12	12	12	16	16	16
M	1	1	2	2	2	2	3	3	3
N	1	1	2	2	2	2	3	3	3
G	197	222	247	272	297	322	347	372	397

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBB1□□S

RCS2 2-axis Combinations X axis: SS8R (100W, Reversed, Single-slider)
Y axis: SA7R (Reversed)

Model Details

IK2 — SXBB1□□S — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.

Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 1000 mm　　Y axis 300 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	1000mm/s	500mm/s
Y axis	800mm/s	400mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
50mm	8.0kg	16kg
100mm	8.0kg	16kg
150mm	7.0kg	15kg
200mm	7.0kg	12.5kg
250mm	6.0kg	9.0kg
300mm	6.0kg	8.0kg

List by Stroke

		Incremental						Absolute					
	Y-axis stroke	50	100	150	200	250	300	50	100	150	200	250	300
X-axis stroke	50	–	–	–	–	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–	–	–	–	–
	850	–	–	–	–	–	–	–	–	–	–	–	–
	900	–	–	–	–	–	–	–	–	–	–	–	–
	950	–	–	–	–	–	–	–	–	–	–	–	–
	1000	–	–	–	–	–	–	–	–	–	–	–	–

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600	650-900	950-1000
Wiring 2 (Next to Y-axis)	Y-axis stroke	50-200	250-300	–	–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List of Options

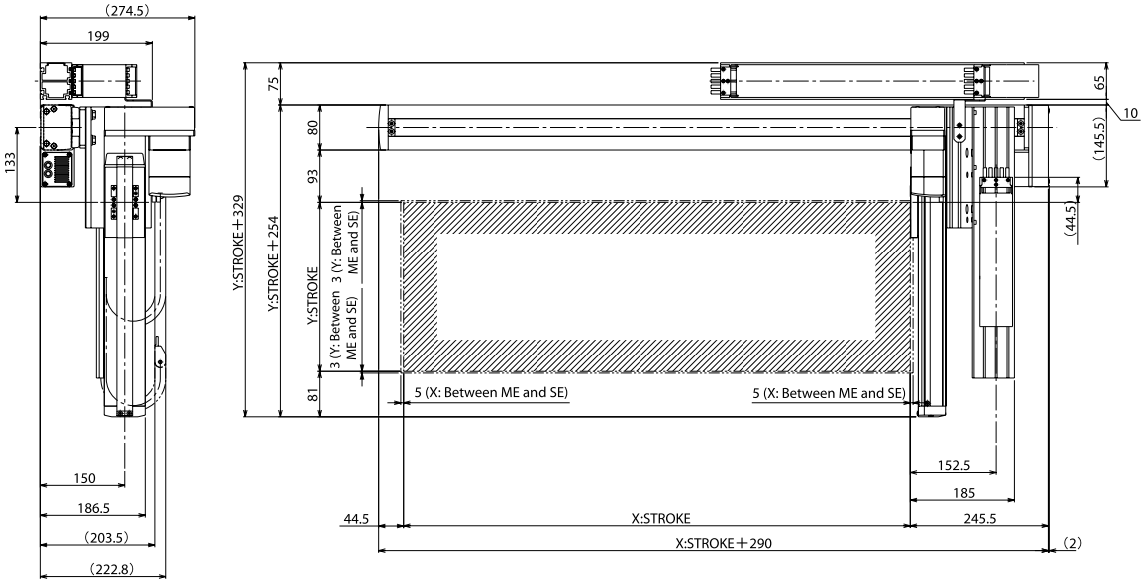
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

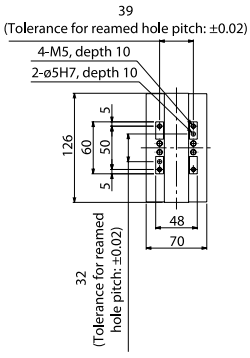
Specifications

Item		X axis					Y axis
Axis model		RCS2-SS8R					RCS2-SA7R
Stroke (Can be set in 50-mm increments)		50-1000mm					50-300mm
Max speed	Stroke	50-600mm	650-700mm	750-800mm	850-900mm	950-1000mm	50-300mm
	High speed	1000mm/s	960mm/s	765mm/s	625mm/s	515mm/s	800mm/s
	Medium speed	500mm/s	480mm/s	380mm/s	310mm/s	255mm/s	400mm/s
Motor output (W)		100W					60W
Ball screw lead		High-speed type: 20mm Medium-speed type: 10mm					High-speed type: 16mm Medium-speed type: 8mm
Drive method		Ball screw, ø16 mm, rolled, C10					Ball screw, ø12 mm, rolled, C10
Positioning repeatability		±0.02mm					
Base material		Dedicated alloy steel					Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)					

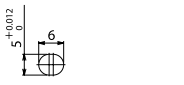
Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

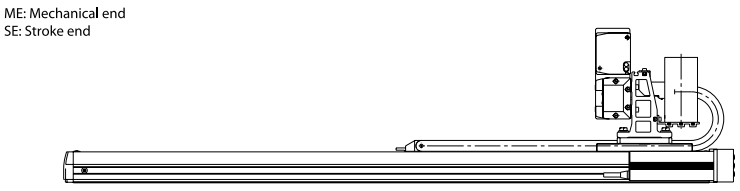


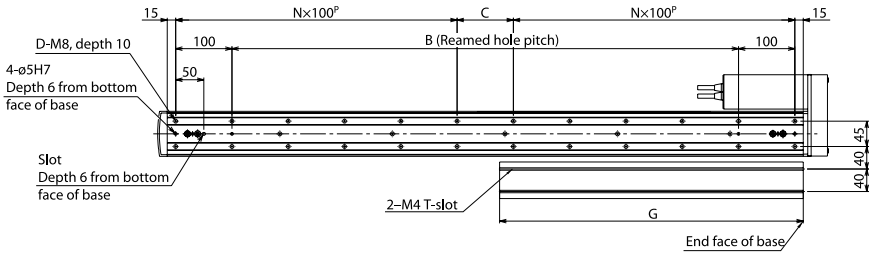


Detail view of Y-axis slider



Detail view of slot in bottom face of X-axis base





Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
B	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	8	8	8	10	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	114.5	139.5	164.5	189.5	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBB1□□D

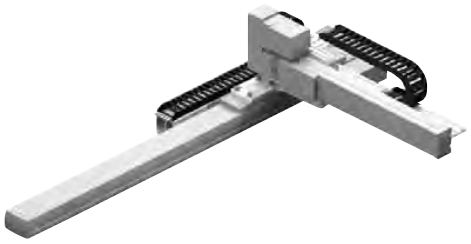
RCS2 2-axis Combinations X axis: SS8R (100W, Reversed, Double-slider)
Y axis: SA7R (Reversed)

Model Details

IK2 – SXBB1 □□D – Encoder type – Axis 1 (X axis) – Axis 2 (Y axis) – Controllres – Cable – Shipping configuration

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 800 mm Y axis 400 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	1000mm/s	500mm/s
Y axis	800mm/s	400mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
200mm	–	15kg
250mm	–	12.5kg
300mm	–	12.5kg
350mm	6.0kg	12kg
400mm	5.5kg	10.5kg

List by Stroke

X-axis stroke \ Y-axis stroke	Incremental 200	250	300	350	400	Absolute 200	250	300	350	400
50	–	–	–	–	–	–	–	–	–	–
100	–	–	–	–	–	–	–	–	–	–
150	–	–	–	–	–	–	–	–	–	–
200	–	–	–	–	–	–	–	–	–	–
250	–	–	–	–	–	–	–	–	–	–
300	–	–	–	–	–	–	–	–	–	–
350	–	–	–	–	–	–	–	–	–	–
400	–	–	–	–	–	–	–	–	–	–
450	–	–	–	–	–	–	–	–	–	–
500	–	–	–	–	–	–	–	–	–	–
550	–	–	–	–	–	–	–	–	–	–
600	–	–	–	–	–	–	–	–	–	–
650	–	–	–	–	–	–	–	–	–	–
700	–	–	–	–	–	–	–	–	–	–
750	–	–	–	–	–	–	–	–	–	–
800	–	–	–	–	–	–	–	–	–	–

Note: For the X high-speed/Y high-speed type, the Y-axis stroke must be 350 mm or more.

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600	650-800
Wiring 2 (Next to Y-axis)	Y-axis stroke	200	250-400	–
				–

List of Options

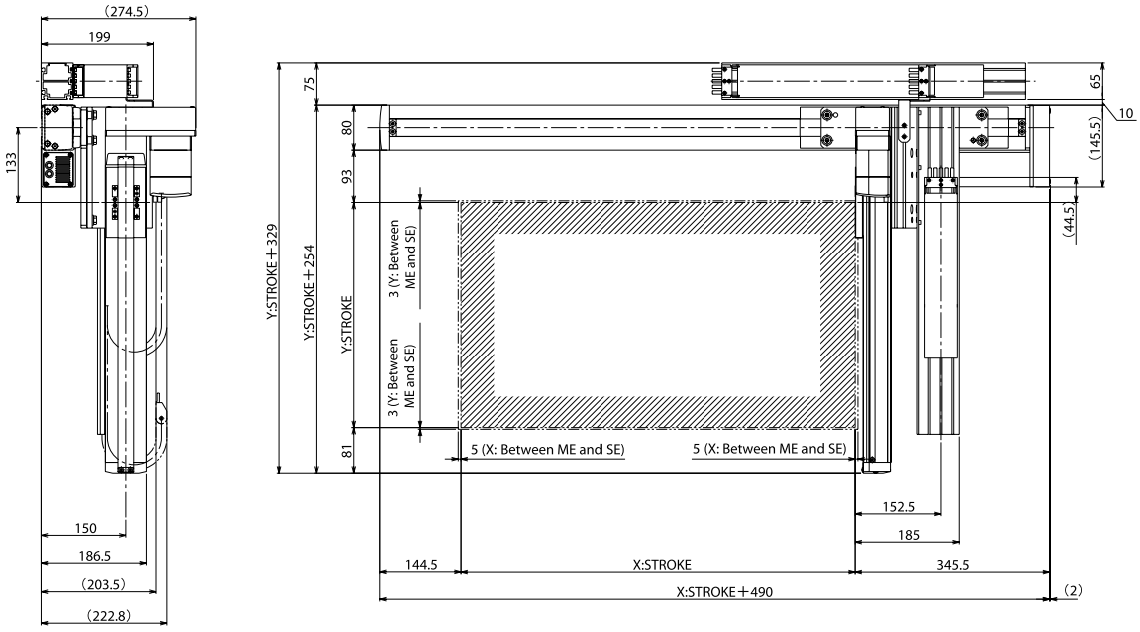
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

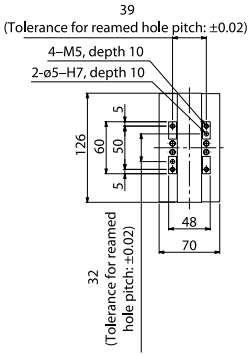
Specifications

Item		X axis					Y axis
Axis model		RCS2-SS8R					RCS2-SA7R
Stroke (Can be set in 50-mm increments)		50-800mm					High-speed type: 350-400mm Medium-speed type: 200-400mm
Max speed	Stroke	50-400mm	450-500mm	550-600mm	650-700mm	750-800mm	200-400mm
	High speed	1000mm/s	960mm/s	765mm/s	625mm/s	515mm/s	800mm/s
	Medium speed	500mm/s	480mm/s	380mm/s	310mm/s	255mm/s	400mm/s
Motor output (W)		100W					60W
Ball screw lead		High-speed type: 20mm Medium-speed type: 10mm					High-speed type: 16mm Medium-speed type: 8mm
Drive method		Ball screw, ø16 mm, rolled, C10					Ball screw, ø12 mm, rolled, C10
Positioning repeatability		±0.02mm					
Base material		Dedicated alloy steel					Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)					

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

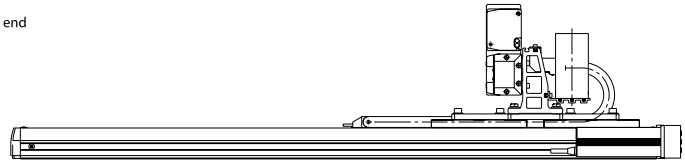


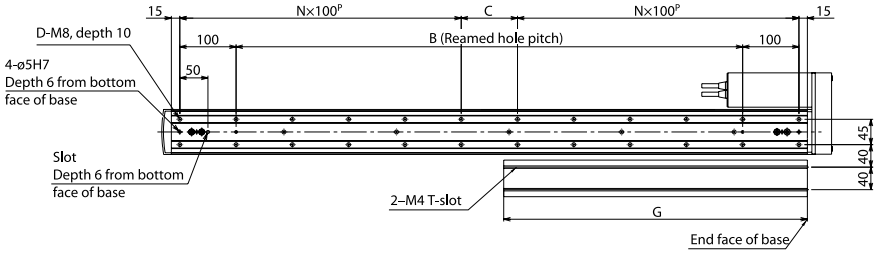


Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base

ME: Mechanical end
SE: Stroke end





Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
X: Effective stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
B	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBB2□□S

RCS2 2-axis Combinations X axis: SS8C (100W, Straight, Single-slider)
Y axis: SA7R (Reversed)

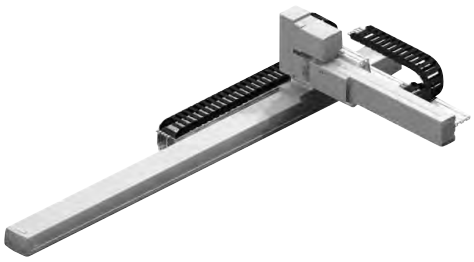
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

IK2 — SXBB2 □□ S — □ — □ □ — □ □ — □ — □ — □ — □

- Combination directions: 1-4
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 1000 mm　　Y axis 300 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	1000mm/s	500mm/s
Y axis	800mm/s	400mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
50mm	8.0kg	16kg
100mm	8.0kg	16kg
150mm	7.0kg	15kg
200mm	7.0kg	12.5kg
250mm	6.0kg	9.0kg
300mm	6.0kg	8.0kg

List by Stroke

		Incremental						Absolute					
	Y-axis stroke	50	100	150	200	250	300	50	100	150	200	250	300
X-axis stroke	50	–	–	–	–	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–	–	–	–	–
	850	–	–	–	–	–	–	–	–	–	–	–	–
	900	–	–	–	–	–	–	–	–	–	–	–	–
	950	–	–	–	–	–	–	–	–	–	–	–	–
	1000	–	–	–	–	–	–	–	–	–	–	–	–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600	650-900	950-1000
Wiring 2 (Next to Y-axis)	Y-axis stroke	50-200	250-300	–	–
				–	–

List of Options

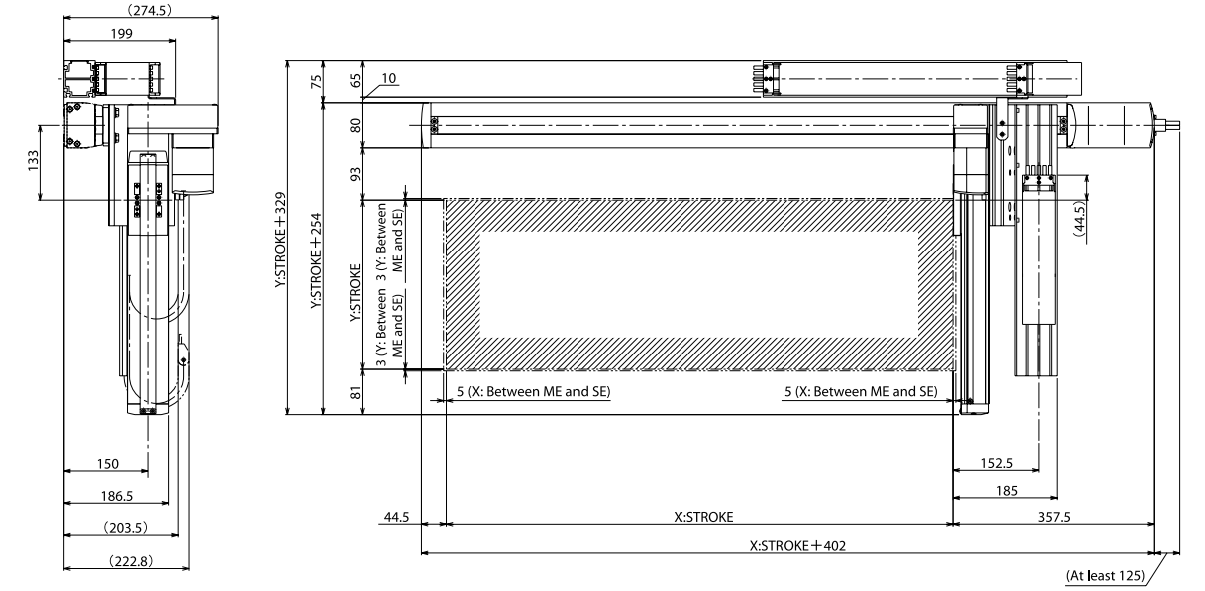
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

Specifications

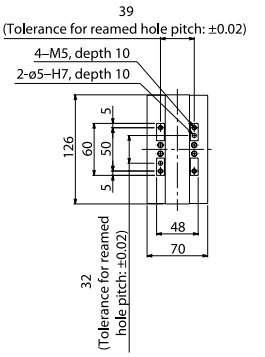
Item		X axis					Y axis
Axis model		RCS2-SS8C					RCS2-SA7R
Stroke (Can be set in 50-mm increments)		50-1000mm					50-300mm
Max speed	Stroke	50-600mm	650-700mm	750-800mm	850-900mm	950-1000mm	50-300mm
	High speed	1000mm/s	960mm/s	765mm/s	625mm/s	515mm/s	800mm/s
	Medium speed	500mm/s	480mm/s	380mm/s	310mm/s	255mm/s	400mm/s
Motor output (W)		100W					60W
Ball screw lead		High-speed type: 20mm Medium-speed type: 10mm					High-speed type: 16mm Medium-speed type: 8mm
Drive method		Ball screw, ø16 mm, rolled, C10					Ball screw, ø12 mm, rolled, C10
Positioning repeatability		±0.02mm					
Base material		Dedicated alloy steel					Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)					

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

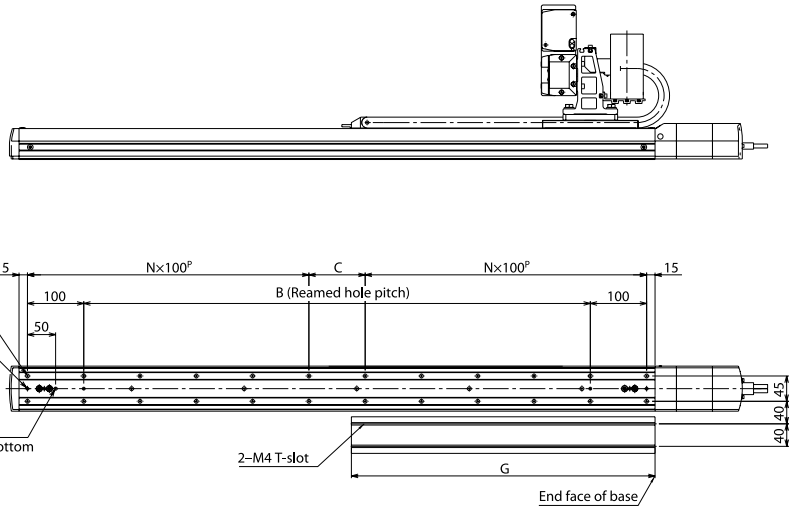


ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
B	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	8	8	8	10	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	114.5	139.5	164.5	189.5	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBB2□□D

RCS2 2-axis Combinations X axis: SS8C (100W, Straight, Double-slider)
Y axis: SA7R (Reversed)

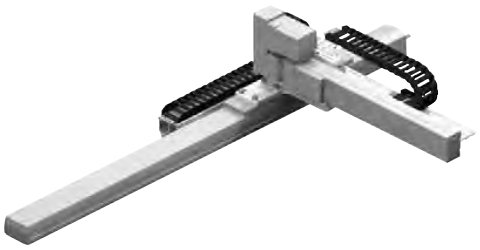
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

IK2 — SXBB2 □□ D — □ — □ □ — □ □ — □ — □ — □ — □

- Combination directions: 1-4
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 800 mm Y axis 400 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	1000mm/s	500mm/s
Y axis	800mm/s	400mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
200mm	–	15kg
250mm	–	12.5kg
300mm	–	12.5kg
350mm	6.0kg	12kg
400mm	5.5kg	10.5kg

List by Stroke

		Incremental					Absolute				
	Y-axis stroke	200	250	300	350	400	200	250	300	350	400
X-axis stroke	50	–	–	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–	–	–

Note: For the X high-speed/Y high-speed type, the Y-axis stroke must be 350 mm or more.

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600	650-800
Wiring 2 (Next to Y-axis)	Y-axis stroke	200	250-400	–
				–

List of Options

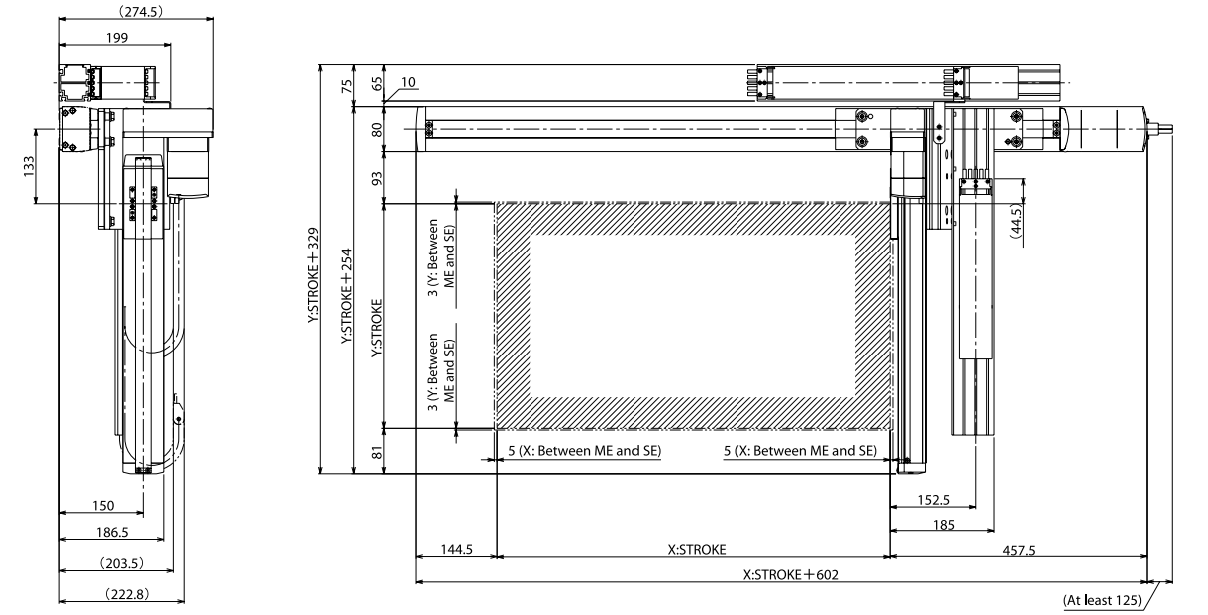
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

Specifications

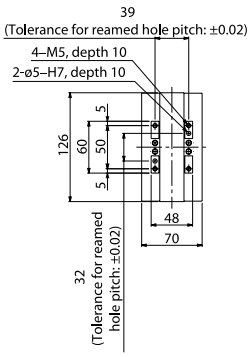
Item		X axis					Y axis
Axis model		RCS2-SS8C					RCS2-SA7R
Stroke (Can be set in 50-mm increments)		50-800mm					High-speed type: 350-400mm Medium-speed type: 200-400mm
Max speed	Stroke	50-400mm	450-500mm	550-600mm	650-700mm	750-800mm	200-400mm
	High speed	1000mm/s	960mm/s	765mm/s	625mm/s	515mm/s	800mm/s
	Medium speed	500mm/s	480mm/s	380mm/s	310mm/s	255mm/s	400mm/s
Motor output (W)		100W					60W
Ball screw lead		High-speed type: 20mm Medium-speed type: 10mm					High-speed type: 16mm Medium-speed type: 8mm
Drive method		Ball screw, ø16 mm, rolled, C10					Ball screw, ø12 mm, rolled, C10
Positioning repeatability		±0.02mm					
Base material		Dedicated alloy steel					Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)					

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

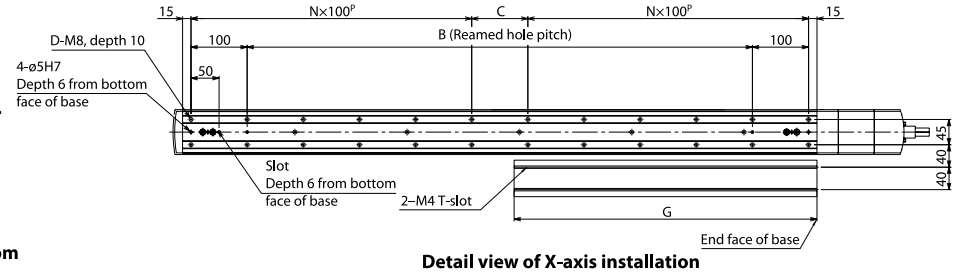


ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
X: Effective stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
B	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBA1□□S

RCS2 2-axis Combinations X axis: SS8R (150W, Reversed, Single-slider)
Y axis: SS8R (100W, Reversed)

Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

IK2 – SXBA1□□S – □ – □ □ – □ □ – □ – □ – □ – □

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.

Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 1000 mm Y axis 350 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	1000mm/s	500mm/s
Y axis	1000mm/s	500mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
50mm	12kg	24kg
100mm	12kg	20.5kg
150mm	11.5kg	15.5kg
200mm	11kg	12.5kg
250mm	10kg	–
300mm	8.5kg	–
350mm	7kg	–

List by Stroke

		Incremental							Absolute						
	Y-axis stroke	50	100	150	200	250	300	350	50	100	150	200	250	300	350
X-axis stroke	50	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	850	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	900	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	950	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	1000	–	–	–	–	–	–	–	–	–	–	–	–	–	–

Note: For the X medium-speed/Y medium-speed type, the Y-axis stroke must be 200 mm or less.

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600	650-900	950-1000
Wiring 2 (Next to Y-axis)	Y-axis stroke	50-200	250-300	–	–
				–	–

List of Options

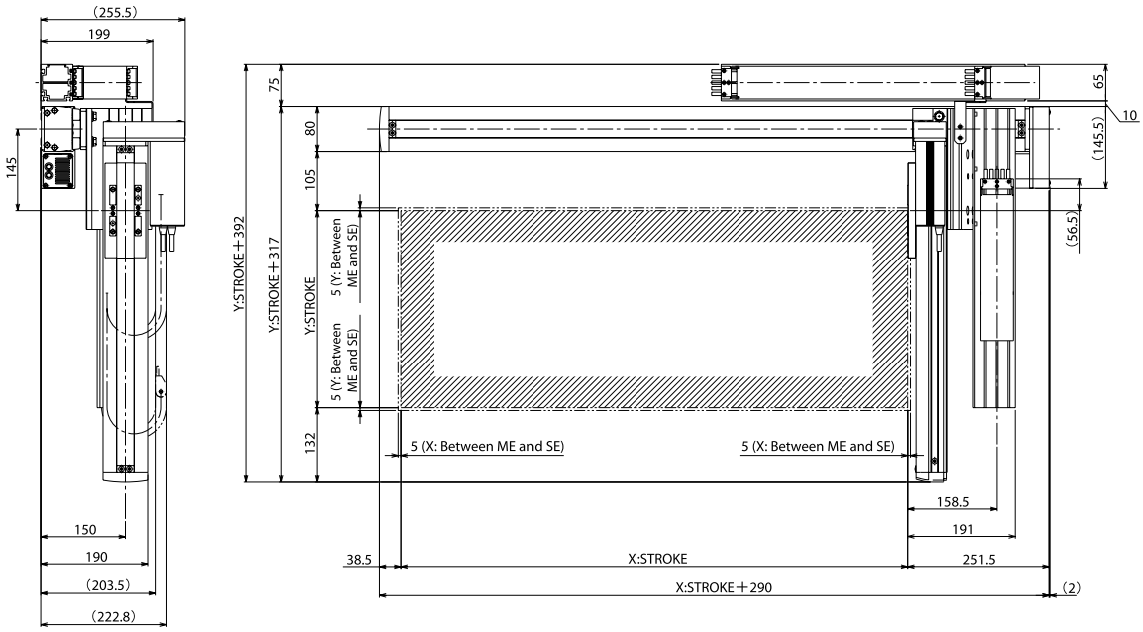
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

Specifications

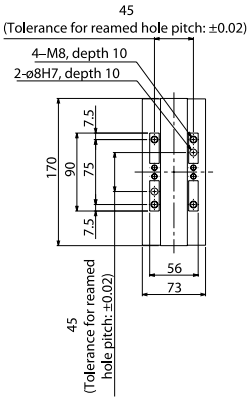
Item		X axis					Y axis
Axis model		RCS2-SS8R					RCS2-SS8R
Stroke (Can be set in 50-mm increments)		50-1000mm					High-speed type: 50-350mm Medium-speed type: 50-200mm
Max speed	Stroke	50-600mm	650-700mm	750-800mm	850-900mm	950-1000mm	50-350mm
	High speed	1000mm/s	960mm/s	765mm/s	625mm/s	515mm/s	1000mm/s
	Medium speed	500mm/s	480mm/s	380mm/s	310mm/s	255mm/s	500mm/s
Motor output (W)		150W					100W
Ball screw lead		High-speed type: 20mm Medium-speed type: 10mm					
Drive method		Ball screw, ø16 mm, rolled, C10					
Positioning repeatability		±0.02mm					
Base material		Dedicated alloy steel					
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)					

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

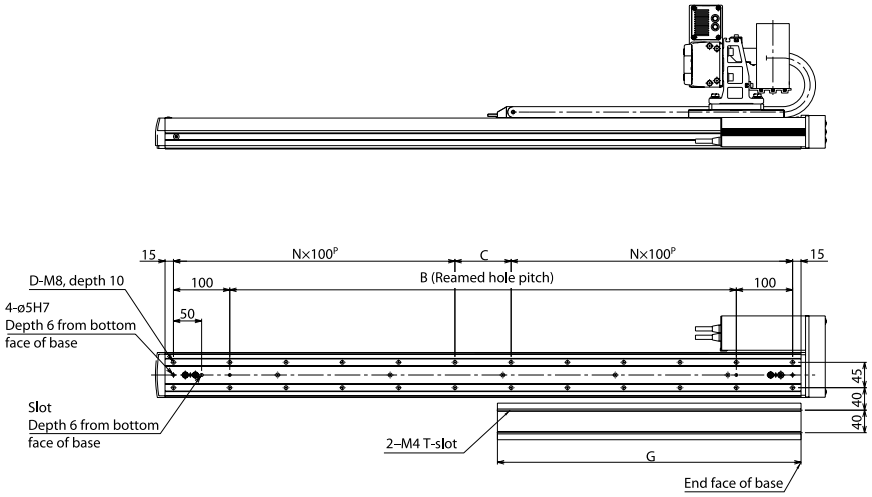


ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
B	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	8	8	8	10	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	114.5	139.5	164.5	189.5	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBA1□□D

RCS2 2-axis Combinations X axis: SS8R (150W, Reversed, Double-slider)
Y axis: SS8R (100W, Reversed)

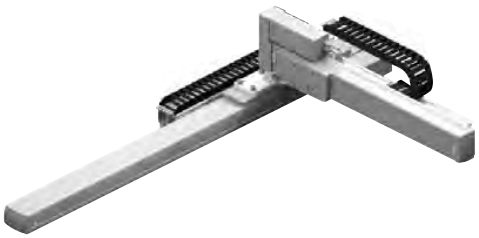
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

IK2 – SXBA1 □□ D – □ – □ □ – □ □ – □ – □ – □ – □

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 800 mm　　Y axis 400 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	1000mm/s	500mm/s
Y axis	1000mm/s	500mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
100mm	–	24kg
150mm	–	24kg
200mm	–	23kg
250mm	–	19kg
300mm	11kg	16kg
350mm	10.5kg	13.5kg
400mm	10kg	11.5kg

List by Stroke

X-axis stroke \ Y-axis stroke	Incremental 100	150	200	250	300	350	400	Absolute 100	150	200	250	300	350	400
50	–	–	–	–	–	–	–	–	–	–	–	–	–	–
100	–	–	–	–	–	–	–	–	–	–	–	–	–	–
150	–	–	–	–	–	–	–	–	–	–	–	–	–	–
200	–	–	–	–	–	–	–	–	–	–	–	–	–	–
250	–	–	–	–	–	–	–	–	–	–	–	–	–	–
300	–	–	–	–	–	–	–	–	–	–	–	–	–	–
350	–	–	–	–	–	–	–	–	–	–	–	–	–	–
400	–	–	–	–	–	–	–	–	–	–	–	–	–	–
450	–	–	–	–	–	–	–	–	–	–	–	–	–	–
500	–	–	–	–	–	–	–	–	–	–	–	–	–	–
550	–	–	–	–	–	–	–	–	–	–	–	–	–	–
600	–	–	–	–	–	–	–	–	–	–	–	–	–	–
650	–	–	–	–	–	–	–	–	–	–	–	–	–	–
700	–	–	–	–	–	–	–	–	–	–	–	–	–	–
750	–	–	–	–	–	–	–	–	–	–	–	–	–	–
800	–	–	–	–	–	–	–	–	–	–	–	–	–	–

Note: For the X high-speed/Y high-speed type, the Y-axis stroke must be 300 mm or more.

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600	650-800
Wiring 2 (Next to Y-axis)	Y-axis stroke	200	250-400	–

List of Options

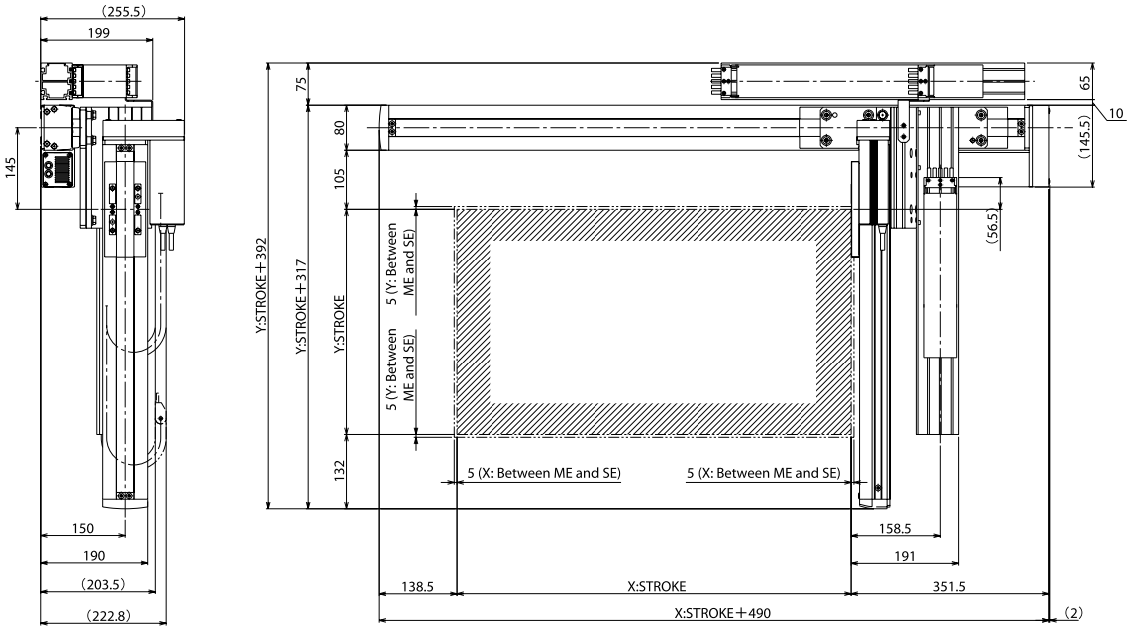
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1(X-axis) Axis 2 (Y-axis)

Specifications

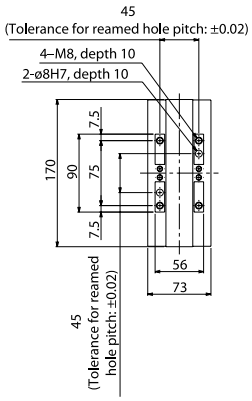
Item		X axis					Y axis
Axis model		RCS2-SS8R					RCS2-SS8R
Stroke (Can be set in 50-mm increments)		50-800mm					High-speed type: 300-400mm Medium speed type: 100-400mm
Max speed	Stroke	50-400mm	450-500mm	550-600mm	650-700mm	750-800mm	100-400mm
	High speed	1000mm/s	960mm/s	765mm/s	625mm/s	515mm/s	1000mm/s
	Medium speed	500mm/s	480mm/s	380mm/s	310mm/s	255mm/s	500mm/s
Motor output (W)		150W					100W
Ball screw lead		High-speed type: 20mm Medium-speed type: 10mm					
Drive method		Ball screw, ø16 mm, rolled, C10					
Positioning repeatability		±0.02mm					
Base material		Dedicated alloy steel					
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)					

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

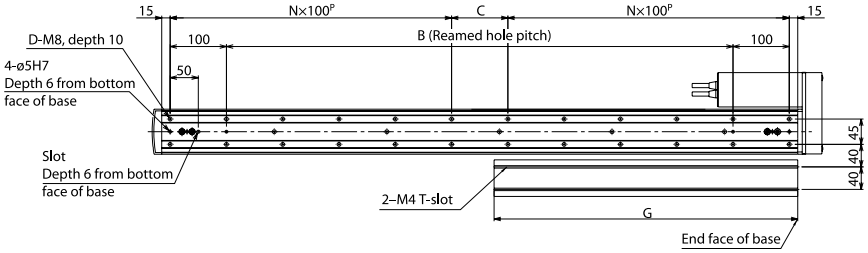


ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
X: Effective stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
B	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBA2□□S

RCS2 2-axis Combinations X axis: SS8C (150W, Straight, Single-slider)
Y axis: SS8R (100W, Reversed)

Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

IK2 – SXBA2□□S – □ – □ □ – □ □ – □ – □ – □ – □

- Combination directions: 1-4
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K, SSEL, XSEL-P/Q; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.

Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 1000 mm Y axis 350 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	1000mm/s	500mm/s
Y axis	1000mm/s	500mm/s

Maximum Load Capacity

X high-speed, Y high-speed	X high-speed, Y high-speed	X medium-speed, Y medium-speed
50mm	12kg	24kg
100mm	12kg	20.5kg
150mm	11.5kg	15.5kg
200mm	11kg	12.5kg
250mm	10kg	–
300mm	8.5kg	–
350mm	7kg	–

List by Stroke

		Incremental							Absolute						
	Y-axis stroke	50	100	150	200	250	300	350	50	100	150	200	250	300	350
X-axis stroke	50	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	850	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	900	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	950	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	1000	–	–	–	–	–	–	–	–	–	–	–	–	–	–

Note: For the X medium-speed/Y medium-speed type, the Y-axis stroke must be 200 mm or less.

List by Cable Length

Type	Cable code	Length	
Standard type	1L	1m	
	3L	3m	
	5L	5m	

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600	650-900	950-1000
Wiring 2 (Next to Y-axis)	Y-axis stroke	50-200	250-300	–	–
				–	–

List of Options

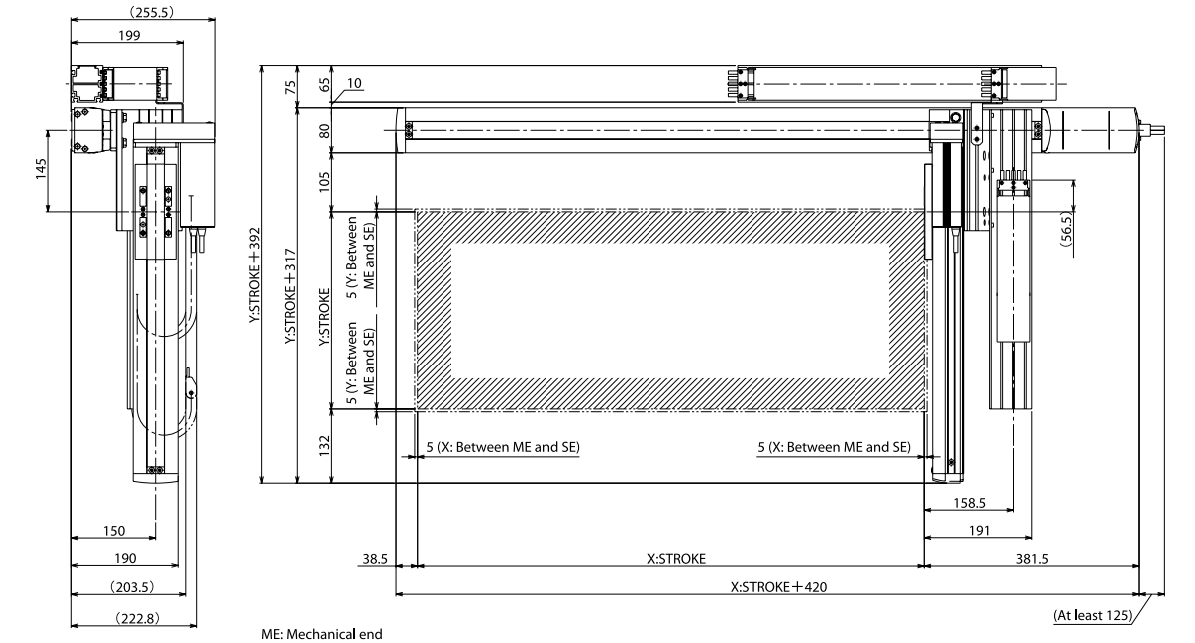
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

Specifications

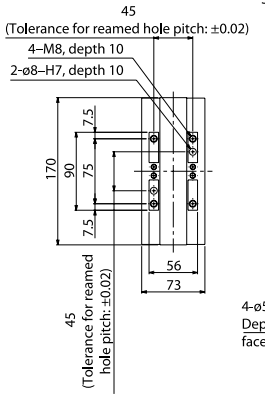
Item		X axis					Y axis
Axis model		RCS2-SS8C					RCS2-SS8R
Stroke (Can be set in 50-mm increments)		50-1000mm					High-speed type: 50-350mm Medium speed type: 50-200mm
Max speed	Stroke	50-600mm	650-700mm	750-800mm	850-900mm	950-1000mm	50-350mm
	High speed	1000mm/s	960mm/s	765mm/s	625mm/s	515mm/s	1000mm/s
	Medium speed	500mm/s	480mm/s	380mm/s	310mm/s	255mm/s	500mm/s
Motor output (W)		150W					100W
Ball screw lead		High-speed type: 20mm Medium-speed type: 10mm					
Drive method		Ball screw, ø16 mm, rolled, C10					
Positioning repeatability		±0.02mm					
Base material		Dedicated alloy steel					
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)					

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

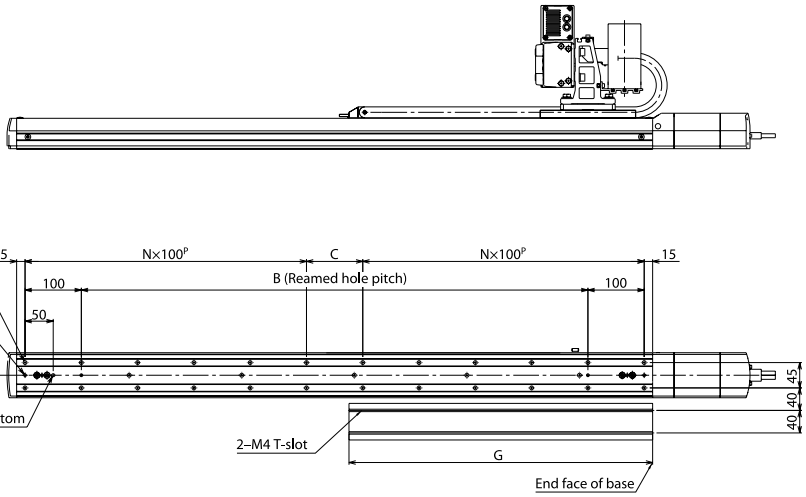


ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider

Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

■Dimensions by Stroke

X: Model	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
B	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	8	8	8	10	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	114.5	139.5	164.5	189.5	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXBA2□□D

RCS2 2-axis Combinations X axis: SS8C (150W, Straight, Double-slider)
Y axis: SS8R (100W, Reversed)

Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Controllres — Cable — Shipping configuration

IK2 — SXBA2□□D — □ — □ □ — □ □ — □ — □ — □ — □ — □

- Combination directions: 1–4
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Y high-speed; MM: X medium-speed, Y medium-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.

Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

X axis 800 mm　　Y axis 400 mm

Maximum Speed

	High-speed type	Medium-speed type
X axis	1000mm/s	500mm/s
Y axis	1000mm/s	500mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed	X medium-speed, Y medium-speed
100mm	–	24kg
150mm	–	24kg
200mm	–	23kg
250mm	–	19kg
300mm	11kg	16kg
350mm	10.5kg	13.5kg
400mm	10kg	11.5kg

List by Stroke

		Incremental							Absolute						
	Y-axis stroke	100	150	200	250	300	350	400	100	150	200	250	300	350	400
X-axis stroke	50	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–	–	–	–	–	–	–

Note: For the X high-speed/Y high-speed type, the Y-axis stroke must be 300 mm or more.

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	50-300	350-600	650-800
Wiring 2 (Next to Y-axis)	Y-axis stroke	200	250-400	–
				–

List of Options

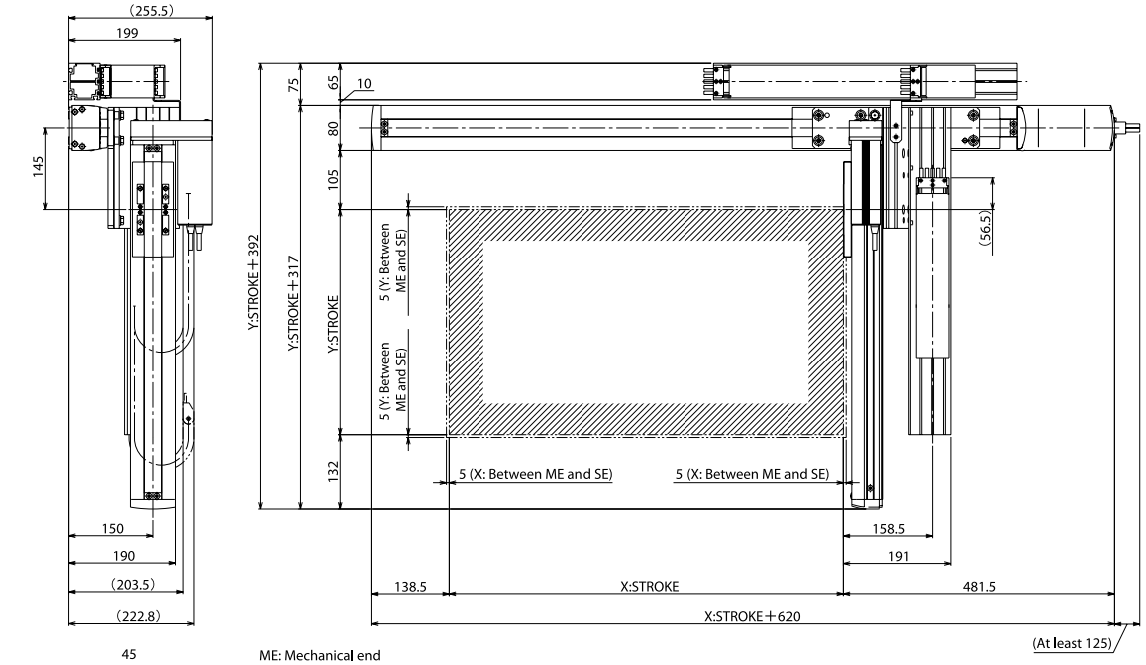
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Y-axis)

Specifications

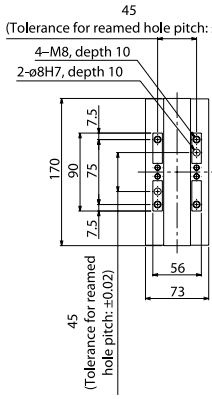
Item		X axis					Y axis
Axis model		RCS2-SS8C					RCS2-SS8R
Stroke (Can be set in 50-mm increments)		50-800mm					High-speed type: 300-400mm Medium speed type: 100-400mm
Max speed	Stroke	50-400mm	450-500mm	550-600mm	650-700mm	750-800mm	100-400mm
	High speed	1000mm/s	960mm/s	765mm/s	625mm/s	515mm/s	1000mm/s
	Medium speed	500mm/s	480mm/s	380mm/s	310mm/s	255mm/s	500mm/s
Motor output (W)		150W					100W
Ball screw lead		High-speed type: 20mm Medium-speed type: 10mm					
Drive method		Ball screw, ø16 mm, rolled, C10					
Positioning repeatability		±0.02mm					
Base material		Dedicated alloy steel					
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)					

Dimensions

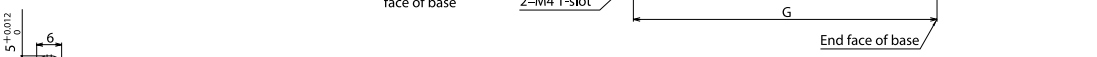
Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.



ME: Mechanical end
SE: Stroke end



Detail view of Y-axis slider



Detail view of slot in bottom face of X-axis base

Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
X: Effective stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
B	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXZB1□□S

RCS2 2-axis combination (XZ) X axis: SS8R (100W, Reversed, Single-slider)
Z axis: SA7R (Reversed)

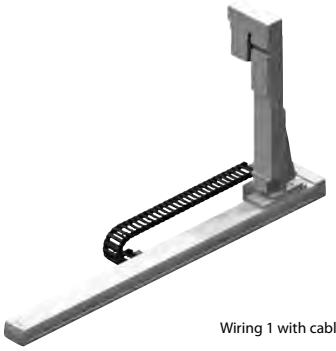
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Z axis) — Controllres — Cable — Shipping configuration

IK2 — SXZB1 □□ S — □ — □ □ — □ □ B□ — □ — □ — □ — □

- Combination directions: 1-4
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Z high-speed; HM: X high-speed, Z medium-speed; HL: X high-speed, Z low-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: B: Brake; NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL; XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Wiring 1 with cable track

Maximum Stroke

X axis 1000 mm Z axis 250 mm

Maximum Speed

	High-speed type	Medium-speed type	Low-speed type
X axis	1000mm/s	–	–
Z axis	800mm/s	400mm/s	200mm/s

Maximum Load Capacity

Z-axis stroke	Z-axis high-speed, lead 16	Z-axis medium-speed, lead 8	Z-axis low-speed, lead 4
50mm	2.0kg	4.0kg	8.0kg
100mm	2.0kg	4.0kg	7.0kg
150mm	2.0kg	3.5kg	5.0kg
200mm	2.0kg	3.5kg	4.0kg
250mm	1.5kg	2.5kg	3.0kg

List by Stroke

		Incremental					Absolute				
	Z-axis stroke	50	100	150	200	250	50	100	150	200	250
X-axis stroke	50	–	–	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–	–	–
	850	–	–	–	–	–	–	–	–	–	–
	900	–	–	–	–	–	–	–	–	–	–
	950	–	–	–	–	–	–	–	–	–	–
	1000	–	–	–	–	–	–	–	–	–	–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	150-300	350-600	650-900	950-1000

List of Options

Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Z-axis)

Specifications

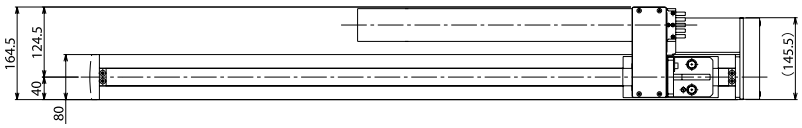
Item		X axis					Z axis
Axis model		RCS2-SS8R					RCS2-SA7R
Stroke (Can be set in 50-mm increments)		50-1000mm					50-250mm
Max speed	Stroke	50-600mm	650-700mm	750-800mm	850-900mm	950-1000mm	50-250mm
	High speed	1000mm/s	960mm/s	765mm/s	625mm/s	515mm/s	800mm/s
	Medium speed	-	-	-	-	-	400mm/s
	Low speed	-	-	-	-	-	200mm/s
Motor output (W)		100W					60W
Ball screw lead		High-speed type: 20mm					High-speed type: 16mm Medium-speed type: 8mm Low-speed type: 4mm
Drive method		Ball screw, ø16 mm, rolled, C10					Ball screw, ø12 mm, rolled, C10
Positioning repeatability		±0.02mm					
Base material		Dedicated alloy steel					Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)					

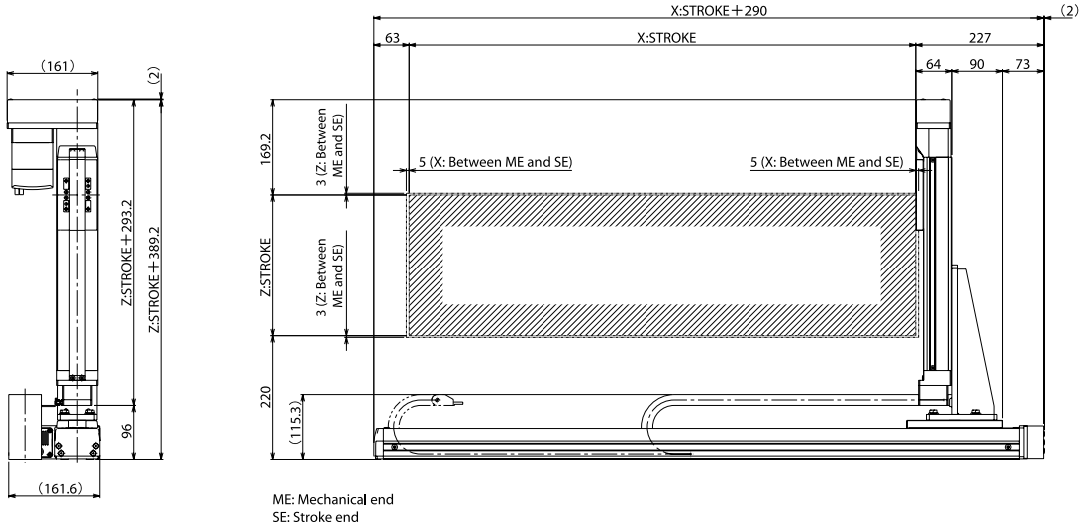
Dimensions

You can download CAD drawings from our website. www.intelligentactuator.com

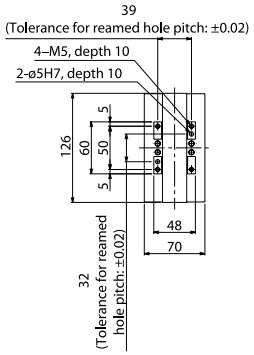
2D CAD

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

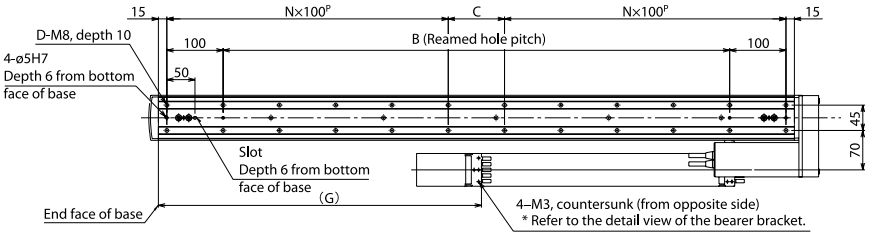




ME: Mechanical end
SE: Stroke end



Detail view of Z-axis slider



Detail view of X-axis installation

Detail view of slot in bottom face of X-axis base

Dimensions by Stroke

X: Model	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
B	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	8	8	8	10	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	–	–	199	224	249	274	299	324	349	374	399	424	449	474	499	524	549	574	599	624

* A bearer is not set when the X stroke is 50 or 100.

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SXZB1□□D

RCS2 2-axis Combinations(XZ) X axis: SS8R (100W, Reversed, Double-slider) Z axis: SA7R (Reversed)

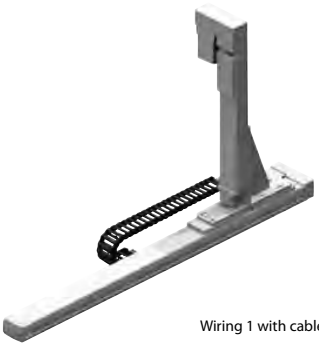
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Z axis) — Controllres — Cable — Shipping configuration

IK2 – SXZB1 □□ D – □ – □ □ – □ B□ – □ – □ – □ – □ – □

- Combination directions: 1-4
- Differences between Single-slider and Double-slider Types: HH: X high-speed, Z high-speed; HM: X high-speed, Z medium-speed; HL: X high-speed, Z low-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm … (Can be set in 50-mm increments)
- Options: B: Brake; NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL; XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Wiring 1 with cable track

Maximum Stroke

X axis 800 mm Z axis 300 mm

Maximum Speed

	High-speed type	Medium-speed type	Low-speed type
X axis	1000mm/s	–	–
Z axis	800mm/s	400mm/s	200mm/s

Maximum Load Capacity

Z-axis stroke	Z-axis high-speed, lead 16	Z-axis medium-speed, lead 8	Z-axis low-speed, lead 4
150mm	–	–	7.0kg
200mm	–	–	7.0kg
250mm	–	–	5.5kg
300mm	1.5kg	3.0kg	5.5kg

List by Stroke

		Incremental				Absolute			
	Y-axis stroke	150	200	250	300	150	200	250	300
X-axis stroke	50	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–

Note: For the Z high-speed type and Z medium-speed type, The Z-axis stroke is limited to 300 mm.

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Cable track

Wiring 1 (Next to X-axis)	X-axis stroke	150-300	350-600	650-800

List of Options

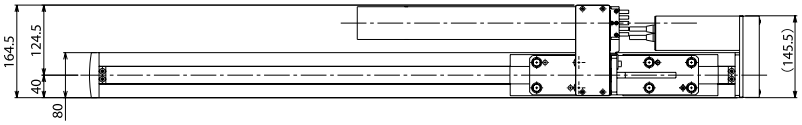
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (X-axis) Axis 2 (Z-axis)

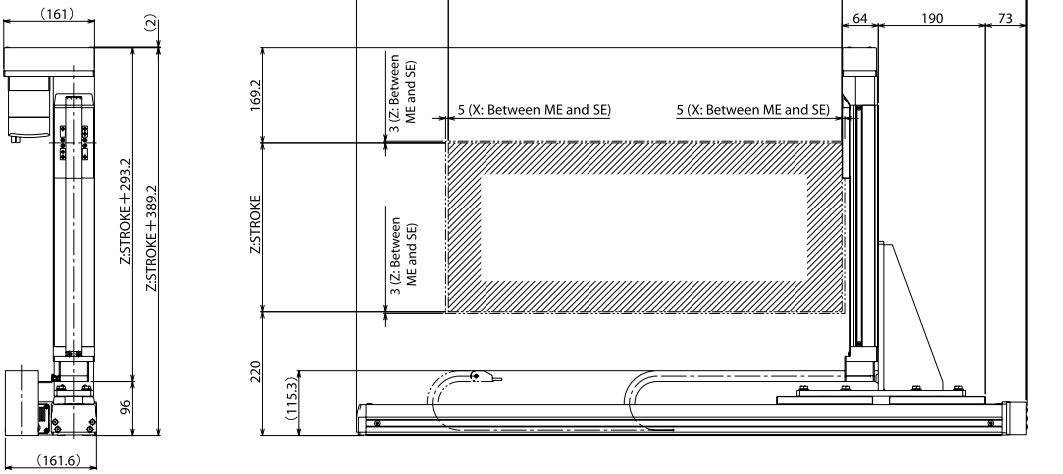
Specifications

Item		X axis					Z axis
Axis model		RCS2-SS8R					RCS2-SA7R
Stroke (Can be set in 50-mm increments)		50-800mm					High-speed type: 300mm Medium-speed type: 300mm Low-speed type: 150-300mm
Max speed	Stroke	50-400mm	450-500mm	550-600mm	650-700mm	750-800mm	150-300mm
	High speed	1000mm/s	960mm/s	765mm/s	625mm/s	515mm/s	800mm/s
	Medium speed	-	-	-	-	-	400mm/s
	Low speed	-	-	-	-	-	200mm/s
Motor output (W)		100W					60W
Ball screw lead		High-speed type: 20mm					High-speed type: 16mm Medium-speed type: 8mm Low-speed type: 4mm
Drive method		Ball screw, ø16 mm, rolled, C10					Ball screw, ø12 mm, rolled, C10
Positioning repeatability		±0.02mm					
Base material		Dedicated alloy steel					Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)					

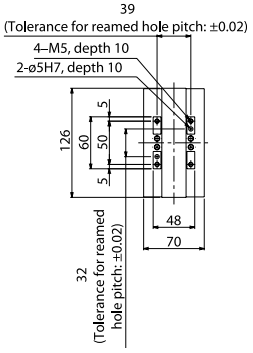
Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

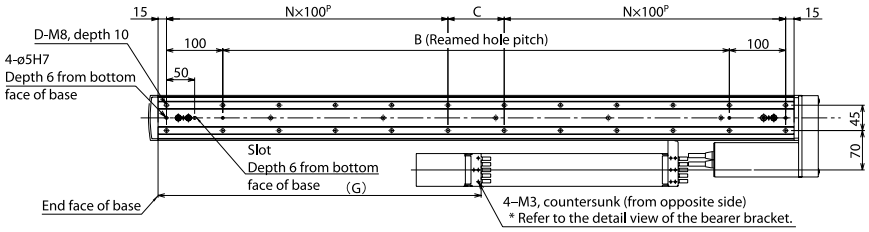




ME: Mechanical end
SE: Stroke end



Detail view of Z-axis slider



Detail view of X-axis installation

Detail view of slot in bottom face of X-axis base

■Dimensions by Stroke

X: Nominal stroke	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
X: Effective stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
B	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	–	–	299	324	349	374	399	424	449	474	499	524	549	574	599	624

* A bearer is not set when the X stroke is 50 or 100.

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK2-SYBB1□□S

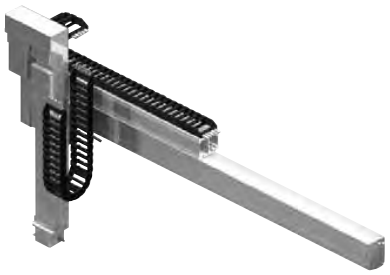
RCS2 2-axis combination (YZ) Y axis: SS8R (100W, Reversed, Single-slider)
Z axis: SA7R (Reversed)

Model Details

IK2 – SYBB1 □□S – □ – □ □ – □ B□ – □ – □ – □ – □ – □

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HH: Y high-speed, Z high-speed; HM: Y high-speed, Z medium-speed; HL: Y high-speed, Z low-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: B: Brake; NM: Opposite-home specification; SR: Slider roller specification
- Controllres: T1: XSEL-J/K; T2: SSEL; XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



Both wiring 1 and wiring 2 assume use of a cable track.

Maximum Stroke

Y axis 1000 mm Z axis 300 mm

Maximum Speed

	High-speed type	Medium-speed type	Low-speed type
Y axis	1000mm/s	–	–
Z axis	800mm/s	400mm/s	200mm/s

Maximum Load Capacity

Z-axis stroke	Z-axis high-speed, lead 16	Z-axis medium-speed, lead 8	Z-axis low-speed, lead 4
50mm	2.0kg	4.0kg	8.0kg
100mm	2.0kg	4.0kg	8.0kg
150mm	2.0kg	3.5kg	7.0kg
200mm	2.0kg	3.5kg	7.0kg
250mm	1.5kg	3.0kg	6.0kg
300mm	1.5kg	3.0kg	5.5kg

List by Stroke

Y-axis stroke \ Z-axis stroke	Incremental 50	100	150	200	250	300	Absolute 50	100	150	200	250	300
50	–	–	–	–	–	–	–	–	–	–	–	–
100	–	–	–	–	–	–	–	–	–	–	–	–
150	–	–	–	–	–	–	–	–	–	–	–	–
200	–	–	–	–	–	–	–	–	–	–	–	–
250	–	–	–	–	–	–	–	–	–	–	–	–
300	–	–	–	–	–	–	–	–	–	–	–	–
350	–	–	–	–	–	–	–	–	–	–	–	–
400	–	–	–	–	–	–	–	–	–	–	–	–
450	–	–	–	–	–	–	–	–	–	–	–	–
500	–	–	–	–	–	–	–	–	–	–	–	–
550	–	–	–	–	–	–	–	–	–	–	–	–
600	–	–	–	–	–	–	–	–	–	–	–	–
650	–	–	–	–	–	–	–	–	–	–	–	–
700	–	–	–	–	–	–	–	–	–	–	–	–
750	–	–	–	–	–	–	–	–	–	–	–	–
800	–	–	–	–	–	–	–	–	–	–	–	–
850	–	–	–	–	–	–	–	–	–	–	–	–
900	–	–	–	–	–	–	–	–	–	–	–	–
950	–	–	–	–	–	–	–	–	–	–	–	–
1000	–	–	–	–	–	–	–	–	–	–	–	–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Cable track

Wiring 1 (Next to Y-axis)	Y-axis stroke	50-300	350-600	650-900	950-1000
Wiring 2 (Next to Z-axis)	Z-axis stroke	50-200	250-300	–	–
				–	–

List of Options

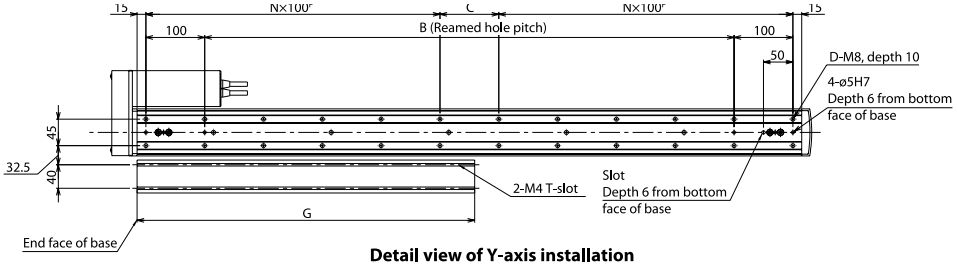
Name	Option code	
Opposite-home specification	NM	
Slider roller specification	SR	Axis 1 (Y-axis) Axis 2 (Z-axis)

Specifications

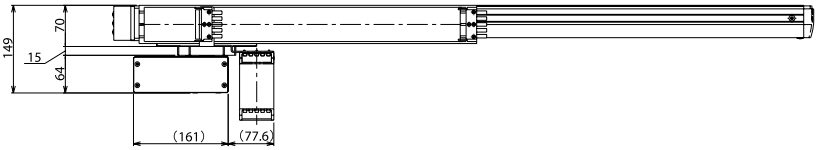
Item		Y axis					Z axis
Axis model		RCS2-SS8R					RCS2-SA7R
Stroke (Can be set in 50-mm increments)		50-1000mm					50-300mm
Max speed	Stroke	50-600mm	650-700mm	750-800mm	850-900mm	950-1000mm	50-300mm
	High speed	1000mm/s	960mm/s	765mm/s	625mm/s	515mm/s	800mm/s
	Medium speed	-	-	-	-	-	400mm/s
	Low speed	-	-	-	-	-	200mm/s
Motor output (W)		100W					60W
Ball screw lead		High-speed type: 20mm					High-speed type: 16mm Medium-speed type: 8mm Low-speed type: 4mm
Drive method		Ball screw, ø16 mm, rolled, C10					Ball screw, ø12 mm, rolled, C10
Positioning repeatability		±0.02mm					
Base material		Dedicated alloy steel					Aluminum
Surrounding air temperature/humidity		0 to 40°C, 85% RH or below (non-condensing)					

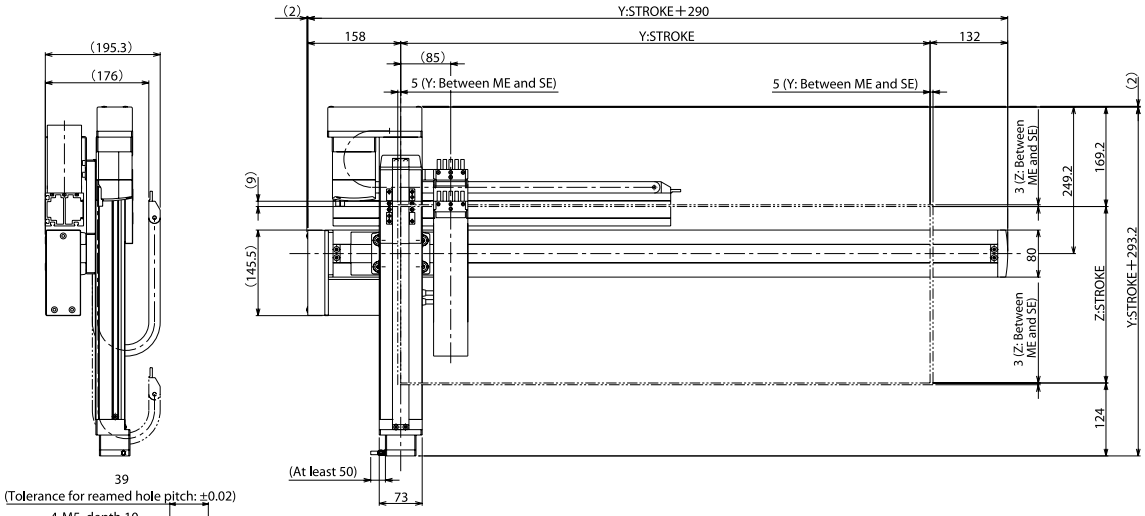
Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2. Both wiring 1 and wiring 2 assume use of a cable track.
Note 3. For details on the cable track, refer to P. 90.
Note 4. For details on the bracket on the moving end of the cable track, refer to P. 90.

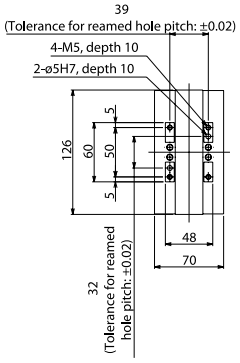


Detail view of Y-axis installation





ME: Mechanical end
SE: Stroke end



Detail view of Z-axis slider

Detail view of slot in bottom face of Y-axis base

Dimensions by Stroke

Y: Model	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
B	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	8	8	8	10	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	149	174	199	224	249	274	299	324	349	374	399	424	449	474	499	524	549	574	599	624

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK3-PBBG1□□S

RCP2 3-axis combination (XYB+Z-axes, base mount)
X axis: SS8R (Reversed, Single-slider)
Y axis: SA7R (Reversed) Z axis: SA6R (Reversed)

Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Axis 3 (Z axis) — Controllers — Cable — Shipping configuration

IK3 — PBBG1□□S — □ — □ □ — □ □ — □ □ — B□ — P1 — □ — □ — □ — □

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HHH: X high-speed, Y high-speed, Z high-speed; HHM: X high-speed, Y high-speed, Z medium-speed; HHL: X high-speed, Y high-speed, Z low-speed
- Encoder type: I: Incremental
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: B: Brake; NM: Opposite-home specification; SR: Slider roller specification
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.

With cable tracks (Wiring 3 does not come with a cable track.)

Maximum Stroke

X axis 1000 mm | Y axis 300 mm | Z axis 200 mm

Maximum Speed

	X high-speed, Y high-speed, Z high-speed	X high-speed, Y high-speed, Z medium-speed	X high-speed, Y high-speed, Z low-speed
X axis	220mm/s		
Y axis	420mm/s		
Z axis	500mms	250mm/s	125mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed, Z high-speed	X high-speed, Y high-speed, Z medium-speed	X high-speed, Y high-speed, Z low-speed
50mm	1.0kg	2.0kg	4.0kg
100mm			
150mm			
200mm			
250mm			
300mm			

List by Stroke

		Incremental											
Y-axis stroke		50				100				150			
Z-axis stroke		50	100	150	200	50	100	150	200	50	100	150	200
X-axis stroke	50	–	–	–	–	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–	–	–	–	–
	850	–	–	–	–	–	–	–	–	–	–	–	–
	900	–	–	–	–	–	–	–	–	–	–	–	–
	950	–	–	–	–	–	–	–	–	–	–	–	–
	1000	–	–	–	–	–	–	–	–	–	–	–	–

		Incremental											
Y-axis stroke		200				250				300			
Z-axis stroke		50	100	150	200	50	100	150	200	50	100	150	200
X-axis stroke	50	–	–	–	–	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–	–	–	–	–
	850	–	–	–	–	–	–	–	–	–	–	–	–
	900	–	–	–	–	–	–	–	–	–	–	–	–
	950	–	–	–	–	–	–	–	–	–	–	–	–
	1000	–	–	–	–	–	–	–	–	–	–	–	–

Cable track

		Y-axis stroke	
		50-200	250-300
X-axis stroke	50-400	–	–
	450-600	–	–
	650-800	–	–
	850-1000	–	–

Note) Both wiring 1 and wiring 2 should have a cable bear, or neither of the two should have a cable track. A cable track cannot be specified for one of the wirings.

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axes 2 and 3 come with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

List by Cable Length

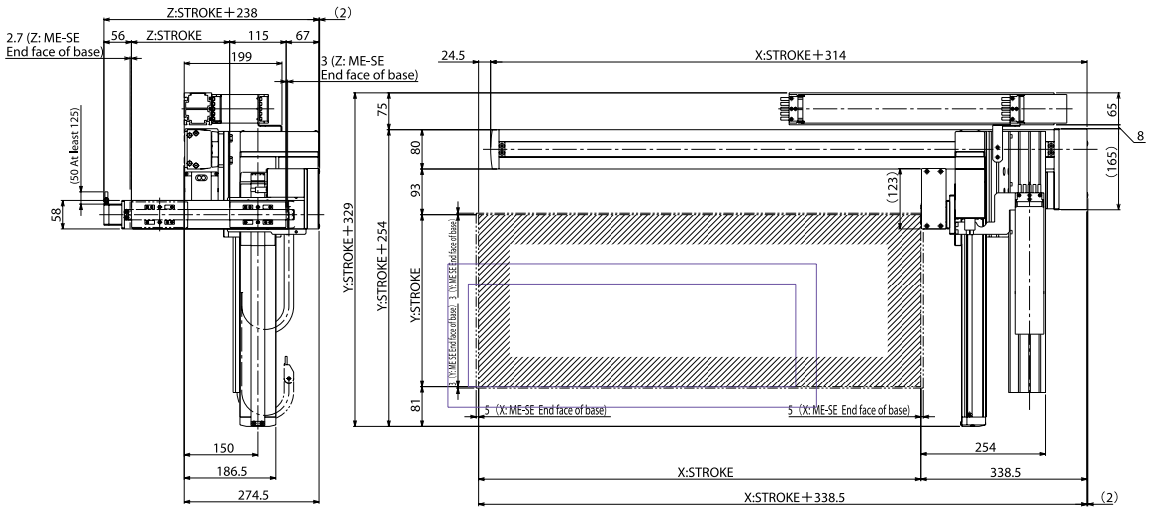
Name	Option code
Opposite-home specification	NM
Slider roller specification	SR

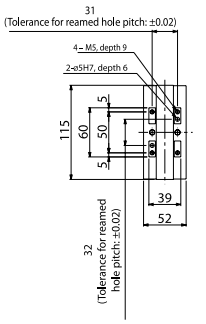
Specifications

Item	X axis	Y axis	Z axis
Axis model	RCP2-SS8R	RCP2-SA7R	RCP2-SA6R
Stroke (Can be set in 50-mm increments)	50-1000mm	50-300mm	50-200mm
Axis 2	High-speed type: 220mm/s	High-speed type: 420mm/s	High-speed type: 500mm/s Medium-speed type: 250mm/s Low-speed type: 125mm/s
Motor size	56-square pulse motor	56-square pulse motor	42-square pulse motor
Ball screw lead	High-speed type: 20mm	High-speed type: 16mm	High-speed type: 12mm Medium-speed type: 6mm Low-speed type: 3mm
Drive method	Ball screw, ø16mm, rolled, C10	Ball screw, ø12mm, rolled, C10	Ball screw, ø10mm, rolled, C10
Positioning repeatability	±0.02mm		
Base material	Dedicated alloy steel	Aluminum	
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)		

Dimensions

Note 1. The connected position shown in the drawing defines the home.
Note 2.The drawing below assumes that both wiring 1 and wiring 2 have a cable track.
Note 3. For details on the cable track, refer to P. 90.

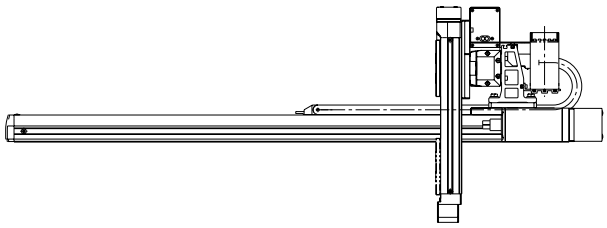


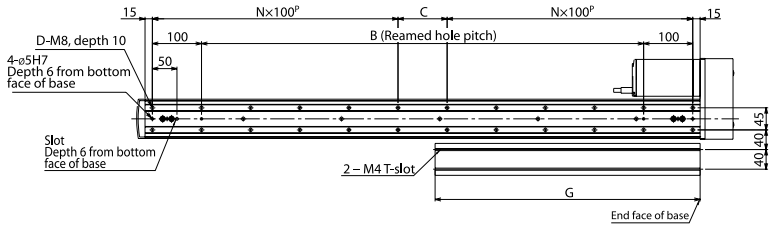


Detail view of Z-axis slider

Detail view of slot in bottom face of X-axis base

ME: Mechanical end
SE: Stroke end





Detail view of X-axis installation

Dimensions by Stroke

X: Model	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
B	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	8	8	8	10	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	114.5	139.5	164.5	189.5	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK3-PBBG1□□D

RCP2 3-axis combination (XYB+Z-axes, base mount)
X axis: SS8R (Reversed, Double-slider)
Y axis: SA7R (Reversed) Z axis: SA6R (Reversed)

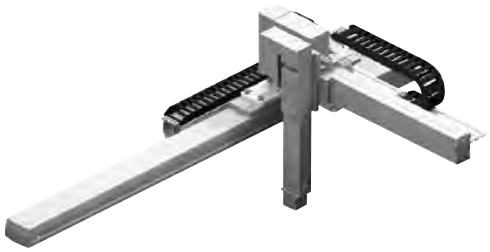
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Axis 3 (Z axis) — Controllers — Cable — Shipping configuration

IK3 – PBBG1□□D – □ – □ □ – □ □ – □ B□ – P1 – □ – □ – □ – □

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HHH: X high-speed, Y high-speed, Z high-speed; HHM: X high-speed, Y high-speed, Z medium-speed; HHL: X high-speed, Y high-speed, Z low-speed
- Encoder type: I: Incremental
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: B: Brake; NM: Opposite-home specification; SR: Slider roller specification
- Cable length: 1L: 1m, 3L: 3m, 5L: 5m, □L: □m
- Wiring 1: N: Cable only, CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



With cable tracks (Wiring 3 does not come with a cable track.)

Maximum Stroke

X axis 800 mm | Y axis 400 mm | Z axis 200 mm

Maximum Speed

	X high-speed, Y high-speed, Z high-speed	X high-speed, Y high-speed, Z medium-speed	X high-speed, Y high-speed, Z low-speed
X axis	220mm/s		
Y axis	420mm/s		
Z axis	500mms	250mm/s	125mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed, Z high-speed	X high-speed, Y high-speed, Z medium-speed	X high-speed, Y high-speed, Z low-speed
350mm	1.0kg	2.0kg	4.0kg
400mm			

List by Stroke

		Incremental							
Y-axis stroke		350				400			
Z-axis stroke		50	100	150	200	50	100	150	200
X-axis stroke	50	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Cable track

		Y-axis stroke
		350-400
X-axis stroke	50-400	–
	450-600	–
	650-800	–

Note) Both wiring 1 and wiring 2 should have a cable bear, or neither of the two should have a cable track. A cable track cannot be specified for one of the wirings.

List by Cable Length

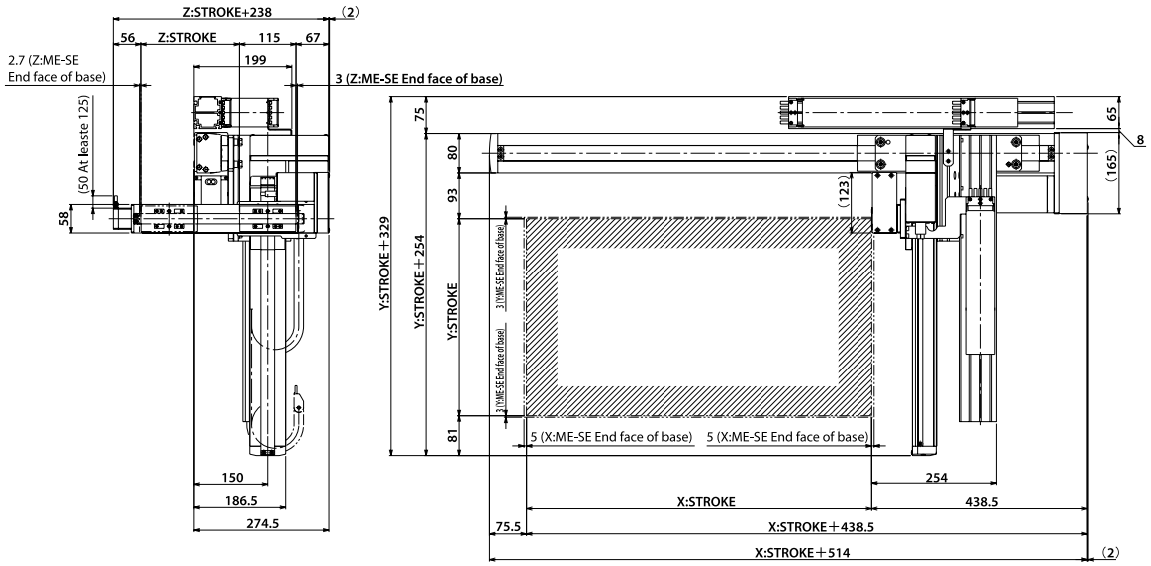
Name	Option code
Opposite-home specification	NM
Slider roller specification	SR

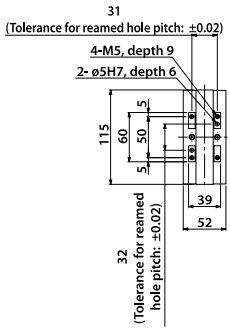
Specifications

Item	X axis	Y axis	Z axis
Axis model	RCP2-SS8R	RCP2-SA7R	RCP2-SA6R
Stroke (Can be set in 50-mm increments)	50-800mm	350-400mm	50-200mm
Max speed	High-speed type: 220mm/s	High-speed type: 420mm/s	High-speed type: 500mm/s Medium-speed type: 250mm/s Low-speed type: 125mm/s
Motor size	56-square pulse motor	56-square pulse motor	42-square pulse motor
Ball screw lead	High-speed type: 20mm	High-speed type: 16mm	High-speed type: 12mm Medium-speed type: 6mm Low-speed type: 3mm
Drive method	Ball screw, ø16mm, rolled, C10	Ball screw, ø12mm, rolled, C10	Ball screw, ø10mm, rolled, C10
Positioning repeatability	±0.02mm		
Base material	Dedicated alloy steel	Aluminum	
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)		

Dimensions

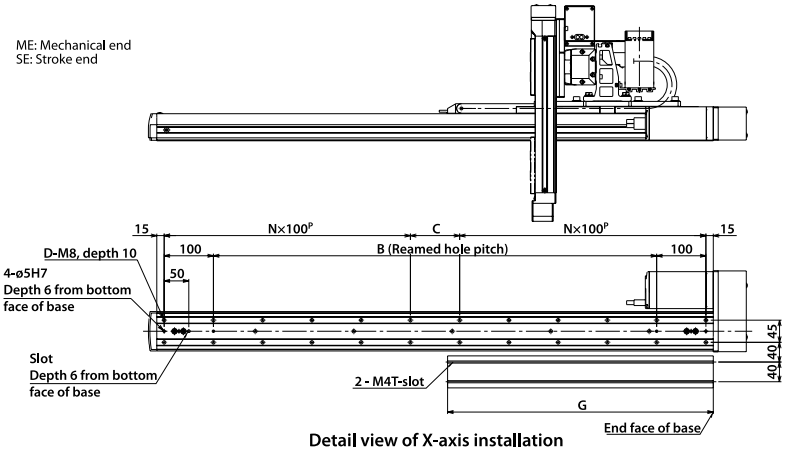
Note 1. The connected position shown in the drawing defines the home.
Note 2.The drawing below assumes that both wiring 1 and wiring 2 have a cable track.
Note 3. For details on the cable track, refer to P. 90.





Detail view of Z-axis slider

Detail view of slot in bottom



Detail view of X-axis installation

■Dimensions by Stroke

X: Nominal stroke	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
X: Effective stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
B	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK3-SBBG1□□S

RCS2 3-axis combination (XYB+Z-axes, base mount)
X axis: SS8R (100W, Reversed, Single-slider)
Y axis: SA7R (Reversed) Z axis: SA6R (Reversed)

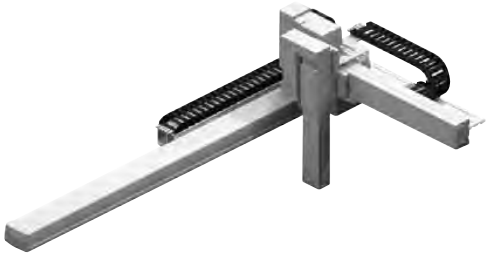
Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Axis 3 (Z axis) — Controllers — Cable — Shipping configuration

IK3 — SBBG1□□S — □ — □ □ — □ □ — □ □ — B□ — □ — □ — □ — □

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HHH: X high-speed, Y high-speed, Z high-speed; HHM: X high-speed, Y high-speed, Z medium-speed; HHL: X high-speed, Y high-speed, Z low-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: B: Brake; NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.



With cable tracks (Wiring 3 does not come with a cable track.)

Maximum Stroke

X axis 1000 mm | Y axis 300 mm | Z axis 200 mm

Maximum Speed

	X high-speed, Y high-speed, Z high-speed	X high-speed, Y high-speed, Z medium-speed	X high-speed, Y high-speed, Z low-speed
X axis	1000mm/s		
Y axis	800mm/s		
Z axis	800mms	400mm/s	200mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed, Z high-speed	X high-speed, Y high-speed, Z medium-speed	X high-speed, Y high-speed, Z low-speed
50mm	1.0kg	2.0kg	4.0kg
100mm			
150mm			
200mm			
250mm			
300mm			

List by Stroke

		Incremental											
Y-axis stroke		50				100				150			
Z-axis stroke		50	100	150	200	50	100	150	200	50	100	150	200
X-axis stroke	50	–	–	–	–	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–	–	–	–	–
	850	–	–	–	–	–	–	–	–	–	–	–	–
	900	–	–	–	–	–	–	–	–	–	–	–	–
	950	–	–	–	–	–	–	–	–	–	–	–	–
	1000	–	–	–	–	–	–	–	–	–	–	–	–

		Incremental											
Y-axis stroke		200				250				300			
Z-axis stroke		50	100	150	200	50	100	150	200	50	100	150	200
X-axis stroke	50	–	–	–	–	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–	–	–	–	–
	850	–	–	–	–	–	–	–	–	–	–	–	–
	900	–	–	–	–	–	–	–	–	–	–	–	–
	950	–	–	–	–	–	–	–	–	–	–	–	–
	1000	–	–	–	–	–	–	–	–	–	–	–	–

		Incremental											
Y-axis stroke		50				100				150			
Z-axis stroke		50	100	150	200	50	100	150	200	50	100	150	200
X-axis stroke	50	–	–	–	–	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–	–	–	–	–
	850	–	–	–	–	–	–	–	–	–	–	–	–
	900	–	–	–	–	–	–	–	–	–	–	–	–
	950	–	–	–	–	–	–	–	–	–	–	–	–
	1000	–	–	–	–	–	–	–	–	–	–	–	–

		Incremental											
Y-axis stroke		200				250				300			
Z-axis stroke		50	100	150	200	50	100	150	200	50	100	150	200
X-axis stroke	50	–	–	–	–	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–	–	–	–	–
	850	–	–	–	–	–	–	–	–	–	–	–	–
	900	–	–	–	–	–	–	–	–	–	–	–	–
	950	–	–	–	–	–	–	–	–	–	–	–	–
	1000	–	–	–	–	–	–	–	–	–	–	–	–

Cable track

		Y-axis stroke	
		50-200	250-300
X-axis stroke	50-400	–	–
	450-600	–	–
	650-800	–	–
	850-1000	–	–

Note) Both wiring 1 and wiring 2 should have a cable bear, or neither of the two should have a cable track. A cable track cannot be specified for one of the wirings.

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Options

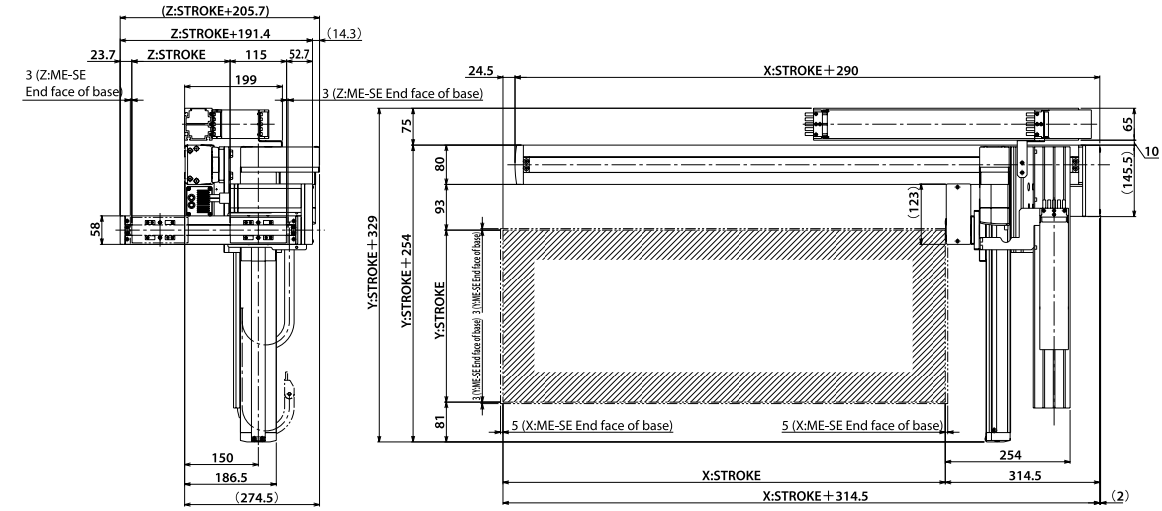
Name	Option code
Opposite-home specification	NM
Slider roller specification	SR

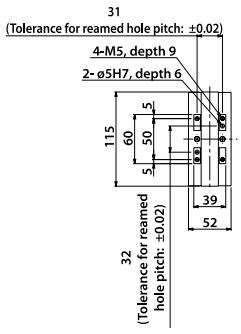
Specifications

Item	X axis	Y axis	Z axis
Axis model	RCS2-SS8R	RCS2-SA7R	RCS2-SA6R
Stroke (Can be set in 50-mm increments)	50-1000mm	50-300mm	50-200mm
Max speed	High-speed type: 1000mm/s	High-speed type: 800mm/s	High-speed type: 800mm/s Medium-speed type: 400mm/s Low-speed type: 200mm/s
Motor output (W)	100W	60W	30W
Ball screw lead	High-speed type: 20mm	High-speed type: 16mm	High-speed type: 12mm Medium-speed type: 6mm Low-speed type: 3mm
Drive method	Ball screw, ø16mm, rolled, C10	Ball screw, ø12mm, rolled, C10	Ball screw, ø10mm, rolled, C10
Positioning repeatability	±0.02mm		
Base material	Dedicated alloy steel	Aluminum	
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)		

Dimensions

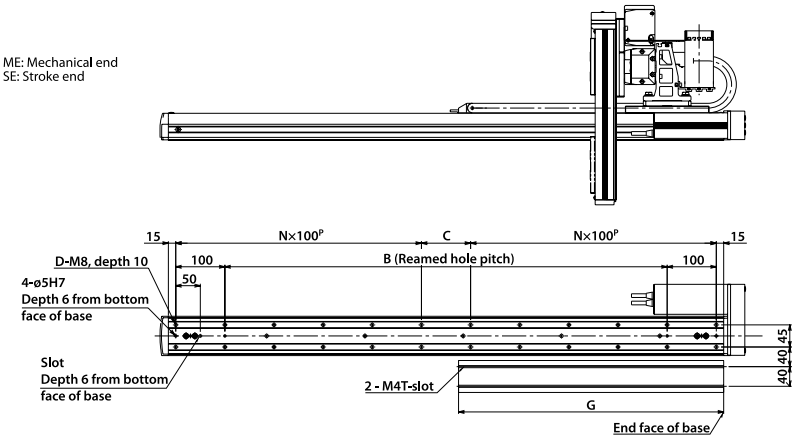
Note 1. The connected position shown in the drawing defines the home.
Note 2.The drawing below assumes that both wiring 1 and wiring 2 have a cable track.
Note 3. For details on the cable track, refer to P. 90.





Detail view of Z-axis slider

Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Model	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
B	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	8	8	8	10	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	114.5	139.5	164.5	189.5	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

Controllers

Applicable controller

Refer to P. 91 for the controllers.

IK3-SBBG1□□D

RCS2 3-axis combination (XYB+Z-axes, base mount)
X axis: SS8R (100W, Reversed, Single-slider)
Y axis: SA7R (Reversed) Z axis: SA6R (Reversed)

Model Details

Series — Type — Encoder type — Axis 1 (X axis) — Axis 2 (Y axis) — Axis 3 (Z axis) — Controllers — Cable — Shipping configuration

IK3 – SBBG1□□D – □ – □ □ – □ □ – □ B□ – □ – □□ – □ – □ – □

- Combination directions: 1-2
- Differences between Single-slider and Double-slider Types: HHH: X high-speed, Y high-speed, Z high-speed; HHM: X high-speed, Y high-speed, Z medium-speed; HHL: X high-speed, Y high-speed, Z low-speed
- Encoder type: I: Incremental; A: Absolute
- Stroke (mm): 5: 50mm ~ (Can be set in 50-mm increments)
- Options: B: Brake; NM: Opposite-home specification; SR: Slider roller specification
- Controllers: T1: XSEL-J/K; T2: SSEL, XSEL-P/Q
- Cable length: 1L: 1m; 3L: 3m; 5L: 5m; □L: □m
- Wiring 1: N: Cable only; CT: With cable track
- Wiring 2
- Shipping configuration: K: Individual components (kit)

* Refer to P. 10 for details on the items comprising the model name.

With cable tracks (Wiring 3 does not come with a cable track.)

Maximum Stroke

X axis 800 mm | Y axis 400 mm | Z axis 200 mm

Maximum Speed

	X high-speed, Y high-speed, Z high-speed	X high-speed, Y high-speed, Z medium-speed	X high-speed, Y high-speed, Z low-speed
X axis	1000mm/s		
Y axis	800mm/s		
Z axis	800mms	400mm/s	200mm/s

Maximum Load Capacity

Y-axis stroke	X high-speed, Y high-speed, Z high-speed	X high-speed, Y high-speed, Z medium-speed	X high-speed, Y high-speed, Z low-speed
350mm	1.0kg	2.0kg	4.0kg
400mm			

List by Stroke

		Incremental								Absolute							
Y-axis stroke		350				400				350				400			
Z-axis stroke		50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200
X-axis stroke	50	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	100	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	150	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	200	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	250	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	300	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	350	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	400	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	450	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	500	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	550	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	600	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	650	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	700	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	750	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–
	800	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–	–

Cable track

		Y-axis stroke
		350-400
X-axis stroke	50-400	–
	450-600	–
	650-800	–

Note) Both wiring 1 and wiring 2 should have a cable bear, or neither of the two should have a cable track. A cable track cannot be specified for one of the wirings.

List by Cable Length

Type	Cable code	Length
Standard type	1L	1m
	3L	3m
	5L	5m

* Axis 1 comes with a standard cable, while axis 2 comes with a robot cable.
* Refer to P. 90 for lengths other than those specified above.

Lis by Cable Length

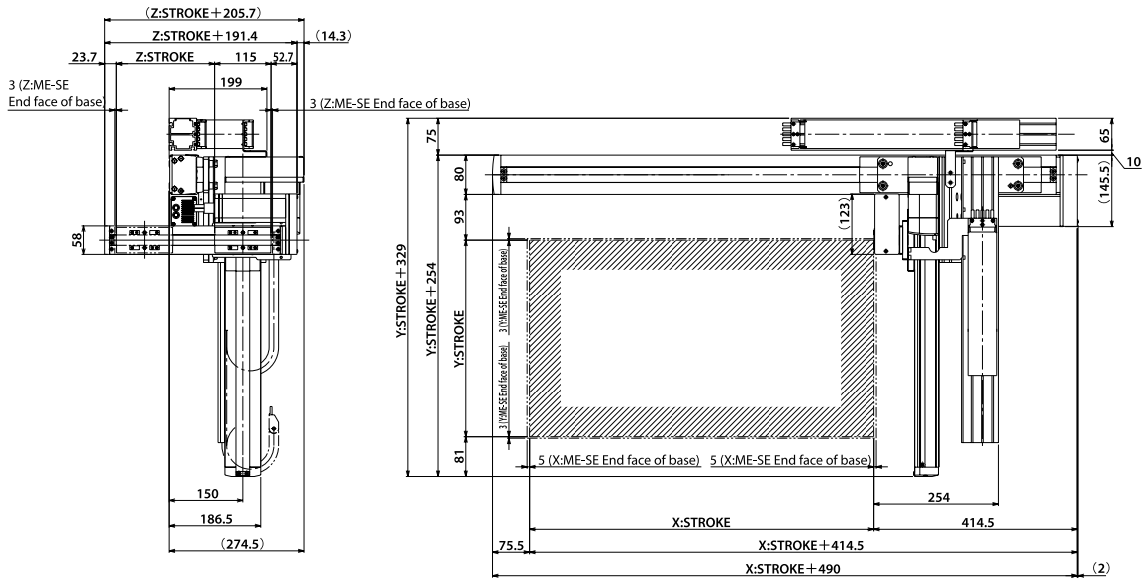
Name	Option code
Opposite-home specification	NM
Slider roller specification	SR

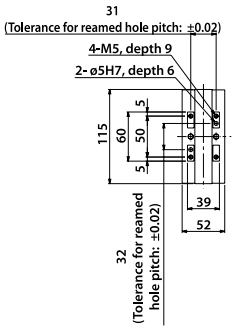
Specifications

Item	X axis	Y axis	Z axis
Axis model	RCS2-SS8R	RCS2-SA7R	RCS2-SA6R
Stroke (Can be set in 50-mm increments)	50-800mm	350-400mm	50-200mm
Max speed	High-speed type: 1000mm/s	High-speed type: 800mm/s	High-speed type: 800mm/s Medium-speed type: 400mm/s Low-speed type: 200mm/s
Motor output (W)	100W	60W	30W
Ball screw lead	High-speed type: 20mm	High-speed type: 16mm	High-speed type: 12mm Medium-speed type: 6mm Low-speed type: 3mm
Drive method	Ball screw, ø16mm, rolled, C10	Ball screw, ø12mm, rolled, C10	Ball screw, ø10mm, rolled, C10
Positioning repeatability	±0.02mm		
Base material	Dedicated alloy steel	Aluminum	
Surrounding air temperature/humidity	0 to 40°C, 85% RH or below (non-condensing)		

Dimensions

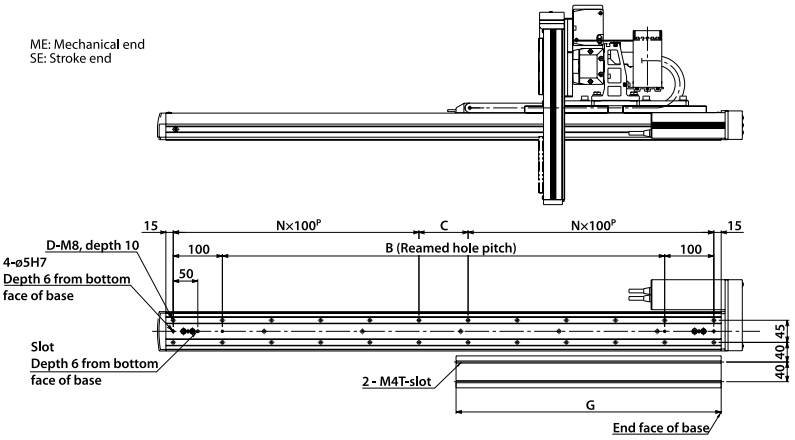
Note 1. The connected position shown in the drawing defines the home.
Note 2.The drawing below assumes that both wiring 1 and wiring 2 have a cable track.
Note 3. For details on the cable track, refer to P. 90.





Detail view of Z-axis slider

Detail view of slot in bottom face of X-axis base



Detail view of X-axis installation

Dimensions by Stroke

X: Nominal stroke	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
X: Effective stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
B	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
C	50	100	150	0	50	100	150	0	50	100	150	0	50	100	150	0
D	12	12	12	14	16	16	16	18	20	20	20	22	24	24	24	26
N	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6
G	214.5	239.5	264.5	289.5	314.5	339.5	364.5	389.5	414.5	439.5	464.5	489.5	514.5	539.5	564.5	589.5

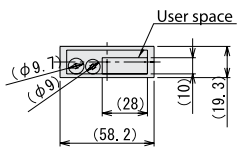
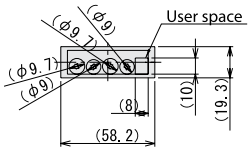
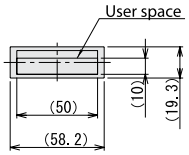
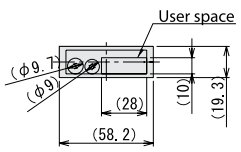
Controllers

Applicable controller

Refer to P. 91 for the controllers.

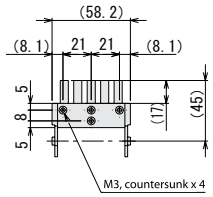
Reference

Cable Track

Section view of axis 1 cable storage		Detail view of axis 2 cable storage	
			
2-axis combination	3-axis combination	2-axis combination	3-axis combination

Detail View of Bracket on Moving End of Cable Track

Moving end of cable track for wiring 2 in XYB or YZ combination
Moving end of cable track for wiring 1 in XZ combination



List by Cable Length

Cable code	Length	RCP2 2-axis IK2-P	RCS2 2-axis IK2-S	RCP2 3-axis IK3-P	RCS2 3-axis IK3-S
1L	1m	—	—	—	—
2L	2m	—	—	—	—
3L	3m	—	—	—	—
4L	4m	—	—	—	—
5L	5m	—	—	—	—
6L	6m	—	—	—	—
7L	7m	—	—	—	—
8L	8m	—	—	—	—
9L	9m	—	—	—	—
10L	10m	—	—	—	—
11L	11m	—	—	—	—
12L	12m	—	—	—	—
13L	13m	—	—	—	—
14L	14m	—	—	—	—
15L	15m	—	—	—	—
16L	16m	—	—	—	—
17L	17m	—	—	—	—
18L	18m	—	—	—	—
19L	19m	—	—	—	—
20L	20m	—	—	—	—

* Axis 1 comes with a standard cable, while axes 2 and 3 come with a robot cable.

Controllers

List of Applicable Controllers

	IA kit model	Applicable controller	
2-axis	IK2-PXBD IK2-PXBC	PSEL-C-2-42PI-42PI-NP-2-0	2-axis controller
		PCON-C-42PI-NP-2-0	1-axis controller
		RPCON-42P	1 unit
	IK2-PXBB IK2-PXZB IK2-PYBB	PSEL-C-2-56PI-56PI-NP-2-0	2-axis controller
		PCON-C-56PI-NP-2-0	1-axis controller
		RPCON-56P	1 unit
	IK2-SXBD	SSEL-C-2-60I-20I-NP-2-[1]	2-axis controller (incremental)
		SSEL-C-2-60A-20A-NP-2-[1]	2-axis controller (absolute)
		SCON-C-60I-NP-2-[1]	1-axis controller (incremental for X-axis)
		SCON-C-60A-NP-2-[1]	1-axis controller (absolute for X-axis)
		SCON-C-20I-NP-2-[1]	1-axis controller (incremental for Y-axis)
		SCON-C-20A-NP-2-[1]	1-axis controller (absolute for Y-axis)
	IK2-SXBC	SSEL-C-2-60I-30I-NP-2-[1]	2-axis controller (incremental)
		SSEL-C-2-60A-30A-NP-2-[1]	2-axis controller (absolute)
		SCON-C-60I-NP-2-[1]	1-axis controller (incremental for X-axis)
		SCON-C-60A-NP-2-[1]	1-axis controller (absolute for X-axis)
		SCON-C-30I-NP-2-[1]	1-axis controller (incremental for Y-axis)
		SCON-C-30A-NP-2-[1]	1-axis controller (absolute for Y-axis)
	IK2-SXBB	SSEL-C-2-100I-60I-NP-2-[1]	2-axis controller (incremental)
		SSEL-C-2-100A-60A-NP-2-[1]	2-axis controller (absolute)
		SCON-C-100I-NP-2-[1]	1-axis controller (incremental for X-axis)
		SCON-C-100A-NP-2-[1]	1-axis controller (absolute for X-axis)
		SCON-C-60I-NP-2-[1]	1-axis controller (incremental for Y-axis)
		SCON-C-60A-NP-2-[1]	1-axis controller (absolute for Y-axis)
	IK2-SXBA	SSEL-C-2-150I-100I-NP-2-[1]	2-axis controller (incremental)
		SSEL-C-2-150A-100A-NP-2-[1]	2-axis controller (absolute)
		SCON-C-150I-NP-2-[1]	1-axis controller (incremental for X-axis)
		SCON-C-150A-NP-2-[1]	1-axis controller (absolute for X-axis)
		SCON-C-100I-NP-2-[1]	1-axis controller (incremental for Y-axis)
		SCON-C-100A-NP-2-[1]	1-axis controller (absolute for Y-axis)
	IK2-SXZB	SSEL-C-2-100I-60I-NP-2-[1]	2-axis controller (incremental)
		SSEL-C-2-100A-60A-NP-2-[1]	2-axis controller (absolute)
		SCON-C-100I-NP-2-[1]	1-axis controller (incremental for X-axis)
		SCON-C-100A-NP-2-[1]	1-axis controller (absolute for X-axis)
		SCON-C-60I-NP-2-[1]	1-axis controller (incremental for Z-axis)
		SCON-C-60A-NP-2-[1]	1-axis controller (absolute for Z-axis)
	IK2-SYBB	SSEL-C-2-100I-60I-NP-2-[1]	2-axis controller (incremental)
		SSEL-C-2-100A-60A-NP-2-[1]	2-axis controller (absolute)
		SCON-C-100I-NP-2-[1]	1-axis controller (incremental for Y-axis)
		SCON-C-100A-NP-2-[1]	1-axis controller (absolute for Y-axis)
		SCON-C-60I-NP-2-[1]	1-axis controller (incremental for Z-axis)
		SCON-C-60A-NP-2-[1]	1-axis controller (absolute for Z-axis)
3-axis	IK3-PBBG	PSEL-C-2-56PI-42PI-NP-2-0	2-axis controller (for X/Y-axes)
		PCON-C-56PI-NP-2-0	1-axis controller (for X-axis)
		PCON-C-42PI-NP-2-0	1-axis controller (for Y-axis, Z-axis)
		RPCON-56P	1-axis controller (for X-axis)
		RPCON-42P	1-axis controller (for Y-axis, Z-axis)
	IK3-SBBG	SSEL-C-2-100I-60I-NP-2-[1]	2-axis controller (incremental for X/Y-axis)
		SSEL-C-2-100A-60A-NP-2-[1]	2-axis controller (absolute for X/Y-axis)
		SCON-C-100I-NP-2-[1]	1-axis controller (incremental for X-axis)
		SCON-C-100A-NP-2-[1]	1-axis controller (absolute for X-axis)
		SCON-C-60I-NP-2-[1]	1-axis controller (incremental for Y-axis)
		SCON-C-60A-NP-2-[1]	1-axis controller (absolute for Y-axis)
		SCON-C-30I-NP-2-[1]	1-axis controller (incremental for Z-axis)
		SCON-C-30A-NP-2-[1]	1-axis controller (absolute for Z-axis)
		XSEL-J/K/P/Q	Multi-axis controller (incremental or absolute for X/Y/Z-axis)

[1] Power-supply voltage (1: Single-phase 100 VAC / 2: Single-phase 200 VAC)

PSEL

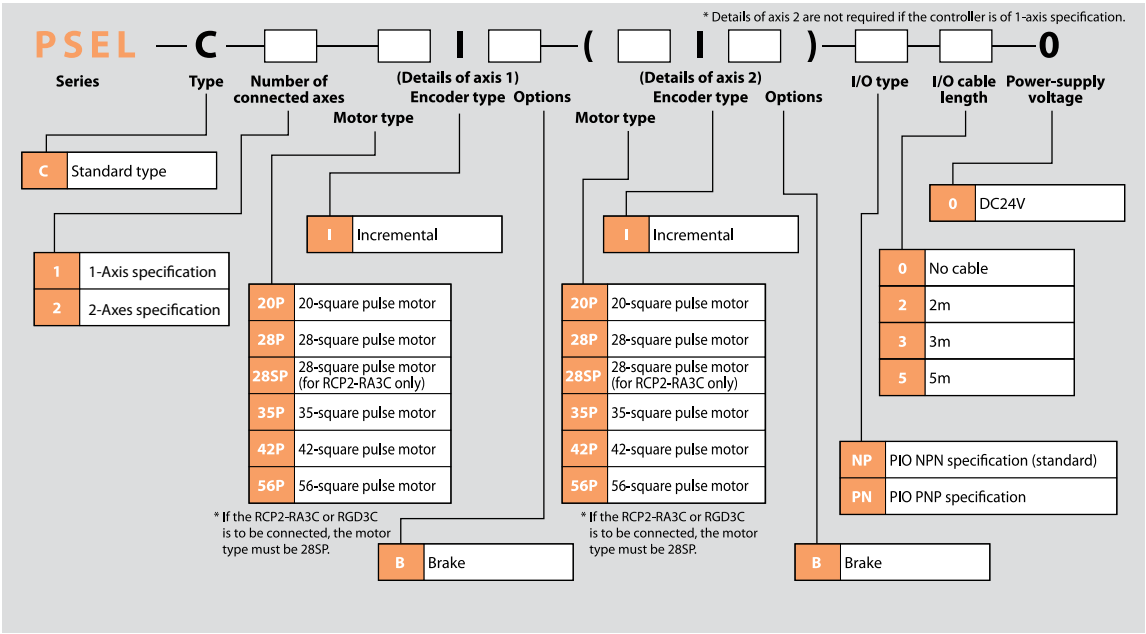
RCP2-series
program controller

Model List

A program controller capable of operating RCP2-series actuators. Various controls can be performed with a single unit.

Type	C	
Name	Program mode	Positioner mode
Exterior view		
Description	This controller can operate actuators and communicate with external devices without requiring any additional device. If two axes are operated, arc interpolation and path operation can be performed.	Up to 1,500 positioning points are supported. Push-motion operation and teaching operation are also possible.
Number of positions	1,500	

Model



I/O Specifications

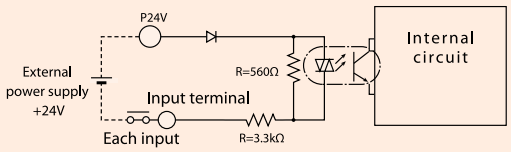
■Input External input specifications

Item	Specification
Input voltage	DC24V ±10%
Input current	7 mA per circuit
ON/OFF voltages	ON voltage (min.) NPN: DC16V/PNP: DC8V OFF voltage (max.) NPN: DC5V/PNP: DC19V
Insulation method	Photo-coupler

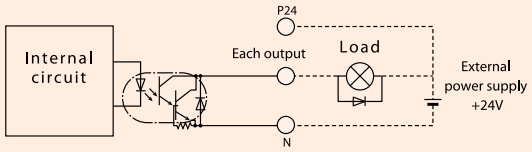
■Output External output specifications

Item	Specification
Load voltage	DC24V
Maximum load current	100 mA per point, total 400 mA for 8 points
Leak current (max.)	Max. 0.1 mA per point
Insulation method	Photo-coupler

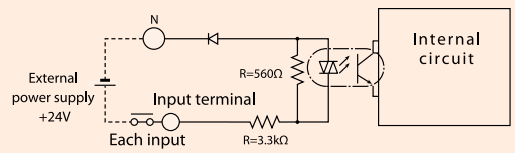
NPN specification



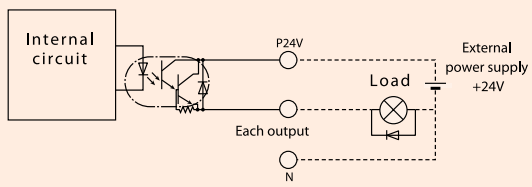
NPN specification



PNP specification



PNP specification



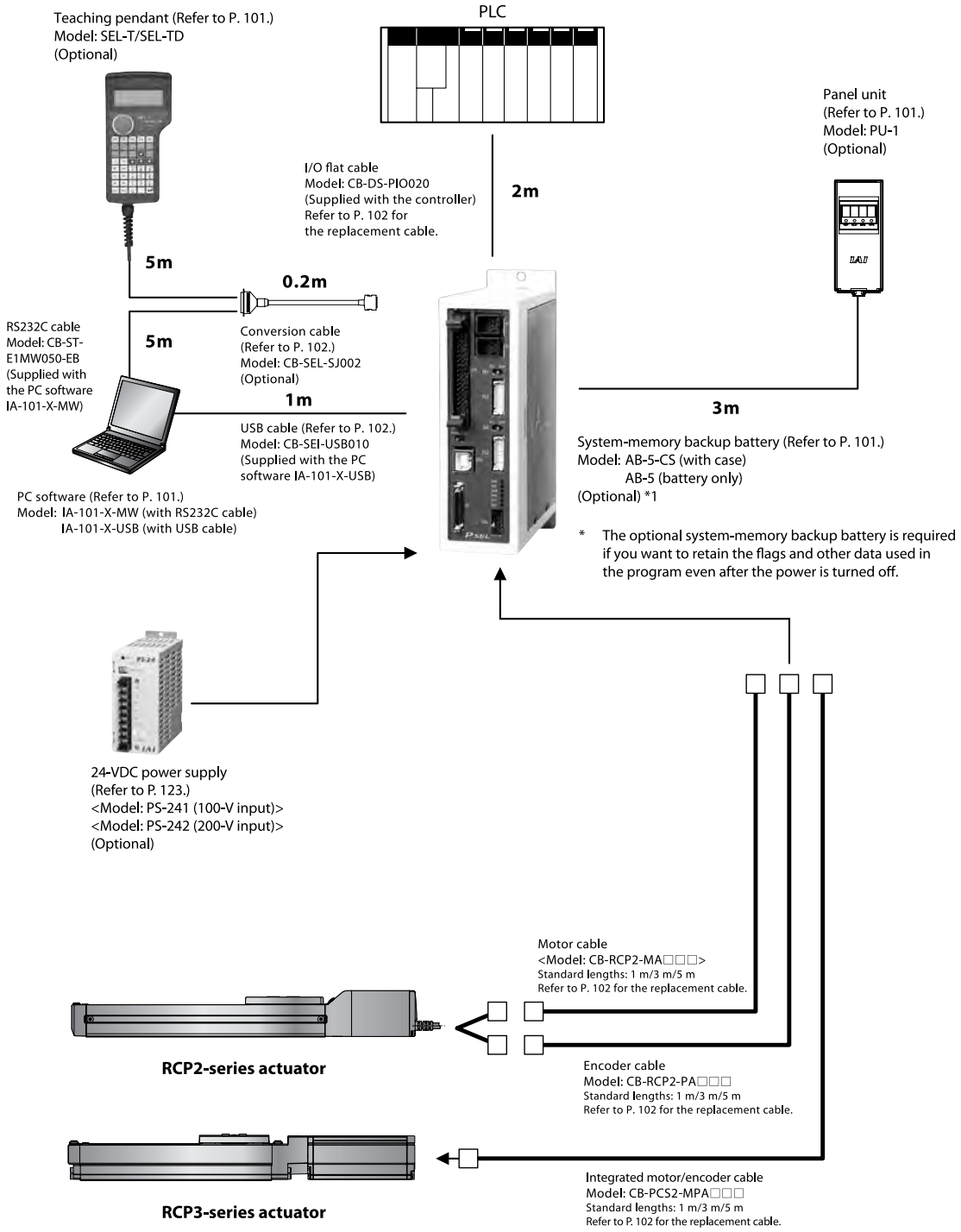
Explanation of I/O Functions

The PSEL controller can be operated in the "Program Mode" where a program is entered to operate the actuator or "Positioner Mode" where the actuator is moved to positions specified by signals received from a host PLC.
The positioner mode includes the following five input patterns to support various applications.

■Functions by Controller Type

Operation mode		Features
Program mode		You can use Super SEL, a language that allows for complex controls using simple commands, to perform linear and smooth interpolation operations, path operation ideal for coating and other applications, arch motion and palletizing operations, and more.
Product-type Switchover Mode	Standard mode	The basic operation mode where all you need is to specify a position number and enter a start signal. Push-motion operation, and linear interpolation operation of two axes, is also supported.
	Type switching mode	When the system handles multiple loads of the same shape but slightly different hole positions, you can issue movement commands to the same position number by changing the type number.
	2-axis independent mode	When a 2-axis controller is used, the two axes can be operated independently using separate commands.
	Teaching mode	The slider (rod) can be moved using an external signal to register the stopped position as position data.
	DS-S-C1 compatible mode	If you have been using a DS-S-C1 controller, you can swap it with a PSEL controller without having to change the host programs. * Compatibility with actuators is not assured.

System Configuration

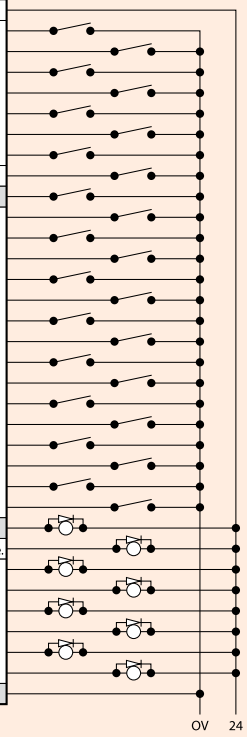


Explanation of I/O Functions

Program Mode

Pin No.	Category	Port No.	Program Mode	Function
1A	P24		24-V input	Connect 24 V.
1B	Input	016	Program No. 1 selection	Select the program number of the program you want to start. (Enter one of ports 016 to 022 by a BCD code.)
2A		017	Program No. 2 selection	
2B		018	Program No. 4 selection	
3A		019	Program No. 8 selection	
3B		020	Program No. 10 selection	
4A		021	Program No. 20 selection	
4B		022	Program No. 40 selection	
5A		023	CPU reset	The system is reset and enters the same state achieved after the power has been reconnected.
5B		000	Start	The program selected by one of port Nos. 016 to 022 is started.
6A		001	General-purpose input	The system waits for an external input in response to a program command.
6B		002	General-purpose input	
7A		003	General-purpose input	
7B		004	General-purpose input	
8A		005	General-purpose input	
8B		006	General-purpose input	
9A		007	General-purpose input	
9B		008	General-purpose input	
10A		009	General-purpose input	
10B		010	General-purpose input	
11A		011	General-purpose input	
11B		012	General-purpose input	
12A		013	General-purpose input	
12B		014	General-purpose input	
13A		015	General-purpose input	
13B	Output	300	Alarm	This signal is output when an alarm has occurred. (Contact B)
14A		301	Ready	This signal is output when the controller has started properly and become ready to operate.
14B		302	General-purpose output	These signals can be turned ON/OFF freely using program commands.
15A		303	General-purpose output	
15B		304	General-purpose output	
16A		305	General-purpose output	
16B		306	General-purpose output	
17A		307	General-purpose output	
17B	N		OV input	Connect OV.

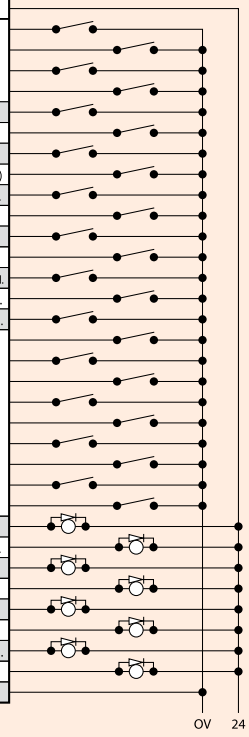
Wiring diagram



Positioner, Standard Mode

Pin No.	Category	Port No.	Standard Positioner Mode	Function
1A	P24		24-V input	Connect 24 V.
1B	Input	016	Position input 10	Use one of port Nos. 007 to 019 to specify the position number corresponding to the position to move the actuator to. The value can be specified by either a BCD or binary code.
2A		017	Position input 11	
2B		018	Position input 12	
3A		019	Position input 13	
3B		020	–	–
4A		021	–	–
4B		022	–	–
5A		023	Error reset	This signal resets minor errors. (The power must be reconnected to reset major errors.)
5B		000	Start	The actuator starts moving to the position corresponding to the selected position number.
6A		001	Home return	The actuator returns home.
6B		002	Servo ON	The servo is turned ON/OFF.
7A		003	Push motion	The actuator performs push-motion operation.
7B		004	Pause	The actuator pauses when this signal turns OFF, and resumes the remaining operation when the signal turns ON.
8A		005	Cancel	The actuator stops when this signal turns OFF, and the remaining operation is cancelled.
8B		006	Interpolation setting	In the case of a 2-axis specification, the actuators move via linear interpolation while this signal is ON.
9A		007	Position input 1	Use one of port Nos. 007 to 019 to specify the position number corresponding to the position to move the actuator to. The value can be specified by either a BCD or binary code.
9B		008	Position input 2	
10A		009	Position input 3	
10B		010	Position input 4	
11A		011	Position input 5	
11B		012	Position input 6	
12A		013	Position input 7	
12B		014	Position input 8	
13A		015	Position input 9	
13B	Output	300	Alarm	This signal is output when an alarm has occurred. (Contact B)
14A		301	Ready	This signal is output when the controller has started properly and become ready to operate.
14B		302	Positioning complete	This signal is output when movement to the specified position has completed.
15A		303	Home return complete	This signal is output when home return has completed.
15B		304	Servo ON output	This signal is output while the servo is ON.
16A		305	Push-motion complete	This signal is output when push-motion operation has completed.
16B		306	System battery error	This signal is output when the system battery voltage has dropped (to the warning level).
17A		307	–	–
17B	N		OV input	Connect OV.

Wiring diagram

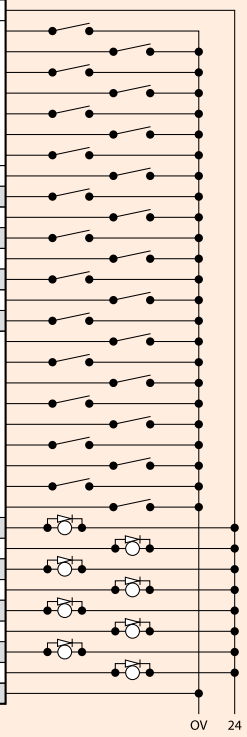


Explanation of I/O Functions

Positioner, Product-Type Switchover Mode

Pin No.	Category	Port No.	Type-switching Positioner Mode	Function
1A	P24		24-V input	Connect 24 V.
1B	Input	016	Position/type input 10	Use one of port Nos. 007 to 022 to specify the position number corresponding to the position to move the actuator to, and another to specify the type number. Assignment of position numbers and type numbers are set using parameters. The value can be specified by either a BCD or binary code.
2A		017	Position/type input 11	
2B		018	Position/type input 12	
3A		019	Position/type input 13	
3B		020	Position/type input 14	
4A		021	Position/type input 15	
4B		022	Position/type input 16	
5A		023	Error reset	This signal resets minor errors. (The power must be reconnected to reset major errors.)
5B		000	Start	The actuator starts moving to the position corresponding to the selected position number.
6A		001	Home return	The actuator returns home.
6B		002	Servo ON	The servo is turned ON/OFF.
7A		003	Push motion	The actuator performs push-motion operation.
7B		004	Pause	The actuator pauses when this signal turns OFF, and resumes the remaining operation when the signal turns ON.
8A		005	Cancel	The actuator stops when this signal turns OFF, and the remaining operation is cancelled.
8B		006	Interpolation setting	In the case of a 2-axis specification, the actuators move via linear interpolation while this signal is ON.
9A		007	Position/type input 1	Use one of port Nos. 007 to 022 to specify the position number corresponding to the position to move the actuator to, and another to specify the type number. Assignment of position numbers and type numbers are set using parameters. The value can be specified by either a BCD or binary code.
9B		008	Position/type input 2	
10A		009	Position/type input 3	
10B		010	Position/type input 4	
11A		011	Position/type input 5	
11B		012	Position/type input 6	
12A		013	Position/type input 7	
12B		014	Position/type input 8	
13A		015	Position/type input 9	
13B	Output	300	Alarm	This signal is output when an alarm has occurred. (Contact B)
14A		301	Ready	This signal is output when the controller has started properly and become ready to operate.
14B		302	Positioning complete	This signal is output when movement to the specified position has completed.
15A		303	Home return complete	This signal is output when home return has completed.
15B		304	Servo ON output	This signal is output while the servo is ON.
16A		305	Push-motion complete	This signal is output when push-motion operation has completed.
16B		306	System battery error	This signal is output when the system battery voltage has dropped (to the warning level).
17A		307	–	–
17B	N		OV input	Connect OV.

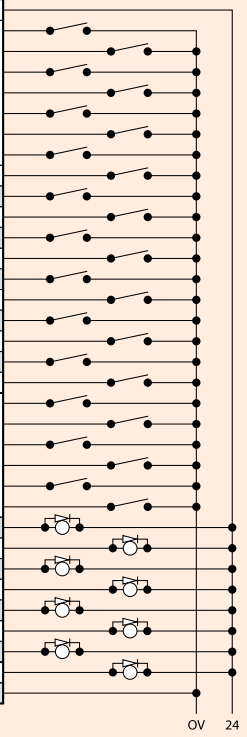
Wiring diagram



Positioner, 2-axes Independent Mode

Pin No.	Category	Port No.	Type-switching Positioner Mode	Function
1A	P24		24-V input	Connect 24 V.
1B	Input	016	Position input 7	Use any of port Nos. 010 to 022 to specify the position number corresponding to the position to move the actuator to. Assignment of position numbers for axes 1 and 2 are set using parameters. The value can be specified by either a BCD or binary code.
2A		017	Position input 8	
2B		018	Position input 9	
3A		019	Position input 10	
3B		020	Position input 11	
4A		021	Position input 12	
4B		022	Position input 13	
5A		023	Error reset	This signal resets minor errors. (The power must be reconnected to reset major errors.)
5B		000	Start 1	Axis 1 starts moving to the selected position number.
6A		001	Home return 1	Axis 1 returns home.
6B		002	Servo ON 1	The servo of axis 1 is turned ON/OFF.
7A		003	Pause 1	Axis 1 pauses when this signal turns OFF, and resumes the remaining operation when the signal turns ON.
7B		004	Cancel 1	Movement of axis 1 is cancelled.
8A		005	Start 2	Axis 2 starts moving to the selected position number.
8B		006	Home return 2	Axis 2 returns home.
9A		007	Servo ON 2	The servo of axis 2 is turned ON/OFF.
9B		008	Pause 2	Axis 2 pauses when this signal turns OFF, and resumes the remaining operation when the signal turns ON.
10A		009	Cancel 2	Movement of axis 2 is cancelled.
10B		010	Position input 1	Use any of port Nos. 010 to 022 to specify the position number corresponding to the position to move the actuator to. Assignment of position numbers for axes 1 and 2 are set using parameters. The value can be specified by either a BCD or binary code.
11A		011	Position input 2	
11B		012	Position input 3	
12A		013	Position input 4	
12B		014	Position input 5	
13A		015	Position input 6	
13B	Output	300	Alarm	This signal is output when an alarm has occurred. (Contact B)
14A		301	Ready	This signal is output when the controller has started properly and become ready to operate.
14B		302	Positioning complete 1	This signal is output when movement of axis 1 to the specified position has completed.
15A		303	Home return complete 1	This signal is output when home return of axis 1 has completed.
15B		304	Servo ON output 1	This signal is output while the servo of axis 1 is ON.
16A		305	Positioning complete 2	This signal is output when movement of axis 2 to the specified position has completed.
16B		306	Home return complete 2	This signal is output when home return of axis 2 has completed.
17A		307	Servo ON output 2	This signal is output while the servo of axis 2 is ON.
17B	N		OV input	Connect OV.

Wiring diagram

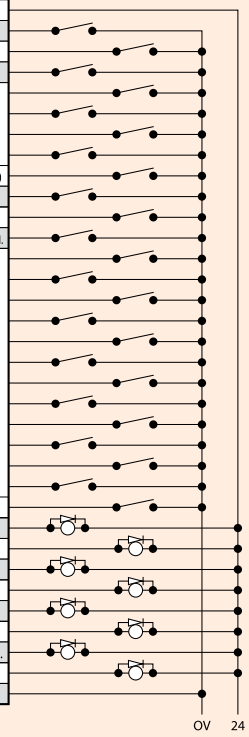


Explanation of I/O Functions

Positioner, Teach Mode

Pin No.	Category	Port No.	Type-switching Positioner Mode	Function
1A	P24		24-V input	Connect 24 V.
1B	Input	016	Axis 1 JOG -	Axis 1 moves in the negative direction while this signal is input.
2A		017	Axis 2 JOG +	Axis 2 moves in the positive direction while this signal is input.
2B		018	Axis 2 JOG -	Axis 2 moves in the negative direction while this signal is input.
3A		019	Inching specification (0.01 mm)	Specify the travel over which to move the actuator by inching. (The travel is the sum of values specified by port Nos. 019 to 022.)
3B		020	Inching specification (0.1 mm)	
4A		021	Inching specification (0.5 mm)	
4B		022	Inching specification (1 mm)	
5A		023	Error reset	This signal resets minor errors. (The power must be reconnected to reset major errors.)
5B		000	Start	The actuator starts moving to the position corresponding to the selected position number.
6A		001	Servo ON	The servo is turned ON/OFF.
6B		002	Pause	The actuator pauses when this signal turns OFF, and resumes the remaining operation when the signal turns ON.
7A		003	Position input 1	Use one of port Nos. 003 to 013 to specify the position number corresponding to the position to move the actuator to, and another to specify the position number under which to input the current position. If port No. 014 for teaching mode specification is ON, the current value is written to the specified position number when port No. 000 for start signal turns ON.
7B		004	Position input 2	
8A		005	Position input 3	
8B		006	Position input 4	
9A		007	Position input 5	
9B		008	Position input 6	
10A		009	Position input 7	
10B		010	Position input 8	
11A		011	Position input 9	
11B		012	Position input 10	
12A		013	Position input 11	
12B		014	Teaching mode specification	
13A		015	Axis 1 JOG +	Axis 1 moves in the positive direction while this signal is input.
13B	Output	300	Alarm	This signal is output when an alarm has occurred. (Contact B)
14A		301	Ready	This signal is output when the controller has started properly and become ready to operate.
14B		302	Positioning complete	This signal is output when movement to the specified position has completed.
15A		303	Home return complete	This signal is output when home return has completed.
15B		304	Servo ON output	This signal is output while the servo is ON.
16A		305	–	–
16B		306	System battery error	This signal is output when the system battery voltage has dropped (to the warning level).
17A		307	–	–
17B	N		OV input	Connect OV.

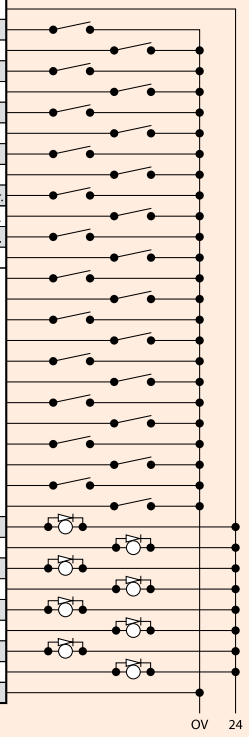
Wiring diagram



Positioner, DS-S-C1 Compatible Mode

Pin No.	Category	Port No.	Standard Positioner Mode	Function
1A	P24		24-V input	Connect 24 V.
1B	Input	016	Position No. 1000	(Same with port Nos. 004 to 015.)
2A		017	–	–
2B		018	–	–
3A		019	–	–
3B		020	–	–
4A		021	–	–
4B		022	–	–
5A		023	CPU reset	The system is reset and enters the same state achieved after the power has been reconnected.
5B		000	Start	The actuator starts moving to the position corresponding to the selected position number.
6A		001	Hold (pause)	The actuator pauses when this signal turns ON, and resumes the remaining operation when the signal turns OFF.
6B		002	Cancel	The actuator stops when this signal turns ON, and the remaining operation is cancelled.
7A		003	Interpolation setting	In the case of a 2-axis specification, the actuators move via linear interpolation while this signal is ON.
7B		004	Position No. 1	Use one of port Nos. 004 to 016 to specify the position number corresponding to the position to move the actuator to. The value is specified by a BCD code.
8A		005	Position No. 2	
8B		006	Position No. 4	
9A		007	Position No. 8	
9B		008	Position No. 10	
10A		009	Position No. 20	
10B		010	Position No. 40	
11A		011	Position No. 80	
11B		012	Position No. 100	
12A		013	Position No. 200	
12B		014	Position No. 400	
13A		015	Position No. 800	
13B	Output	300	Alarm	This signal is output when an alarm has occurred. (Contact A)
14A		301	Ready	This signal is output when the controller has started properly and become ready to operate.
14B		302	Positioning complete	This signal is output when movement to the specified position has completed.
15A		303	–	–
15B		304	–	–
16A		305	–	–
16B		306	System battery error	This signal is output when the system battery voltage has dropped (to the warning level).
17A		307	–	–
17B	N		OV input	Connect OV.

Wiring diagram



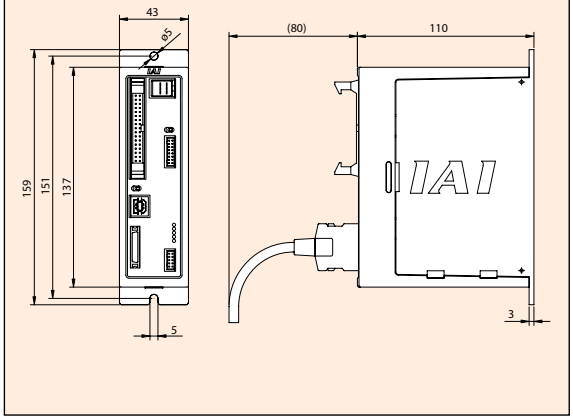
Specification Table

	Item	Specification
Base specifications	Connected actuator	RCP2-series actuator (Note 1)
	Input voltage	24 VDC ±10%
	Power-supply capacity	Max. 5.5 A
	Dielectric strength	500 VDC, 10 MΩ or more
	Withstand voltage	500 VAC, 1 minute
	Rush current	Max. 30 A
	Vibration resistance	XYZ directions: 10 to 57 Hz: (Single amplitude) 0.035 mm (continuous), 0.0 75 mm (intermittent) 58 to 150 Hz: 4.9 m/sec2 (continuous), 9.8 m/sec2 (intermittent)
Control specifications	Number of controlled axes	1/2
	Maximum total output of connected axes	–
	Position detection method	Incremental encoder
	Speed setting	1 mm/sec ~ (The maximum limit varies depending on the actuator.)
	Acceleration setting	0.01 G ~ (The maximum limit varies depending on the actuator.)
	Operation method	Program operation/positioner operation (switchable)
Program	Program language	Super SEL
	Number of programs	64
	Number of program steps	2,000
	Number of multi-tasking programs	8
	Number of positioning points	1500
	Data storage device	Flash ROM (An optional system-memory backup battery can be added.)
	Data input method	Teaching pendant or PC software
Communication related	Number of I/O points	24 input points/8 output points (NPN/PNP selectable)
	I/O power supply	24 VDC ±10%, externally supplied
	PIO cable	CB-DS-PIO□□□ (supplied with the controller)
	Serial communication function	RS232C (half-pitch connector)/USB connector
	Field network cable	(To be supported in the future)
	Motor cable	CB-RCP2-MA□□□ (max. 20 m)
	Encoder cable	CB-RCP2-PA□□□ (max. 20 m)
General specifications	Protective functions	Motor/driver temperature check, encoder open check, soft limit overtravel, system error, battery error, etc.
	Surrounding air temperature/humidity	0 to 40°C, 10 to 95% (non-condensing)
	Surrounding ambience	Free from corrosive gases or significant dust.
	Protection degree	IP20
	Weight	Approx. 450 g
	External dimensions	43 mm (W) x 159 mm (H) x 110 mm (D)

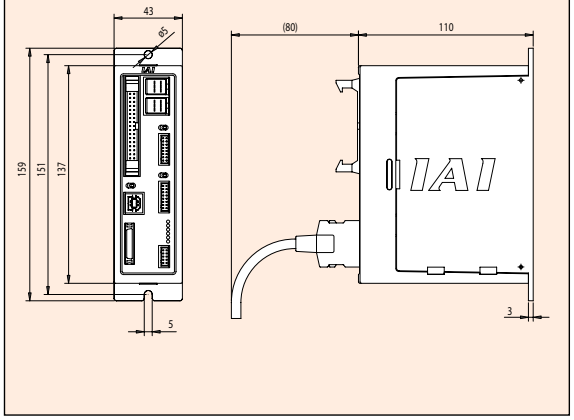
The high-thrust type (RA10C), high-speed type (HS8C/HS8R) and waterproof type (RCP2W-SA16) are not operated.

External Dimensions

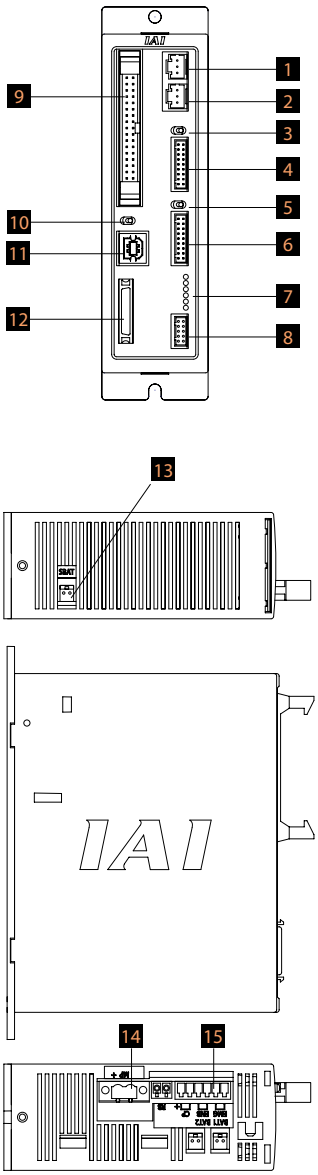
PSEL 1-axis controller



PSEL 2-axis controller



Name of Each part



1 Axis 1 motor connector

Connect the motor cable for actuator axis 1 here.

2 Axis 2 motor connector

Connect the motor cable for actuator axis 2 here.

3 Axis 1 brake switch

This switch is used to release the axis brake. When the switch is set to the left (RLS) position, the brake is forcibly released. When the switch is set to the right (NOM) position, the brake is controlled automatically by the controller.

4 Axis 1 encoder connector

Connect the encoder cable for actuator axis 1 here.

5 Axis 2 brake switch

This switch is used to release the axis brake. When the switch is set to the left (RLS) position, the brake is forcibly released. When the switch is set to the right (NOM) position, the brake is controlled automatically by the controller.

6 Axis 2 encoder connector

Connect the encoder cable for actuator axis 2 here.

7 Status indicator LEDs

These LEDs indicate the operating status of the controller. What is indicated by each LED is explained below:

PWR: The power is currently input to the controller.
RDY: The controller is ready to perform program operation.
ALM: The controller is abnormal.
EMG: An emergency stop has been actuated and the drive source is being cut off.
SV1: The servo of actuator axis 1 is turned ON.
SV2: The servo of actuator axis 2 is turned ON.

8 Panel unit connector

This connector is used to connect the panel unit (optional) for displaying the controller status and error numbers.

9 IO connector

A connector for interface IOs.

If a DIO (24IN/8OUT) interface is used, this connector accepts a 34-pin flat cable connector.

The IO power is also supplied to the controller through this connector (pins 1 and 34).

10 Mode switch

This switch is used to indicate the operation mode of the controller.

The left position indicates the MANU (manual operation) mode, while the right position indicates the AUTO (auto operation) mode. Teaching operation can only be performed in the MANU mode, and operation using external IOs cannot be performed in the MANU mode.

11 USB connector

This connector is used to make USB connection with a PC. When the USB connector is in use, the TP connector cannot be used because communication through the TP connector is cut off.

12 Teaching pendant connector

This half-pitch, IO26-pin connector is used to connect a teaching pendant when the operation mode is MANU. You need a dedicated conversion cable to connect to a conventional D-sub, 25-pin connector.

13 System-memory backup battery connector

This connector is used to connect the battery needed to retain the various data stored in the built-in SRAM of the controller even after the power is cut off. The system-memory backup battery is installed on the exterior of the unit. This battery is not a standard accessory (available as an option).

14 Motor-power input connector

This connector is used to input the motor power and consists of a 2-pin, 2-piece connector by Phoenix Contact.

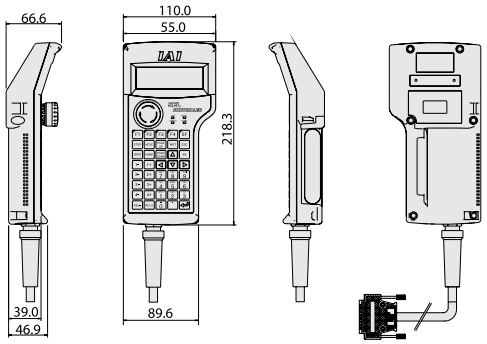
15 Control-power/system input connector

This connector is used to connect the controller power input, emergency stop switch and enable switch, and consists of a 6-pin, 2-piece connector by Phoenix Contact.

Options

Teaching Pendant

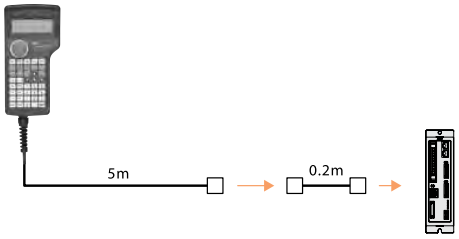
Features A teaching device offering functions for program/position input, test operation, monitoring, and more.



Model/Price

Model	Description
SEL–T–J	Standard type with connector conversion cable
SEL–TD–J	Deadman switch type with connector conversion cable

Configuration



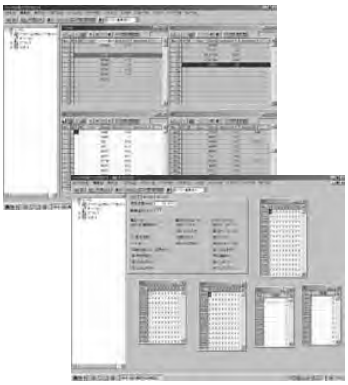
Conversion cable: CB-SEL-SJ002

Specification

Item	SEL–T–J	SEL–TD–J
3-position enable switch	Not equipped	Equipped
ANSI/UL standard	Not compliant	Compliant
CE mark	Compliant	
Display	20 characters x 4 lines	
Surrounding air temperature/humidity	0–40°C 10–90%RH (non-condensing)	
Protection structure	IP54	
Weight	Approx. 0.4 kg (excluding cables)	

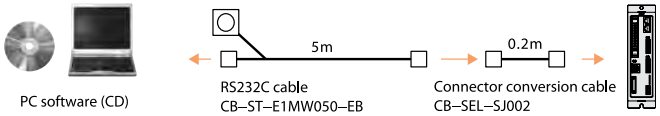
PC Software (Windows only)

Features A software program that assists the initial startup of your system, offering functions for program/position input, test operation, monitoring, and more. The enhanced debugging functions help reduce the startup time.



Model **IA–101–X–MW–J** (with RS232C cable + connector conversion cable)

Configuration



PC software (CD)

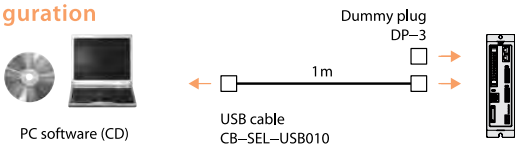
RS232C cable
CB–ST–E1MW050–EB

Connector conversion cable
CB–SEL–SJ002

Model **IA–101–X–USB** (with USB cable)

Note
The PSEL controller only supports version 7.0.0.0 or later.

Configuration



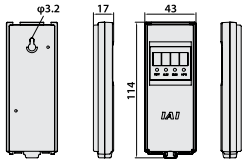
PC software (CD)

USB cable
CB–SEL–USB010

Panel Unit

Features A display for checking controller error codes and the program number of the current program.

Model **PU–1** (cable length: 3 m)



System memory backup battery

Features This battery is needed when global flags, etc., are used in the program and you want the data to be retained even after the power is turned off.

Model **AB–5–CS** (with case)
AB–5 (battery)

Dummy plug

Features This plug is connected to the teaching pendant to cut off the enable circuit when connecting the PSEL controller to a PC via a USB cable.
(This plug is supplied with the PC software IA-101-X-USB.)

Model **DP–3**

Options

USB cable

Features This cable is used to connect a controller with USB port to a PC.
To connect a controller without USB port (XSEL) to a PC, connect the controller's RS232C cable to a USB cable via a USB conversion adapter and connect the USB cable to the USB port on the PC.
(Refer to the PC software IA-101-X-USBMW.)

Model **CB–SEL–USB010** (cable length: 1 m)

Connector conversion cable

Features This conversion cable is used to connect the D-sub, 25-pin connector for teaching pendant or PC to the teaching connector (half-pitch) on the PSEL controller.

Model **CB–SEL–SJ002** (cable length: 0.2 m)

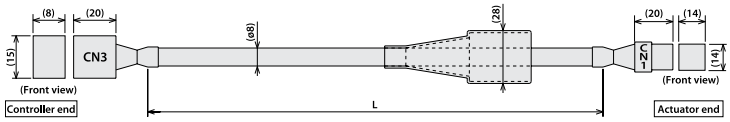
Replacement Parts

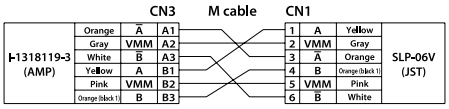
If you must order a replacement cable, etc., after the initial purchase of your product, specify the correct model by referring to the information below.

Motor Cable

Item **CB-RCP2-MA□□□** * The standard motor cable is a robot cable.

* □□□ indicates the cable length (L). A desired length up to 20 m can be specified. Example) 080 = 8 m

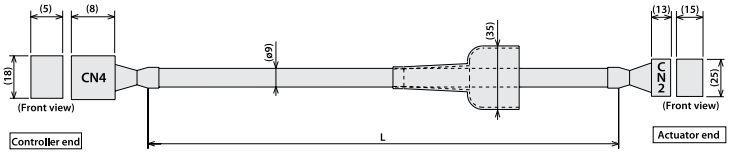


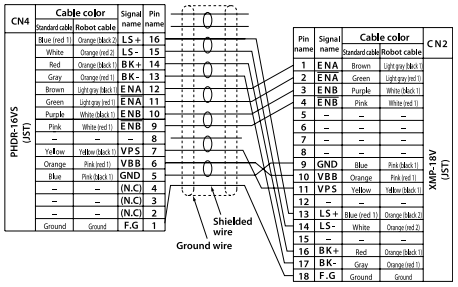


Encoder Cable/Robot Encoder Cable

Item **CB-RCP2-PB□□□/CB-RCP2-PB□□□-RB** * The standard encoder cable is a normal cable. A robot cable can be specified as an option.

* □□□ indicates the cable length (L). A desired length up to 20 m can be specified. Example) 080 = 8 m

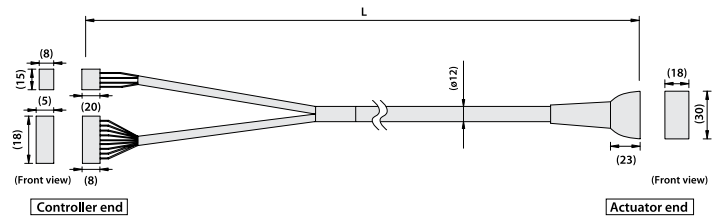


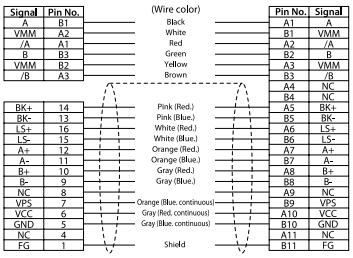


Integrated Motor/Encoder Cable for RCP3

Item **CB-PCS-MPA□□□**

* □□□ indicates the cable length (L). A desired length up to 10 m can be specified. Example) 080 = 8 m

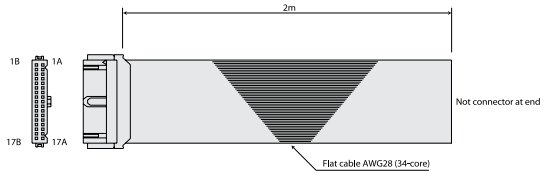




I/O Flat Cable

Item **CB-DS-PIO□□□**

* □□□ indicates the cable length (L). A desired length up to 10 m can be specified. Example) 080 = 8 m



No.	Color	Wire	No.	Color	Wire
1A	Brown 1	Flat cable, pressure-welded	9B	Gray 2	Flat cable, pressure-welded
1B	Red 1		10A	White 2	
2A	Orange 1		10B	Black 2	
2B	Yellow 1		11A	Brown-3	
3A	Green 1		11B	Red 3	
3B	Blue 1		12A	Orange 3	
4A	Purple 1		12B	Yellow 3	
4B	Gray 1		13A	Green 3	
5A	White 1		13B	Blue 3	
5B	Black 1		14A	Purple 3	
6A	Brown-2		14B	Gray 3	
6B	Red 2		15A	White 3	
7A	Orange 2		15B	Black 3	
7B	Yellow 2		16A	Brown-4	
8A	Green 2		16B	Red 4	
8B	Blue 2		17A	Orange 4	
9A	Purple 2		17B	Yellow 4	

SSEL

RCS2-series
program controller

Model List/Pricing

A program controller capable of operating RCS2-series actuators. Various controls can be performed with a single unit.

Type	C	
Name	Program mode	Positioner mode
Exterior view		
Description	This controller can operate actuators and communicate with external devices without requiring any additional device. If two axes are operated, arc interpolation, path operation and synchronized operation can be performed.	Up to 20,000 positioning points are supported. Push-motion operation and teaching operation are also possible.
Number of positions	20,000	

Model

* Details of axis 2 are not required if the controller is of 1-axis specification.

SSEL – C – ☐ ☐ ☐ ☐ (☐ ☐ ☐) ☐ ☐ ☐

Series: SSEL

Type: C Standard type

Number of connected axes: 1 1-axis specification; 2 2-axes specification

(Details of axis 1) Motor type: 20 20-watt servo motor; 30D 30-watt servo motor for RCS2; 30R 30-watt servo motor for RS; 60 60-watt servo motor; 100 100-watt servo motor; 150 150-watt servo motor; 200 200-watt servo motor; 300 300-watt servo motor; 400 400-watt servo motor; 600 600-watt servo motor; 750 750-watt servo motor

(Details of axis 1) Encoder type: I Incremental; A Absolute

(Details of axis 1) Options: B Brake; C Creep sensor; L Home sensor/LS; M Master axis specification

(Details of axis 2) Motor type: 20 20-watt servo motor; 30D 30-watt servo motor for RCS2; 30R 30-watt servo motor for RS; 60 60-watt servo motor; 100 100-watt servo motor; 150 150-watt servo motor; 200 200-watt servo motor; 300 300-watt servo motor; 400 400-watt servo motor; 600 600-watt servo motor; 750 750-watt servo motor

(Details of axis 2) Encoder type: I Incremental; A Absolute

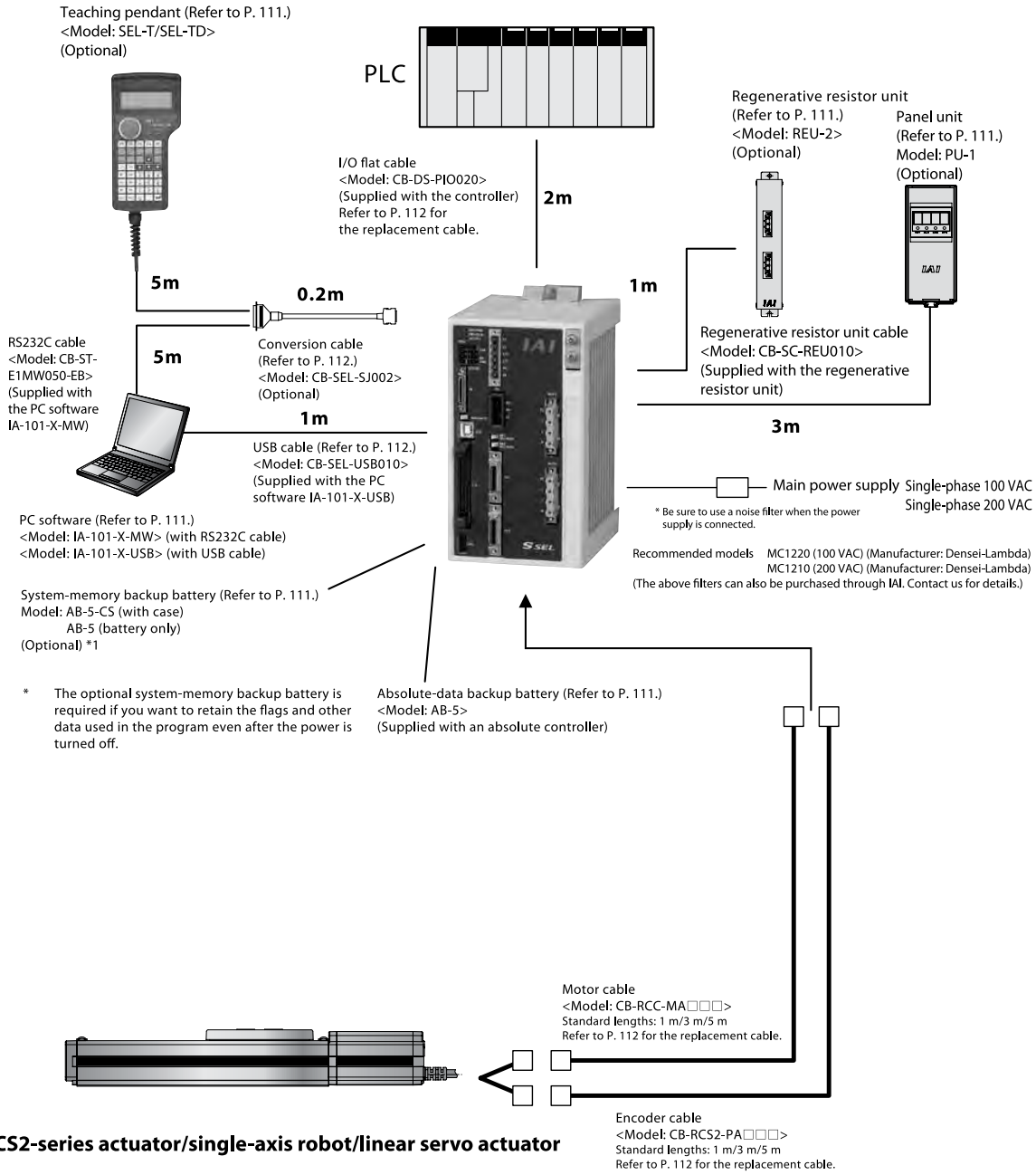
(Details of axis 2) Options: B Brake; C Creep sensor; L Home sensor/LS; S Slave axis specification

I/O type: NP PIO NPN specification (standard); PN PIO PNP specification; DV DeviceNet Connection specification; CC CC-Link Connection specification; PR ProfiBus Connection specification

I/O cable length: 0 No cable; 2 2m; 3 3m; 5 5m

Power-supply voltage: 1 Single-phase 100 VAC; 2 Single-phase 200 VAC

System Configuration



RCS2-series actuator/single-axis robot/linear servo actuator

I/O Specifications

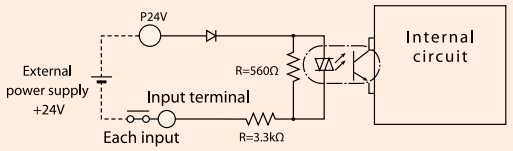
Input External input specifications

Item	Specification
Input voltage	DC24V ±10%
Input current	7 mA per circuit
ON/OFF voltages	ON voltage (min.) NPN: DC16V/PNP: DC8V OFF voltage (max.) NPN: DC5V/PNP: DC19V
Insulation method	Photo-coupler

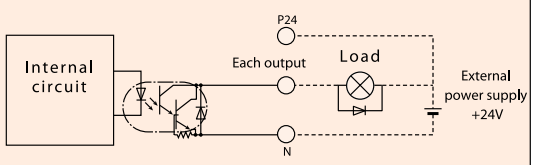
Output External output specifications

Item	Specification
Load voltage	DC24V
Maximum load current	100 mA per point, total 400 mA for 8 points
Leak current (max.)	Max. 0.1 mA per point
Insulation method	Photo-coupler

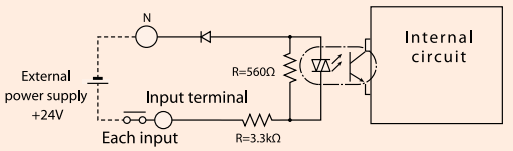
NPN specification



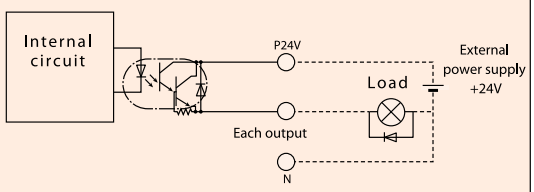
NPN specification



PNP specification



PNP specification



Explanation of I/O Functions

The SSEL controller can be operated in the "Program Mode" where a program is entered to operate the actuator or "Positioner Mode" where the actuator is moved to positions specified by signals received from a host PLC.
The positioner mode includes the following five input patterns to su pport various applications.

Functions by Controller Type

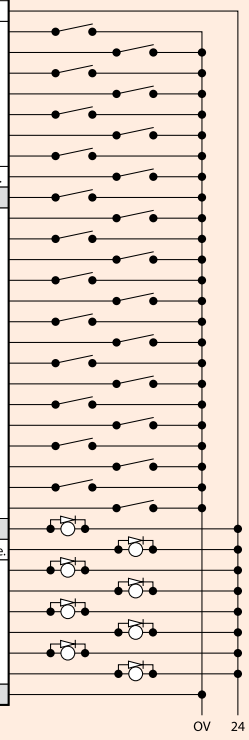
Operation mode		Features
Program mode		You can use Super SEL, a language that allows for complex controls using simple commands, to perform linear and smooth interpolation operations, path operation ideal for coating and other applications, arch motion and palletizing operations, and more.
Product-Type Switchover Mode	Standard mode	The basic operation mode where all you need is to specify a position number and enter a start signal. Push-motion operation, and linear interpolation operation of two axes, is also supported.
	Type switching mode	When the system handles multiple loads of the same shape but slightly different hole positions, you can issue movement commands to the same position number by changing the type number.
	2-axis independent mode	When a 2-axis controller is used, the two axes can be operated independently using separate commands.
	Teaching mode	The slider (rod) can be moved using an external signal to register the stopped position as position data.
	DS-S-C1 compatible mode	If you have been using a DS-S-C1 controller, you can swap it with a PSEL controller without having to change the host programs. * Compatibility with actuators is not assured.

Explanation of I/O Functions

Program Mode

Pin No.	Category	Port No.	Program Mode	Function
1A	P24		24-V input	Connect 24 V.
1B	Input	016	Program No. 1 selection	Select the program number of the program you want to start. (Enter one of ports 016 to 022 by a BCD code.)
2A		017	Program No. 2 selection	
2B		018	Program No. 4 selection	
3A		019	Program No. 8 selection	
3B		020	Program No. 10 selection	
4A		021	Program No. 20 selection	
4B		022	Program No. 40 selection	
5A		023	CPU reset	The system is reset and enters the same state achieved after the power has been reconnected.
5B		000	Start	The program selected by one of port Nos. 016 to 022 is started.
6A		001	General-purpose input	The system waits for an external input in response to a program command.
6B		002	General-purpose input	
7A		003	General-purpose input	
7B		004	General-purpose input	
8A		005	General-purpose input	
8B		006	General-purpose input	
9A		007	General-purpose input	
9B		008	General-purpose input	
10A		009	General-purpose input	
10B		010	General-purpose input	
11A		011	General-purpose input	
11B		012	General-purpose input	
12A		013	General-purpose input	
12B		014	General-purpose input	
13A		015	General-purpose input	
13B	Output	300	Alarm	This signal is output when an alarm has occurred. (Contact B)
14A		301	Ready	This signal is output when the controller has started properly and become ready to operate.
14B		302	General-purpose output	These signals can be turned ON/OFF freely using program commands.
15A		303	General-purpose output	
15B		304	General-purpose output	
16A		305	General-purpose output	
16B		306	General-purpose output	
17A		307	General-purpose output	
17B	N		OV input	Connect OV.

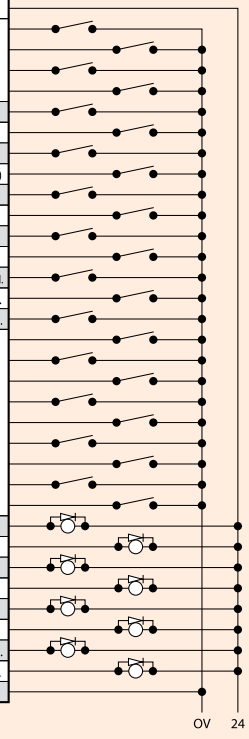
Wiring diagram



Positioner, Standard Mode

Pin No.	Category	Port No.	Standard Positioner Mode	Function
1A	P24		24-V input	Connect 24 V.
1B	Input	016	Position input 10	Use one of port Nos. 007 to 019 to specify the position number corresponding to the position to move the actuator to. The value can be specified by either a BCD or binary code.
2A		017	Position input 11	
2B		018	Position input 12	
3A		019	Position input 13	
3B		020	Position input 14	–
4A		021	Position input 15	–
4B		022	Position input 16	–
5A		023	Error reset	This signal resets minor errors. (The power must be reconnected to reset major errors.)
5B		000	Start	The actuator starts moving to the position corresponding to the selected position number.
6A		001	Home return	The actuator returns home.
6B		002	Servo ON	The servo is turned ON/OFF.
7A		003	Push motion	The actuator performs push-motion operation.
7B		004	Pause	The actuator pauses when this signal turns OFF, and resumes the remaining operation when the signal turns ON.
8A		005	Cancel	The actuator stops when this signal turns OFF, and the remaining operation is cancelled.
8B		006	Interpolation setting	In the case of a 2-axis specification, the actuators move via linear interpolation while this signal is ON.
9A		007	Position input 1	Use one of port Nos. 007 to 019 to specify the position number corresponding to the position to move the actuator to. The value can be specified by either a BCD or binary code.
9B		008	Position input 2	
10A		009	Position input 3	
10B		010	Position input 4	
11A		011	Position input 5	
11B		012	Position input 6	
12A		013	Position input 7	
12B		014	Position input 8	
13A		015	Position input 9	
13B	Output	300	Alarm	This signal is output when an alarm has occurred. (Contact B)
14A		301	Ready	This signal is output when the controller has started properly and become ready to operate.
14B		302	Positioning complete	This signal is output when movement to the specified position has completed.
15A		303	Home return complete	This signal is output when home return has completed.
15B		304	Servo ON output	This signal is output while the servo is ON.
16A		305	Push-motion complete	This signal is output when push-motion operation has completed.
16B		306	System battery error	This signal is output when the system battery voltage has dropped (to the warning level).
17A		307	Absolute battery error	This signal is output when the absolute battery voltage has dropped (to the warning level).
17B	N		OV input	Connect OV.

Wiring diagram

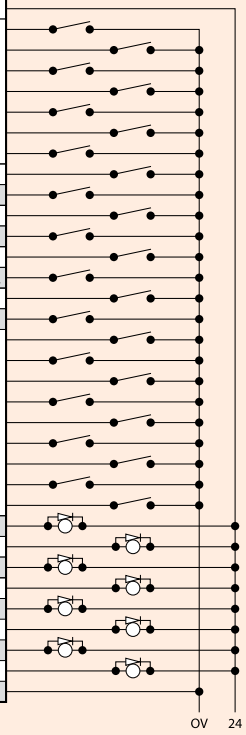


Explanation of I/O Functions

Positioner, Product-Type Switchover Mode

Pin No.	Category	Port No.	Type-switching Positioner Mode	Function
1A	P24		24-V input	Connect 24 V.
1B	Input	016	Position/type input 10	Use one of port Nos. 007 to 022 to specify the position number corresponding to the position to move the actuator to, and another to specify the type number. Assignment of position numbers and type numbers are set using parameters. The value can be specified by either a BCD or binary code.
2A		017	Position/type input 11	
2B		018	Position/type input 12	
3A		019	Position/type input 13	
3B		020	Position/type input 14	
4A		021	Position/type input 15	
4B		022	Position/type input 16	
5A		023	Error reset	This signal resets minor errors. (The power must be reconnected to reset major errors.)
5B		000	Start	The actuator starts moving to the position corresponding to the selected position number.
6A		001	Home return	The actuator returns home.
6B		002	Servo ON	The servo is turned ON/OFF.
7A		003	Push motion	The actuator performs push-motion operation.
7B		004	Pause	The actuator pauses when this signal turns OFF, and resumes the remaining operation when the signal turns ON.
8A		005	Cancel	The actuator stops when this signal turns OFF, and the remaining operation is cancelled.
8B		006	Interpolation setting	In the case of a 2-axis specification, the actuators move via linear interpolation while this signal is ON.
9A		007	Position/type input 1	Use one of port Nos. 007 to 022 to specify the position number corresponding to the position to move the actuator to, and another to specify the type number. Assignment of position numbers and type numbers are set using parameters. The value can be specified by either a BCD or binary code.
9B		008	Position/type input 2	
10A		009	Position/type input 3	
10B		010	Position/type input 4	
11A		011	Position/type input 5	
11B		012	Position/type input 6	
12A		013	Position/type input 7	
12B		014	Position/type input 8	
13A		015	Position/type input 9	
13B	Output	300	Alarm	This signal is output when an alarm has occurred. (Contact B)
14A		301	Ready	This signal is output when the controller has started properly and become ready to operate.
14B		302	Positioning complete	This signal is output when movement to the specified position has completed.
15A		303	Home return complete	This signal is output when home return has completed.
15B		304	Servo ON output	This signal is output while the servo is ON.
16A		305	Push-motion complete	This signal is output when push-motion operation has completed.
16B		306	System battery error	This signal is output when the system battery voltage has dropped (to the warning level).
17A		307	Absolute battery error	This signal is output when the absolute battery voltage has dropped (to the warning level).
17B	N		OV input	Connect OV.

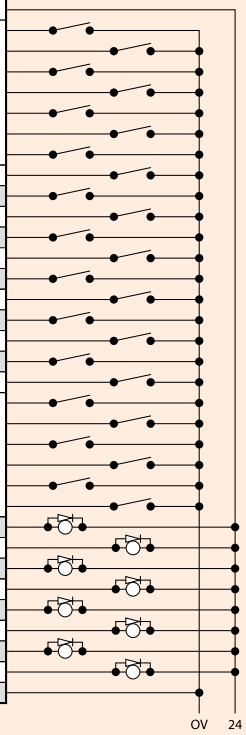
Wiring diagram



Positioner, 2-axes Independent Mode

Pin No.	Category	Port No.	Type-switching Positioner Mode	Function
1A	P24		24-V input	Connect 24 V.
1B	Input	016	Position input 7	Use any of port Nos. 010 to 022 to specify the position number corresponding to the position to move the actuator to. Assignment of position numbers for axes 1 and 2 are set using parameters. The value can be specified by either a BCD or binary code.
2A		017	Position input 8	
2B		018	Position input 9	
3A		019	Position input 10	
3B		020	Position input 11	
4A		021	Position input 12	
4B		022	Position input 13	
5A		023	Error reset	This signal resets minor errors. (The power must be reconnected to reset major errors.)
5B		000	Start 1	Axis 1 starts moving to the selected position number.
6A		001	Home return 1	Axis 1 returns home.
6B		002	Servo ON 1	The servo of axis 1 is turned ON/OFF.
7A		003	Pause 1	Axis 1 pauses when this signal turns OFF, and resumes the remaining operation when the signal turns ON.
7B		004	Cancel 1	Movement of axis 1 is cancelled.
8A		005	Start 2	Axis 2 starts moving to the selected position number.
8B		006	Home return 2	Axis 2 returns home.
9A		007	Servo ON 2	The servo of axis 2 is turned ON/OFF.
9B		008	Pause 2	Axis 2 pauses when this signal turns OFF, and resumes the remaining operation when the signal turns ON.
10A		009	Cancel 2	Movement of axis 2 is cancelled.
10B		010	Position input 1	Use any of port Nos. 010 to 022 to specify the position number corresponding to the position to move the actuator to. Assignment of position numbers for axes 1 and 2 are set using parameters. The value can be specified by either a BCD or binary code.
11A		011	Position input 2	
11B		012	Position input 3	
12A		013	Position input 4	
12B		014	Position input 5	
13A		015	Position input 6	
13B	Output	300	Alarm	This signal is output when an alarm has occurred. (Contact B)
14A		301	Ready	This signal is output when the controller has started properly and become ready to operate.
14B		302	Positioning complete 1	This signal is output when movement of axis 1 to the specified position has completed.
15A		303	Home return complete 1	This signal is output when home return of axis 1 has completed.
15B		304	Servo ON output 1	This signal is output while the servo of axis 1 is ON.
16A		305	Positioning complete 2	This signal is output when movement of axis 2 to the specified position has completed.
16B		306	Home return complete 2	This signal is output when home return of axis 2 has completed.
17A		307	Servo ON output 2	This signal is output while the servo of axis 2 is ON.
17B	N		OV input	Connect OV.

Wiring diagram

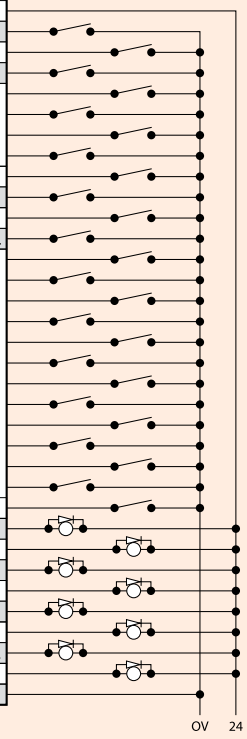


Explanation of I/O Functions

Positioner, Teaching Mode

Pin No.	Category	Port No.	Type-switching Positioner Mode	Function
1A	P24		24-V input	Connect 24 V.
1B	Input	016	Axis 1 JOG –	Axis 1 moves in the negative direction while this signal is input.
2A		017	Axis 2 JOG +	Axis 2 moves in the positive direction while this signal is input.
2B		018	Axis 2 JOG –	Axis 2 moves in the negative direction while this signal is input.
3A		019	Inching specification (0.01 mm)	Specify the travel over which to move the actuator by inching. (The travel is the sum of values specified by port Nos. 019 to 022.)
3B		020	Inching specification (0.1 mm)	
4A		021	Inching specification (0.5 mm)	
4B		022	Inching specification (1 mm)	
5A		023	Error reset	This signal resets minor errors. (The power must be reconnected to reset major errors.)
5B		000	Start	The actuator starts moving to the position corresponding to the selected position number.
6A		001	Servo ON	The servo is turned ON/OFF.
6B		002	Pause	The actuator pauses when this signal turns OFF, and resumes the remaining operation when the signal turns ON.
7A		003	Position input 1	Use one of port Nos. 003 to 013 to specify the position number corresponding to the position to move the actuator to, and another to specify the position number under which to input the current position. If port No. 14 for teaching mode specification is ON, the current value is written to the specified position number when port No. 000 for start signal turns ON.
7B		004	Position input 2	
8A		005	Position input 3	
8B		006	Position input 4	
9A		007	Position input 5	
9B		008	Position input 6	
10A		009	Position input 7	
10B		010	Position input 8	
11A		011	Position input 9	
11B		012	Position input 10	
12A		013	Position input 11	
12B		014	Teaching mode specification	
13A		015	Axis 1 JOG +	Axis 1 moves in the positive direction while this signal is input.
13B	Output	300	Alarm	This signal is output when an alarm has occurred. (Contact B)
14A		301	Ready	This signal is output when the controller has started properly and become ready to operate.
14B		302	Positioning complete	This signal is output when movement to the specified position has completed.
15A		303	Home return complete	This signal is output when home return has completed.
15B		304	Servo ON output	This signal is output while the servo is ON.
16A		305	–	–
16B		306	System battery error	This signal is output when the system battery voltage has dropped (to the warning level).
17A		307	Absolute battery error	This signal is output when the absolute battery voltage has dropped (to the warning level).
17B	N		OV input	Connect OV.

Wiring diagram

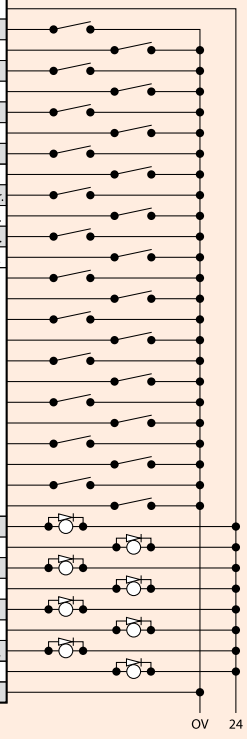


Positioner, DS-S-C1 Compatible Mode

Pin No.	Category	Port No.	Standard Positioner Mode	Function
1A	P24		24-V input	Connect 24 V.
1B	Input	016	Position No. 1000	(Same with port Nos. 004 to 015.)
2A		017	Position No. 2000	–
2B		018	Position No. 4000	–
3A		019	Position No. 8000	–
3B		020	Position No. 10000	–
4A		021	Position No. 20000	–
4B		022	NC (*1)	–
5A		023	CPU reset	The system is reset and enters the same state achieved after the power has been reconnected.
5B		000	Start	The actuator starts moving to the position corresponding to the selected position number.
6A		001	Hold (pause)	The actuator pauses when this signal turns ON, and resumes the remaining operation when the signal turns OFF.
6B		002	Cancel	The actuator stops when this signal turns ON, and the remaining operation is cancelled.
7A		003	Interpolation setting	In the case of a 2-axis specification, the actuators move via linear interpolation while this signal is ON.
7B		004	Position No. 1	Use one of port Nos. 004 to 016 to specify the position number corresponding to the position to move the actuator to. The value is specified by a BCD code.
8A		005	Position No. 2	
8B		006	Position No. 4	
9A		007	Position No. 8	
9B		008	Position No. 10	
10A		009	Position No. 20	
10B		010	Position No. 40	
11A		011	Position No. 80	
11B		012	Position No. 100	
12A		013	Position No. 200	
12B		014	Position No. 400	
13A		015	Position No. 800	
13B	Output	300	Alarm	This signal is output when an alarm has occurred. (Contact A)
14A		301	Ready	This signal is output when the controller has started properly and become ready to operate.
14B		302	Positioning complete	This signal is output when movement to the specified position has completed.
15A		303	–	–
15B		304	–	–
16A		305	–	–
16B		306	System battery error	This signal is output when the system battery voltage has dropped (to the warning level).
17A		307	Absolute battery error	This signal is output when the absolute battery voltage has dropped (to the warning level).
17B	N		OV input	Connect OV.

(*1) This input must be turned OFF. Make sure the signal is not connected.

Wiring diagram



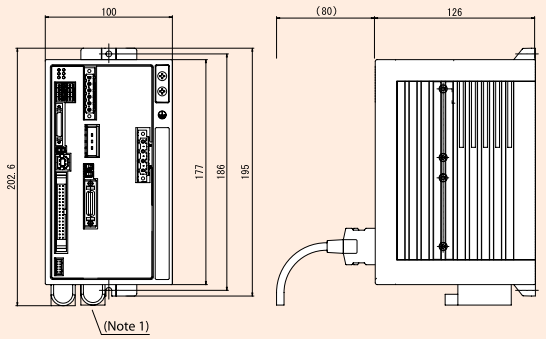
Specification Table

	Item	Specification	
Base specifications	Connected actuator	RCS2-series actuator/single-axis robot/linear servo actuator	
	Input power supply	Single-phase 100 VAC ±10%	Single-phase 200 VAC ±10%
	Power-supply capacity	Max. 1660 VA (400 W, 2-axis operation)	
	Dielectric strength	500 VDC, 10 MΩ or more	
	Withstand voltage	500 VAC, 1 minute	
	Rush current	Max. 30 A	
	Vibration resistance	XYZ directions: 10 to 57 Hz: (Single amplitude) 0.035 mm (continuous), 0.0 75 mm (intermittent) 58 to 150 Hz: 4.9 m/sec2 (continuous), 9.8 m/sec2 (intermittent)	
Control specifications	Number of controlled axes	1/2	
	Maximum total output of connected axes	400 W	800 W
	Position detection method	Incremental encoder/Absolute encoder	
	Speed setting	1 mm/sec ~ (The maximum limit varies depending on the actuator.)	
	Acceleration setting	0.01 G ~ (The maximum limit varies depending on the actuator.)	
	Operation method	Program operation/positioner operation (switchable)	
Program	Program language	Super SEL	
	Number of programs	128 (*1)	
	Number of program steps	9999 (*1)	
	Number of multi-tasking programs	8	
	Number of positioning points	20000 (*1)	
	Data storage device	Flash ROM (An optional system-memory backup battery can be added.)	
	Data input method	Teaching pendant or PC software	
Communication related	Number of I/O points	24 input points/8 output points (NPN/PNP selectable)	
	I/O power supply	24 VDC ±10%, externally supplied	
	PIO cable	CB-DS-PIO□□□ (supplied with the controller)	
	Serial communication function	RS232C (half-pitch connector)/USB connector	
	Field network cable	(To be supported in the future)	
	Motor cable	CB-RCC2-MA□□□ (max. 20 m)	
	Encoder cable	CB-RCS2-PA □□□ (max. 20 m)	
General specifications	Protective functions	Motor overcurrent, motor/driver temperature check, overload check, encoder open check, soft limit overtravel, system battery error, etc.	
	Surrounding air temperature/humidity	0 to 40°C, 10 to 95% (non-condensing)	
	Surrounding ambience	Free from corrosive gases or significant dust.	
	Protection degree	IP20	
	Weight	1.4 kg	
	External dimensions	100 mm (W) x 202.6 mm (H) x 126 mm (D)	

(*1) These specifications are different for PNP controllers. Contact IAI for details.

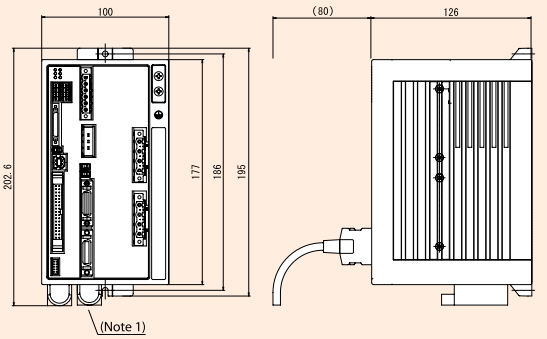
External Dimensions

SSEL 1-axis controller



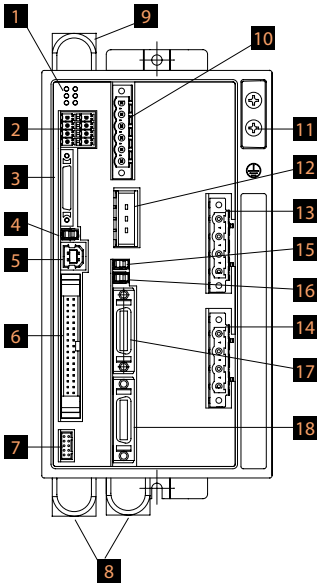
(Note 1) Absolute-data backup battery. This battery is not installed on incremental controllers.

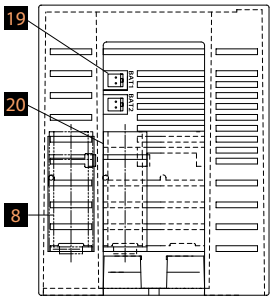
SSEL 2-axis controller

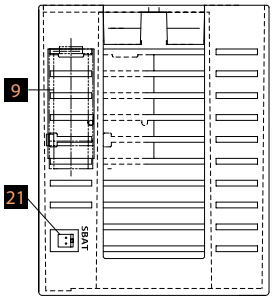


(Note 1) Absolute-data backup battery. This battery is not installed on incremental controllers.

Name of Each Part







1 Status indicator LEDs

These LEDs indicate the operating status of the controller. What is indicated by each LED is explained below:

PWR: The power is currently input to the controller.
RDY: The controller is ready to perform program operation.
ALM: The controller is abnormal.
EMG: An emergency stop has been actuated and the drive source is being cut off.
SV1: The servo of actuator axis 1 is turned ON.
SV2: The servo of actuator axis 2 is turned ON.

2 System I/O connector

This connector connects the emergency stop input, enable input, brake power input, etc.

3 Teaching pendant connector

This half-pitch, IO26-pin connector is used to connect a teaching pendant when the operation mode is MANU. You need a dedicated conversion cable to connect to a conventional D-sub, 25-pin connector.

4 Mode switch

This switch is used to indicate the operation mode of the controller. The left position indicates the MANU (manual operation) mode, while the right position indicates the AUTO (auto operation) mode. Teaching operation can only be performed in the MANU mode, and auto operation using external IOs cannot be performed in the MANU mode.

5 USB connector

This connector is used to make USB connection with a PC. When the USB connector is in use, the TP connector cannot be used because communication through the TP connector is cut off.

6 IO connector

A connector for interface IOs.
If a DIO (24IN/8OUT) interface is used, this connector accepts a 34-pin flat cable connector.
The I/O power is also supplied to the controller through this connector (pins 1 and 34).

7 Panel unit connector

This connector is used to connect the panel unit (optional) for displaying the controller status and error numbers.

8 Absolute-data backup battery

This battery is used to retain position data even after the power is cut off when an absolute axis is operated.

9 System-memory backup battery (optional)

This connector is used to connect the battery needed to retain the various data stored in the built-in SRAM of the controller even after the power is cut off. The system-memory backup battery is an optional. Specify the battery only if necessary.

10 Power-supply connector

A connector for AC power supply. The control power and motor power are input separately.

11 Grounding screw

A screw for protective grounding. Be sure to connect this screw to ground.

12 External regenerative resistor connector

This connector is used to connect an additional regenerative resistor when the built-in regenerative resistor is not enough due to high acceleration, high load, etc.
Whether or not an external regenerative resistor is needed depends on the specifics of the application, such as the axis configuration.

13 Axis 1 motor connector

Connect the motor cable for actuator axis 1 here.

14 Axis 2 motor connector

Connect the motor cable for actuator axis 2 here.

15 Axis 1 brake switch

This switch is used to release the axis brake. When the switch is set to the left (RLS) position, the brake is forcibly released. When the switch is set to the right (NOM) position, the brake is controlled automatically by the controller.

16 Axis 2 brake switch

This switch is used to release the axis brake. When the switch is set to the left (RLS) position, the brake is forcibly released. When the switch is set to the right (NOM) position, the brake is controlled automatically by the controller.

17 Axis 1 encoder connector

Connect the encoder cable for actuator axis 1 here.

18 Axis 2 encoder connector

Connect the encoder cable for actuator axis 2 here.

19 Axis 1 absolute battery connector

This connector is used to connect the absolute-data backup battery for axis 1 when the actuator is equipped with an absolute encoder.

20 Axis 2 absolute battery connector

This connector is used to connect the absolute-data backup battery for axis 2 when the actuator is equipped with an absolute encoder.

21 System-memory backup battery connector

This connector is used to connect the system-memory backup battery.

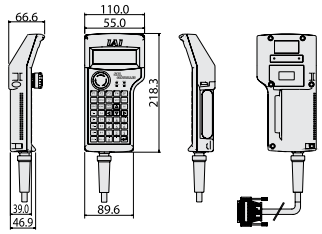
Options

Teaching Pendant

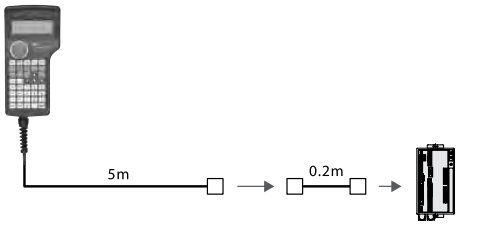
Features A teaching device offering functions for program/position input, test operation, monitoring, and more.

Model/Price

Model	Description
SEL–T–J	Standard type with connector conversion cable
SEL–TD–J	Deadman switch type with connector conversion cable



Configuration



Conversion cable: CB-SEL-SJ002

Specification

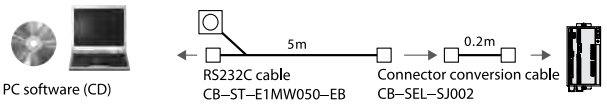
Item	SEL–T–J	SEL–TD–J
3-position enable switch	Not equipped	Equipped
ANSI/UL standard	Not compliant	Compliant
CE mark	Compliant	
Display	20 characters x 4 lines	
Surrounding air temperature/humidity	0–40°C 10–90%RH (non-condensing)	
Protection structure	IP54	
Weight	Approx. 0.4 kg (excluding cables)	

PC Software (Windows only)

Features A software program that assists the initial startup of your system, offering functions for program/position input, test operation, monitoring, and more. The enhanced debugging functions help reduce the startup time.

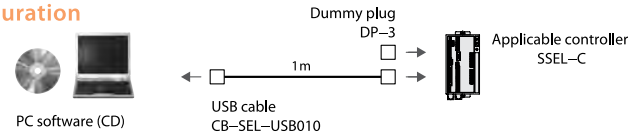
Model **IA–101–X–MW–J** (with RS232C cable + connector conversion cable)
IA–101–X–MW (with RS232C cable)

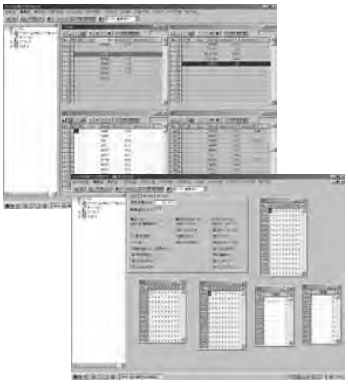
Configuration



Model **IA–101–X–USB** (with USB cable)

Configuration





Note
The SSEL controller only supports version 6.0.0.0 or later.

Regenerative Resistor Unit

Features This unit converts to heat the regenerative current produced when the motor decelerates. Use the table on the right to check the total wattage of the actuators to be operated, and provide a regenerative resistor or resistors if necessary.

Item **REU–2** (for SCON/SSEL)

Specification

Weight	0.9kg
Built-in regenerative resistor	220Ω 80W
Unit-controller connection cable (supplied)	CB–SC–REU010 (for SSEL)

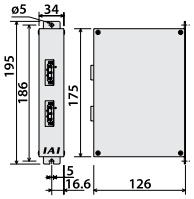
* If two regeneration units are required, order one REU-2 and one REU-1 (refer to P. 132).

Guide for Determining Necessary Number of Regenerative Resistor Units

	Horizontal	Vertical
0 unit	~800W	~200W
1 unit		~600W
2 unit		~800W

* Depending on the operating conditions, the required number of regenerative resistor unit(s) may be more than what is specified above.

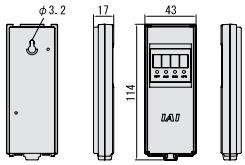
External Dimensions



Panel Unit

Features A display for checking controller error codes and the program number of the current program.

Model **PU–1** (cable length: 3 m)



Absolute-data Backup Battery

Features An absolute-data backup battery used when an absolute actuator is operated. The battery is the same as the system-memory backup battery.

Model **AB–5**

System memory backup battery

Features This battery is needed when global flags, etc., are used in the program and you want the data to be retained even after the power is turned off.

Model **AB–5–CS** (with case)
AB–5 (battery)

Options

Dummy plug

Features This plug is connected to the teaching pendant to cut off the enable circuit when connecting the SSEL controller to a PC via a USB cable.
(This plug is supplied with the PC software IA-101-X-USB.)

Model **DP–3**

USB cable

Features This cable is used to connect a controller with USB port to a PC.
To connect a controller without USB port (XSEL) to a PC, connect the controller's RS232C cable to a USB cable via a USB conversion adapter and connect the USB cable to the USB port on the PC.
(Refer to the PC software IA-101-X-USBMW.)

Model **CB–SEL–USB010** (cable length: 1 m)

Connector conversion cable

Features This conversion cable is used to connect the D-sub, 25-pin connector for teaching pendant or PC to the teaching connector (half-pitch) on the SSEL controller.

Model **CB–SEL–SJ002** (cable length: 0.2 m)

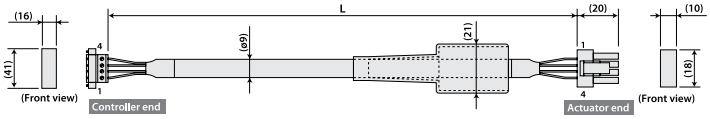
Replacement Parts

If you must order a replacement cable, etc., after the initial purchase of your product, specify the correct model by referring to the information below.

Motor Cable/Robot Motor Cable

Item CB-RCC-MA□□□ / CB-RCC-MA□□□-RB

*□□□ indicates the cable length (L). A desired length up to 30 m can be specified. Example) 080 = 8 m



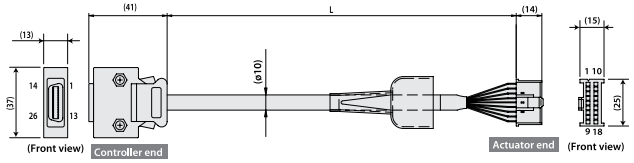
Wire	Color	Signal	
0.75sq	Green	PE	1
	Red	U	2
	White	V	3
	Black	W	4

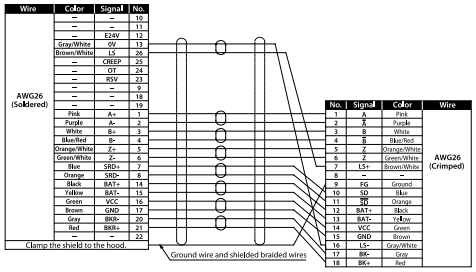
	Signal	Color	Wire
1	U	Red	0.75sq (Crimped)
2	V	White	
3	W	Black	
4	PE	Green	

Encoder Cable/Robot Encoder Cable

Item CB-RCS2-PA□□□ / CB-X3-PA□□□

*□□□ indicates the cable length (L). A desired length up to 30 m can be specified. Example) 080 = 8 m

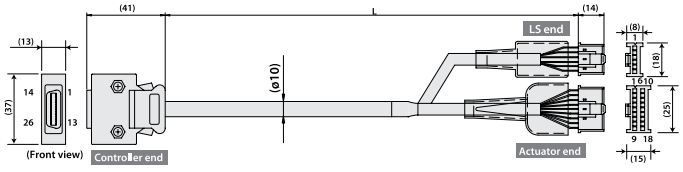


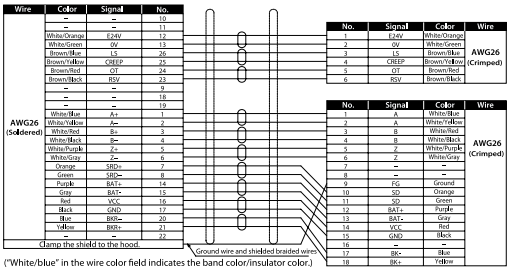


Encoder Cable/Robot Encoder Cable for RCS2-RT6/RT6R/RT7R

Item CB-RCS2-PLA□□□ / CB-X2-PLA□□□

*□□□ indicates the cable length (L). A desired length up to 30 m can be specified. Example) 080 = 8 m



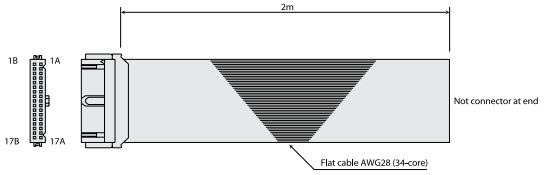


("White/blue" in the wire color field indicates the band color/insulator color.)

I/O Flat Cable

Item CB-DS-PIO□□□

*□□□ indicates the cable length (L). A desired length up to 10 m can be specified. Example) 080 = 8 m



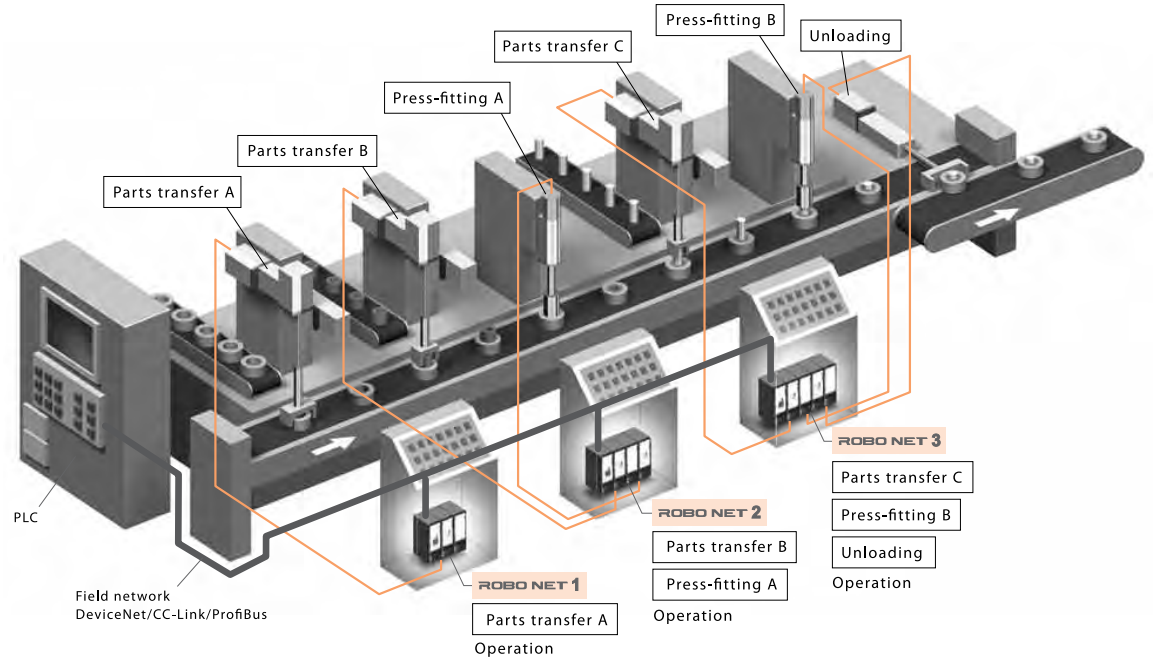
No.	Color	Wire	No.	Color	Wire
1A	Brown 1	Flat cable, pressure-welded	9B	Gray 2	Flat cable, pressure-welded
1B	Red 1		10A	White 2	
2A	Orange 1		10B	Black 2	
2B	Yellow 1		11A	Brown-3	
3A	Green 1		11B	Red 3	
3B	Blue 1		12A	Orange 3	
4A	Purple 1		12B	Yellow 3	
4B	Gray 1		13A	Green 3	
5A	White 1		13B	Blue 3	
5B	Black 1		14A	Purple 3	
6A	Brown-2		14B	Gray 3	
6B	Red 2		15A	White 3	
7A	Orange 2		15B	Black 3	
7B	Yellow 2		16A	Brown-4	
8A	Green 2		16B	Red 4	
8B	Blue 2		17A	Orange 4	
9A	Purple 2		17B	Yellow 4	

ROBONET

Dedicated field network controller

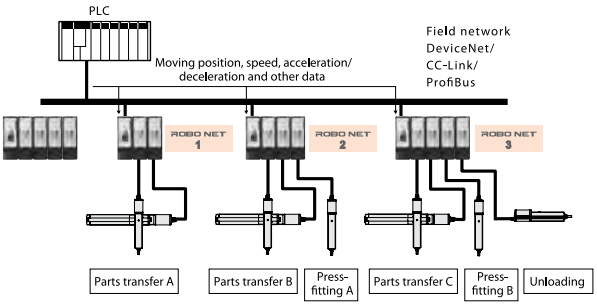
The ROBONET is a new type of controller unit capable of operating ROBO Cylinders at will via a field network. Adopting the wire-saving design, compact size and DIN-rail installation feature, the ROBONET lets you save the hassle of wiring and installation considerably compared to existing controllers.

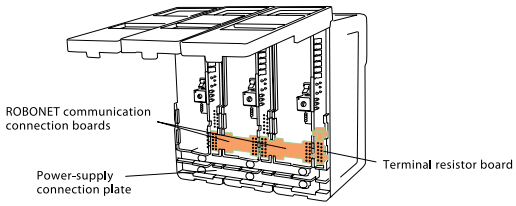
Standard type



1 Wire-saving

Instead of connecting the I/O cables one by one to the PLC terminal, all I/Os can be connected via a field network. This means all you need to complete the wiring is to connect one dedicated cable. Also, units can be linked simply by interconnecting the unit connection boards, which significantly reduces the hassle of controller wiring.





(Linking units inside ROBONET)

2 Operation by Direct Numerical Specification of Moving Position, Speed, Acceleration/Deceleration, Etc.

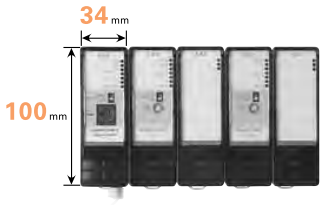
In addition to using the traditional method of entering moving positions and speeds under position numbers and then specifying desired position numbers eternally, you can also send moving positions (coordinates), speeds, accelerations/decelerations, etc., as numeric data to operate the actuator.
This method is effective in situations where the moving position changes for each load or you want to move the load to a desired position.

	ROBONET controller	Standard controller (ACON/PCON)
Movement by position specification	○	○
Movement by direct numerical specification	○	△ (Not supported in the PIO mode) (Supported in the serial communication mode.)
Speed/acceleration specification	○	
Current value output	○	

* The ROBONET operates via a field network, while the standard controller operates using PIOs.

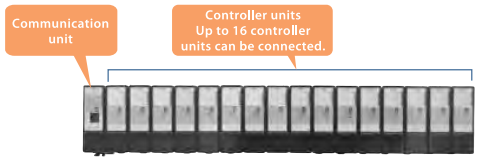
3 Ultra-compact

Each unit adopts an ultra-compact size of just 34 mm (w) x 100 mm (h) x 73 mm (d).
Since there is no base unit and the controllers are linked using connectors, the installation space is minimized even when many units must be connected.



4 Up to 16 Controllers Can Be Operated

Up to 16 controller units can be connected to one communication unit (Gateway R unit). You can connect a desired combination of RACON units (RCA controllers) and RPCON units (RCP2 controllers).



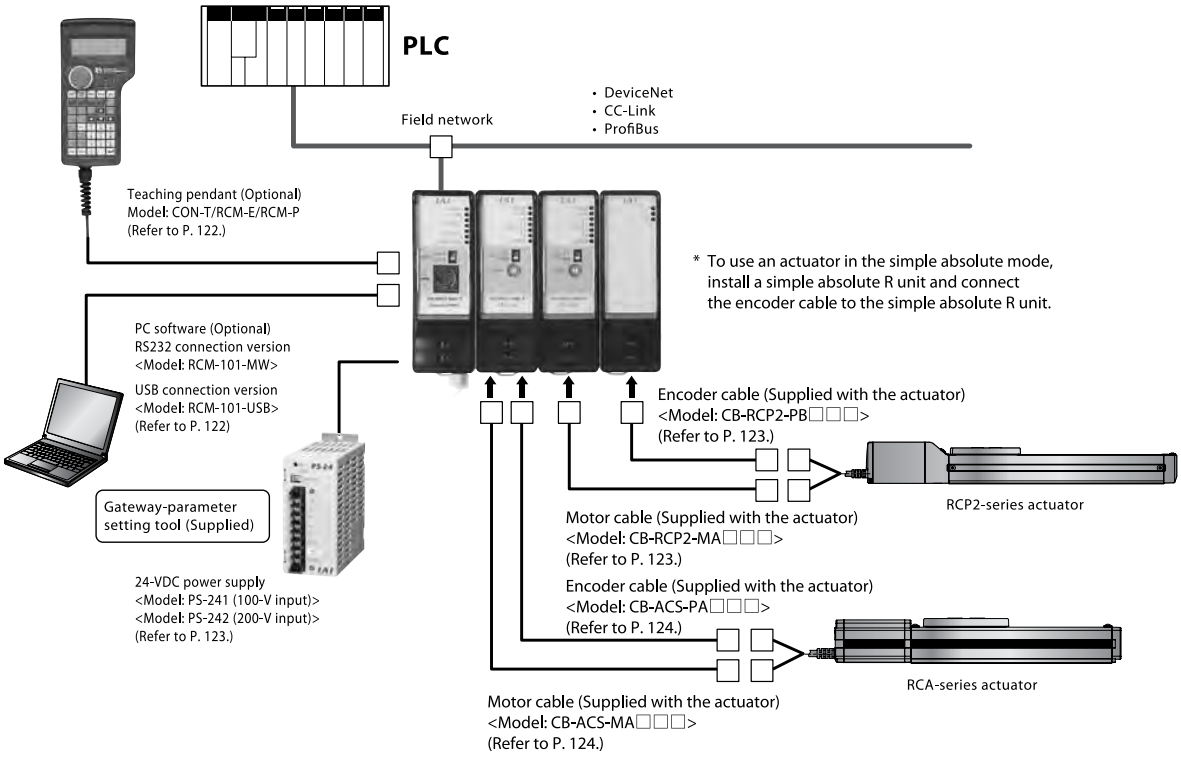
5 Simple Absolute Specification Not Requiring Home Return

The simple absolute R unit lets you operate incremental axes without returning the axes to their home first. If a simple absolute R unit is installed on an RACON unit (RCA controller) or RPCON unit (RCP2 controller), the actuator's encoder data will be backed up even after the power is cut off.

6 Installation to DIN Rail

Since the ROBONET adopts a DIN-rail installation feature, each controller can be affixed or removed with a single touch.

System Configuration



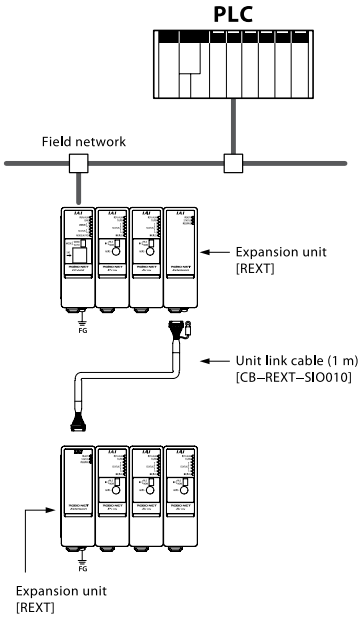
ROBONET Expansion unit

The ROBONET expansion unit (optional) lets you fold the unit link using a cable when many ROBONET units have been connected and the system has become too wide. You can also connect an SCON or other standalone controller to the network via the ROBONET.

[ROBONET expansion set A]
(Unit-folding set)
Model: REXT-SIO
(Items included in the set)

ROBONET expansion unit (model: REXT)	x 2
Unit link cable	x 1

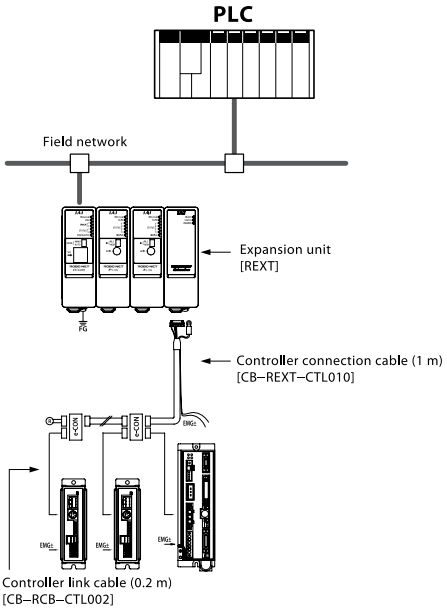
Model: CB-REXT-SIO010



[ROBONET expansion set B]
(Controller connection set)
Model: REXT-CTL
(Items included in the set)

ROBONET expansion unit (model: REXT)	x 1
Controller connection cable	x 1

Model: CB-REXT-CTL010



Component Units

You can order the necessary ROBONET components individually and combine them at your will.
If a need arises to add an actuator later, you can extend the system simply by adding an RACON/RPCON unit.

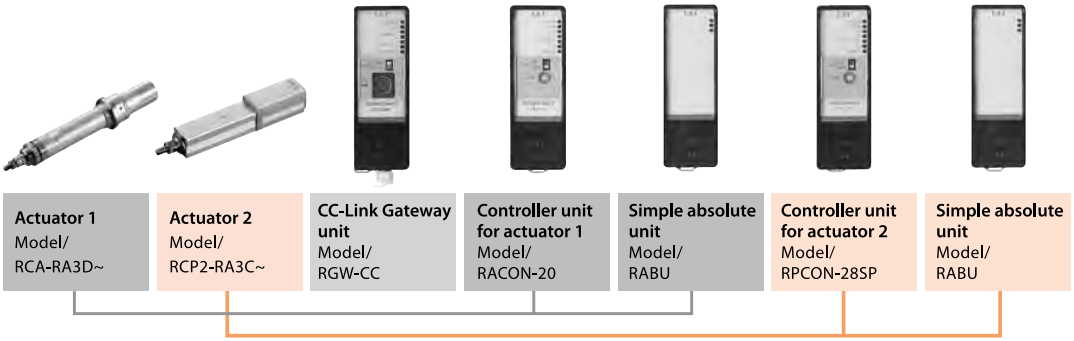
Gateway unit | RACON unit | RPCON unit | Simple absolute R unit | Expansion unit

Unit name	Description	Reference page
Gateway unit	A unit for making connection to a field network. One of four types (DeviceNet, CC-Link, ProfiBus and SIO) can be selected. * This unit is required in every ROBONET configuration.	P118 P119
RACON unit	A controller unit for operating an RCA actuator. (One RACON is required for one actuator axis.) Although the standard specification is incremental, you can also combine a simple absolute R unit to use the RACON unit as a simple absolute controller.	P120
RPCON unit	A controller unit for operating an RCP2 actuator. (One RPCON is required for one actuator axis.) Although the standard specification is incremental, you can also combine a simple absolute R unit to use the RPCON unit as a simple absolute controller.	P120
Simple absolute R unit	A backup battery unit for retaining the encoder data of the actuator after the power is cut off.	P121
Expansion unit	A unit for enabling operation via a network by folding the ROBONET link or connecting a standalone controller (SCON/PCON-CF) to the ROBONET.	P121

How to Order/Notes

You can individually order the necessary units comprising your ROBONET system. The delivered units are assembled by the customer. This feature lets you add units to the system or change existing units at will.

<Example of order> The following two axes are operated via CC-Link. The models specified below assume that the system is intended as an absolute system.



Actuator 1 Model/ RCA-RA3D~	Actuator 2 Model/ RCP2-RA3C~	CC-Link Gateway unit Model/ RGW-CC	Controller unit for actuator 1 Model/ RACON-20	Simple absolute unit Model/ RABU	Controller unit for actuator 2 Model/ RPCON-28SP	Simple absolute unit Model/ RABU

- **Operation Manual**
  The operation manual that comes with each ROBONET product is provided in a CD-ROM, not on paper (as a paper manual). If you with to have a paper operation manual, please specify so in your order. (Both the CD-ROM and paper manuals are free.)
  You can also download the operation manual from our website.

- **Gateway-parameter Setting Tool**
  To connect the ROBONET to a field network, you need the gateway-parameter setting tool to set up the network. This tool can be obtained free of charge through the following methods:
  (1) Download the tool from IAI's website.
  (2) Purchase each PC software, and the tool will come with the PC software (included in the CD).
  To use the gateway-parameter setting tool, you need a cable to connect the PC and controller (PC software cable (model: CB-RCA-SIO050+RCB-CV-MW)). If you don't have any PC software, purchase this cable separately.

- **PC Software, Teaching Pendant**
  To input position data, etc., to a ROBONET controller unit (RACON/RPCON), you need the PC software or teaching pendant.
  The ROBONET supports the PC software (model: RCM-101-MW/USB) of Version 6.04 or later. As for teaching pendants, the ROBONET supports the RCM-T of Version 2.06 or later and RCM-E/RCM-P of Version 2.08 or later.
  The ROBONET can be used with any version of the CON-T.
  If the version of your current PC software or teaching pendant is old, contact your IAI representative.

Explanation of Operation Modes

The ROBONET operates by receiving instructions from a PLC via a field network.
The ROBONET can be operated in any of the three modes specified below. Use a desired mode according to how your system should be operated and controlled.

	Name	Description
1	Positioner mode	In this mode, the actuator is operated by specifying position numbers. The position data, speed, acceleration/deceleration, etc., are input to the position table beforehand. Up to 768 positions can be registered.
2	Simple direct mode	In this mode, only the position data is specified directly by a value, and the remaining items such as speed, acceleration/deceleration, positioning band and current-limiting value during push-motion operation are specified by a position number. Up to 768 positions can be registered.
3	Direct numerical specification mode	In this mode, the actuator is operated by specifying the position data, speed, acceleration/deceleration, positioning band and current-limiting value during push-motion operation directly by values. Since positions are specified numerically, there is no limit to the number of positioning points that can be registered.

List of Functions by Operation Mode

	Positioner mode	Simple direct mode	Direct numerical specification mode
Number of registerable positions	768	768	—
Movement by position number specification	○	×	×
Direct specification of position data	×	○	○
Direct specification of speed and acceleration/deceleration	× (Specified in the position table.)	× (Specified in the position table.)	○
Direct specification of positioning band	× (Specified in the position table.)	× (Specified in the position table.)	○
Push-motion operation	○ (Specified in the position table.)	○ (Specified in the position table.)	○
Monitoring of completed position number	○	○	×
Monitoring of zone output	○	○	○
Monitoring of position zone output	○	○	×
Teaching function	○	×	×
Jogging operation	○	○	○
Inching operation	○	○	○
Monitoring of various status signals (*)	○	○	○
Monitoring of current position (*)	○	○	○
Monitoring of alarm codes (*)	○	○	○
Monitoring of speed/current (*)	×	×	○
Maximum specifiable value of position data	9999.99mm	9999.99mm	9999.99mm
Number of connectable axes	16	16	8

* The various status signals, current position, alarm codes and speed/current can be monitored by accessing each address of the Gateway R unit from the PLC.

Explanation of Component Units (Gateway R Unit)

Gateway R Unit of DeviceNet Specification

This communication unit is used to operate the ROBONET via DeviceNet.

Model **RGW-DV**

Specification

Item			Specification
Power supply			DC24V ±10%
Current consumption			Max. 600 mA
DeviceNet specifications	Communication protocol		Certified DeviceNet 2.0 interface module
			Group 2 only server
			Insulation node of network-power operation type
	Communication specification	Master-slave connection	Bit strobe
			Polling
			Cyclic
	Baud rate		500k/250k/125kbps (switchable using dedicated software)

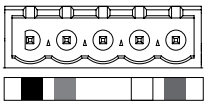
*1 If T-branching communication is to be used, refer to the operation manuals of the master unit and PLC installed in the master unit.

Item		Specification			
DeviceNet specifications	Communication cable length (*)	Baud rate	Maximum network length	Maximum branch length	Total branch length
		500kbps	100m	6m	39m
		250kbps	250m		78m
		125kbps	500m		156m
		Note) When a thick DeviceNet cable is used.			
	Number of occupied nodes	1 node			
Environment conditions	Surrounding air temperature	0~40°C			
	Surrounding humidity	95% RH or below (non-condensing)			
	Operating ambience	Free from corrosive gases, flammable gas, oil mist or powder dust.			
Protection degree		IP20			
Weight		140g			
Accessories		Terminal resistor board (model: TN-1) Network connector/emergency stop connector			

Network Connector

Gateway connector:
MSTBA2.5/5-G-5.08 ABGY AU
(by Phoenix Contact)

Cable-end connector
MSTB2.5/5-ST-5.08 ABGY AU
(by Phoenix Contact)
= Standard accessory



Pin color	Explanation
Black	Power-supply cable -
Blue	Communication data low
-	Shield
White	Communication data high
Red	Power-supply cable +

Applicable Wire for Cable-end Connector

Item	Description
Applicable wire size	Stranded wires: AWG24-12(0.2~2.5mm²)
Stripped length	7mm

Gateway R Unit of CC-Link Specification

This communication unit is used to operate the ROBONET via CC-Link.

Model **RGW-CC**

Specification

Item		Specification
Power supply		DC24V ±10%
Current consumption		Max. 600 mA
CC-Link specifications	Communication protocol	CC-Link Ver2.0 (*)
	Communication specification	10M/5M/2.5M/625k/156kbps (switchable using dedicated software)
	Communication method	Broadcast polling method
	Synchronization method	Frame synchronization method
	Encoding method	NRZI
	Transmission path format	Bus format (conforming to EIA RS485)
	Transmission format	Conforming to HDLC

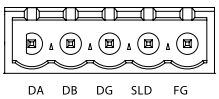
*1 Certified
*2 If T-branching communication is to be used, refer to the operation manuals of the master unit and PLC installed in the master unit.

Item		Specification					
CC-Link specifications	Error control method	CRC ($X^{16}+X^{12}+X^5+1$)					
	Number of occupied stations	Remote device station x1: 4 stations x4: 2 stations x8: 2 stations					
	Communication cable length (*2)	Baud rate (bps)	10M	5M	2.5M	625k	156k
		Total cable length (m)	100	160	400	900	1200
	Communication cable	Dedicated CC-Link cable					
Environment conditions	Surrounding air temperature	0~40°C					
	Surrounding humidity	95% RH or below (non-condensing)					
	Operating ambience	Free from corrosive gases, flammable gas, oil mist or powder dust.					
Protection degree		IP20					
Weight		140g					
Accessories		Terminal resistor board (model: TN-1) Network connector/emergency stop connector Terminal resistor cable (110Ω/130Ω)					

Network Connector

Gateway connector:
MSTBA2.5/5-G-5.08AU
(by Phoenix Contact)

Cable-end connector
MSTB2.5/5-ST-5.08 ABGY AU
(by Phoenix Contact)
= Standard accessory



Signal name	Explanation
DA	Communication line A
DB	Communication line B
CG	Ground
SLD	Connect the shield or cable shield. The SLD signal is connected to "FG" and the enclosure.
FG	Frame ground. The FG signal is connected to "SLD" and the enclosure.

Applicable Wire for Cable-end Connector

Item	Description
Applicable wire size	Stranded wires: AWG24-12(0.2~2.5mm²)
Stripped length	7mm

Gateway R Unit of ProfiBus Specification

This communication unit is used to operate the ROBONET via ProfiBus.

Model RGW-PR

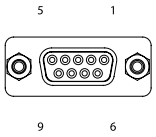
Specification

Item		Specification	
Power supply		DC24V ±10%	
Current consumption		Max. 600 mA	
ProfiBus specifications	Communication protocol	DP slave	
	Baud rate	9.6kbps~12Mbps	
	Communication cable length	9.6kbps	1500m
		500kbps	400m
		1.5Mbps	200m
		3Mbps	200m
		12Mbps	100m

Item		Specification
Environment conditions	Surrounding air temperature	0~40°C
	Surrounding humidity	95% RH or below (non-condensing)
	Operating ambience	Free from corrosive gases, flammable gas, oil mist or powder dust.
Protection degree		IP20
Weight		140g
Accessories		Terminal resistor board (model: TN-1) Network connector/emergency stop connector

Network Connector

Gateway connector:
D-sub, 9-pin connector,
socket end



Pin No.	Signal name	Explanation	Pin No.	Signal name	Explanation
3	B-Line	Communication line B (RS485)	6	+5V	+5-V output (insulated)
4	RTS	Request to send	8	A-Line	Communication line A (RS485)
5	GND	Signal ground (insulated)	Housing	Shield	Cable shield. Connected to the enclosure.

* The mating connector (D-sub, 9-pin connector) is not supplied.
* Pins 1, 2, 7 and 9 are not connected.

Gateway R Unit of SIO Specification

This communication unit is used to operate the ROBONET in serial communication from an XSEL controller (*1) or Modbus communication unit.

Model RGW-SIO

Specification

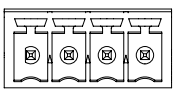
Item		Specification
SIO specifications	Power supply	DC24V ±10%
	Current consumption	Max. 600 mA
	Communication format	Conforming to RS485 (Modbus protocol), 1:1 communication connection
	Communication method	Asynchronous, half-duplex
	Baud rate	Max. 230.4 kbps
	Cable length	100 m or less
	Recommended cable	Twisted paired cable (shielded) x 2

Item		Specification
Environment conditions	Surrounding air temperature	0~40°C
	Surrounding humidity	95% RH or below (non-condensing)
	Operating ambience	Free from corrosive gases, flammable gas, oil mist or powder dust.
	Protection degree	IP20
Weight		140g
Accessories		Terminal resistor board (model: TN-1) Network connector/emergency stop connector

Network Connector

Gateway connector:
MC1.5/4-G-3.5
(by Phoenix Contact)

Cable-end connector
MC1.5/4-ST-3.5
(by Phoenix Contact)
= Standard accessory



Signal name	Explanation	
SA	Communication line A (+)	Conforming to RS485 With a built-in terminal resistor (220Ω)
SB	Communication line A (-)	
SG	Signal ground	
FG	Frame ground. Connected to the enclosure.	

Applicable Wire for Cable-end Connector

Item	Description
Applicable wire size	Stranded wires: AWG28-16 (0.14~1.5mm²)
Stripped length	7mm

RACON Unit: RCA-series Controller

This controller unit is used to operate an RCA actuator in a ROBONET system.

Model **RACON-[1]-[2]**

* Specify the motor wattage in [1] in the model name. (Refer to the table below.)
In [2], specify "ABU" only if you are using the simple absolute unit. (If the simple absolute unit is not used, leave this space blank.)

Model	Applicable actuators
RACON-20-[2]	RCA-SA4☐ / SS4☐ / SA5☐ / SS5☐ / RA4☐-20 / RG☐4☐-20/ A4R / A5R RCACR-SA4C / SA5☐ RCAW-RA4☐-20
RACON-20S-[2]	RCA-RA3☐ / RG☐3 RCAW-RA3☐
RACON-30-[2]	RCA-SA6☐ / SS6☐ / RA4☐-30 / RG☐4☐-30 / A6R RCACR-SA6☐ RCAW-RA4☐-30

Specification

Item		Specification	Item		Specification
General specifications	Power supply	DC24V ±10%	Environment conditions	Surrounding air temperature	0~50°C
	Power-supply capacity	Max. 5.1 A (The specific capacity varies depending on the actuator.)		Surrounding humidity	95% RH or below (non-condensing)
	Operated actuator	RCA series		Operating ambience	Free from corrosive gases, flammable gas, oil mist or powder dust.
	Number of positioning points	768		Protection degree	IP20
	Backup memory	EEPROM	Weight		200g
	Position detection method	Incremental encoder	Accessories		ROBONET communication connection board (model: JB-1), power-supply connection plate (model: PP-1)
	Forced release of electromagnetic brake	Brake release switch			
	Motor cable	Model CB-ACS-MA☐☐☐			
	Encoder cable	Model CB-ACS-PA☐☐☐			

RPCON Unit: RCP2-series Controller

This controller unit is used to operate an RCP2 actuator in a ROBONET system.

Model **RACON-[1]-[2]**

* Specify the motor type in [1] in the model name. (Refer to the table below.)
In [2], specify "ABU" only if you are using the simple absolute unit. (If the simple absolute unit is not used, leave this space blank.)
* The simple absolute unit cannot be used with the RCP2-RA2C, GRS, RTB and RTC.

Model	Applicable actuators
RPCON-20P	RCP2-RA2C / GRS
RPCON-28P-[2]	RCP2-GRM / GR3LS / GR3SS / RTB / RTC
RPCON-28SP-[2]	RCP2-RA3C / RGD3C
RPCON-42P-[2]	RCP2-SA5☐ / SA6☐ / SS7☐ / BA6☐ / BA7☐ / RA4C / RG☐4C /GR3LM / GR3SM RCP2CR-SA5C / SA6C / SS7C RCP2W-RA4C
RPCON-56P-[2]	RCP2-SA7☐ / SS8☐ / RA6C / RG☐6C / RCP2CR-SA7C / SS8C RCP2W-RA6C

* RCP2 actuators of old types are also supported. (Contact IAI for details.)

Specification

Item		Specification	Item		Specification
General specifications	Power supply	DC24V ±10%	Environment conditions	Surrounding air temperature	0~50°C
	Power-supply capacity	Max. 2 A		Surrounding humidity	95% RH or below (non-condensing)
	Operated actuator	RCP2 series		Operating ambience	Free from corrosive gases, flammable gas, oil mist or powder dust.
	Number of positioning points	768		Protection degree	IP20
	Backup memory	EEPROM	Weight		200g
	Position detection method	Incremental encoder	Accessories		ROBONET communication connection board (model: JB-1), power-supply connection plate (model: PP-1)
	Forced release of electromagnetic brake	Brake release switch			
	Motor cable	Model CB-RCP2-MA☐☐☐			
	Encoder cable	Model CB-RCP2-PB☐☐☐			

Explanation of Component Units (Simple Absolute R Unit/Expansion Unit)

Simple absolute R unit

When this data-backup battery unit is connected to an RACON or RPCON (*1), an incremental actuator can be used as an absolute actuator.

*1 One simple absolute R unit is required for one RACON or RPCON unit.

Model **RABU** (RACON/RPCON)

* To order a simple absolute R unit together with a controller unit (RACON/RPCON), specify "-ABU" at the end of the model code of the controller to which the simple absolute R unit will be installed.

Specification

Item		Specification				Item		Specification
General specifications	Power supply	DC24V ±10%				Environment conditions	Surrounding air temperature	0~40°C
	Current consumption	Max. 300 mA					Surrounding humidity	95% RH or below (non-condensing)
	Applicable battery	Ni-MH battery, nickel hydrogen battery					Operating ambience	Free from corrosive gases, flammable gas, oil mist or powder dust.
	Charge time	Approx. 78 hours					Protection degree	IP20
	Battery life	3 years				Weight		330g
	Maximum rotation speed at which absolute data can be backed up (rpm)	800	400	200	100	Accessories		ROBONET communication connection board (model: JB-1), Simple absolute connection board (model: JB-1), power-supply connection plate (model: PP-1)
	Absolute-data backup time (h)	120	240	360	480			

Example of order

In certain situations, such as when many controllers have been linked to the ROBONET and the system has become too wide to fit the control panel, this unit can be used to fold the controller link by connecting a cable in the middle of the link.
You can also install the expansion unit at the end of the ROBONET link and use an external controller cable to operate an SCON or other standalone controller on the network just like the controller units linked to the ROBONET.

Model **REXT** (RPCON/RACON)

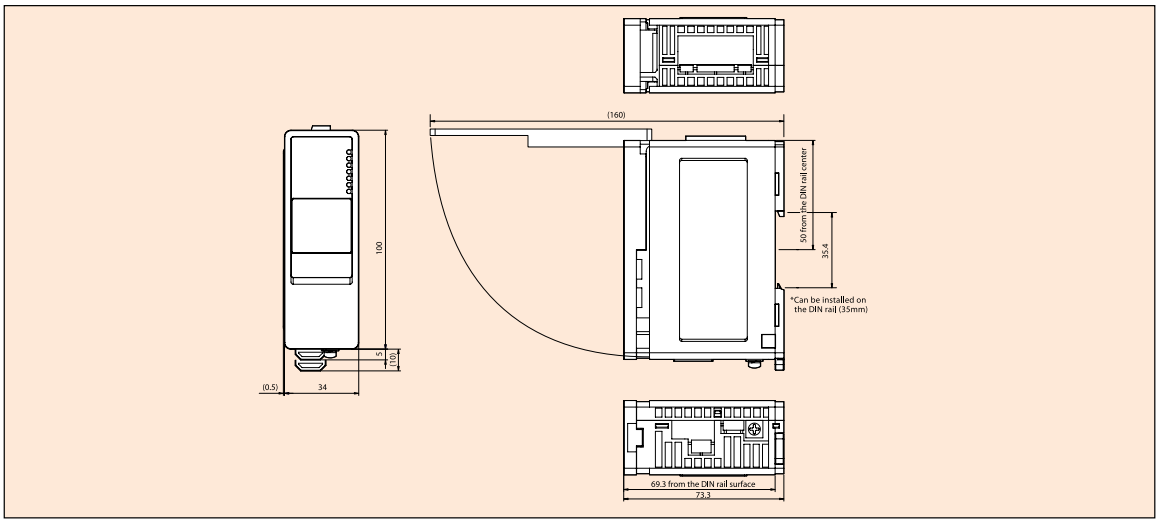
Specification

Item		Specification
General specifications	Power supply	DC24V ±10%
	Current consumption	Max. 100 mA
Environment conditions	Surrounding air temperature	0~40°C
	Surrounding humidity	95% RH or below (non-condensing)
	Operating ambience	Free from corrosive gases, flammable gas, oil mist or powder dust.
	Protection degree	IP20
Weight		140g
Accessories		ROBONET communication connection board (model: JB-1), power-supply connection plate (model: PP-1)

(Note) The cable used when the ROBONET link is folded is different from the one used to connect a standalone controller. For details, refer to the system configuration (ROBONET expansion unit) on P. 117.

External Dimensions

The Gateway R unit, RACON unit, RPCON unit and simple absolute R unit all have the same external dimensions.



Options

ROBONET communication connection board (simple absolute connection board)
Model JB-1

Terminal resistor board
Model TN-1

Power-supply connection plate
Model PP-1

Options

24-VDC Power Supply

Features

This 24-V power supply for ROBO Cylinder has the rated maximum instantaneous output of 17 A. Since multiple PS units can be operated in parallel, you can add up to five PS units to your system if one PS does not provide enough capacity.

Model

PS-241
(100-V input specification)
PS-242
(200-V input specification)

Relationship of actuator and power-supply current

Controller type	Actuator type	Power-supply current [A]		Number of connectable units per PS-24	
				Servos of all axes are turned ON simultaneously *	Servos of all axes are not turned ON simultaneously *
RPCON PCON PSEL	All RCP2 models (Note)	Rating (= Max.)	2	8	8
RACON ACON ASEL	SA4, SA5 (20W)	Rating	1.3	3	6
		Max.	4.4		
	SA6 (30W)	Rating	1.3	4	6
		Max.	4		
	RA3 (20W)	Rating	1.7	3	5
		Max.	5.1		
	RA4 (20W)	Rating	1.3	3	6
		Max.	4.4		
	RA4 (30W)	Rating	1.3	4	6
		Max.	4		

* The first servo ON action after the power is turned on.
(Note) The HS8C, HS8R and RAIOC are excluded.

Replacement Parts

If you must order a replacement cable, etc., after the initial purchase of your product, specify the correct model by referring to the information below.

ROBONET communication connection board (simple absolute connection board)
Model JB-1

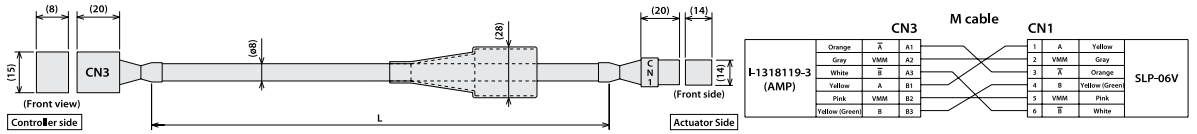
Terminal resistor board
Model TN-1

Power-supply connection plate
Model PP-1

Motor Cable for RCP2

Item CB-RCP2-MA□□□

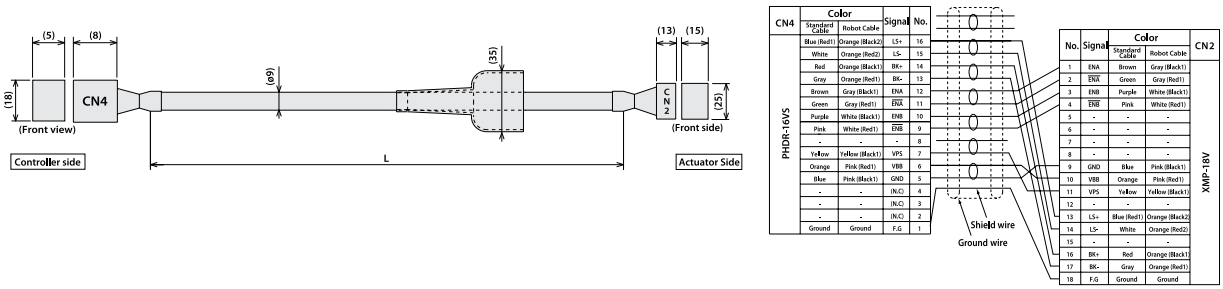
* The standard motor cable is a robot cable. You can select whether or not to use a robot cable.
* □□□ indicates the cable length (L). A desired length up to 20 m can be specified.
Example) 080 = 8 m



Encoder Cable/Robot Encoder Cable for RCP2

Item CB-RCP2-PB□□□/CB-RCP2-PB□□□-RB

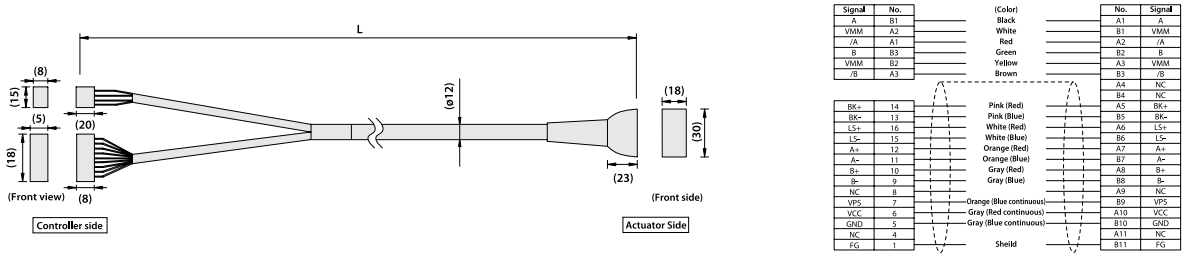
* The standard encoder cable is a normal cable. A robot cable can be specified as an option.
* □□□ indicates the cable length (L). A desired length up to 20 m can be specified.
Example) 080 = 8 m



Integrated Motor/Encoder Cable for RCP3

Item CB-PCS-MPA□□□

* □□□ indicates the cable length (L). A desired length up to 10 m can be specified.
Example) 080 = 8 m

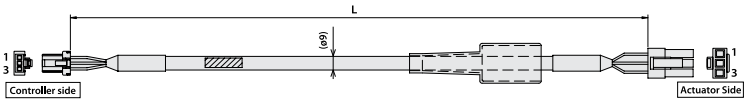


Replacement Parts

Motor Cable for RCA

Item CB-ACS-MA□□□

* □□□ indicates the cable length (L). A desired length up to 20 m can be specified.
Example) 080 = 8 m



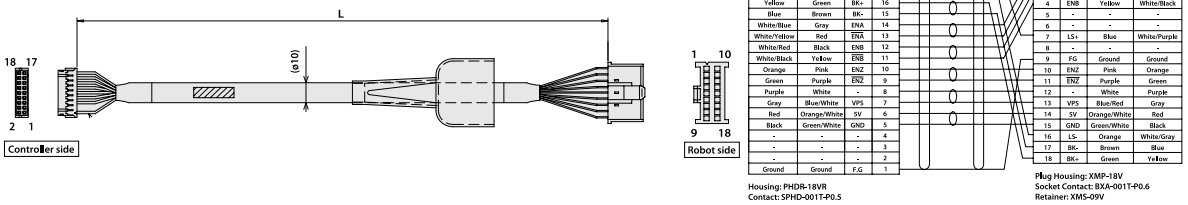
Wire	Color	Signal	No.
AWG22 (Press fit)	Red	U	1
	White	V	2
	Black	W	3

No.	Signal	Color	Wire
1	U	Red	AWG22 (Press fit)
2	V	White	
3	W	Black	

Encoder Cable/Robot Encoder Cable for RCA

Item CB-ACS-PA□□□/CB-ACS-PA□□□-RB

* The standard encoder cable is a normal cable. A robot cable can be specified as an option.
* □□□ indicates the cable length (L). A desired length up to 20 m can be specified.
Example) 080 = 8 m



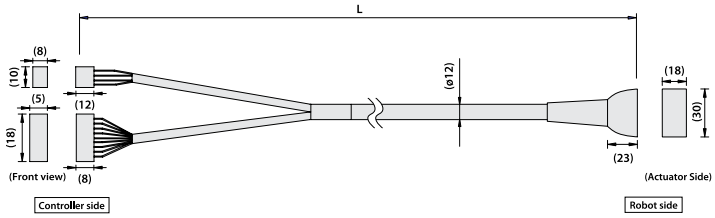
Color		Signal	No.
Robot Cable	Standard Cable		
White/Purple	Blue	LS+	18
White/Gray	Orange	LS-	17
Yellow	Green	BK+	16
Blue	Brown	BK-	15
White/Blue	Gray	ENA	14
White/Yellow	Red	/ENA	13
White/Red	Black	ENB	12
White/Black	Yellow	/ENB	11
Orange	Pink	ENZ	10
Green	Purple	/ENZ	9
Purple	White	-	8
Gray	Blue/White	VPS	7
Red	Orange/White	5V	6
Black	Green/White	GND	5
-	-	-	4
-	-	-	3
-	-	-	2
Ground	Ground	F.G	1

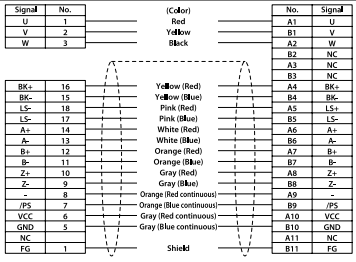
No.	Signal	Color	
		Standard Cable	Robot Cable
1	ENA	Gray	White/Blue
2	/ENA	Red	White/Yellow
3	ENB	Black	White/Red
4	/ENB	Yellow	White/Black
5	-	-	-
6	-	-	-
7	LS+	Blue	White/Purple
8	-	-	-
9	FG	Ground	Ground
10	ENZ	Pink	Orange
11	/ENZ	Purple	Green
12	-	White	Purple
13	VPS	Blue/Red	Gray
14	5V	Orange/White	Red
15	GND	Green/White	Black
16	LS-	Orange	White/Gray
17	BK-	Brown	Blue
18	BK+	Green	Yellow

Integrated Motor/Encoder Cable for RCA2

Item CB-ACS-MPA□□□

* □□□ indicates the cable length (L). A desired length up to 20 m can be specified.
Example) 080 = 8 m





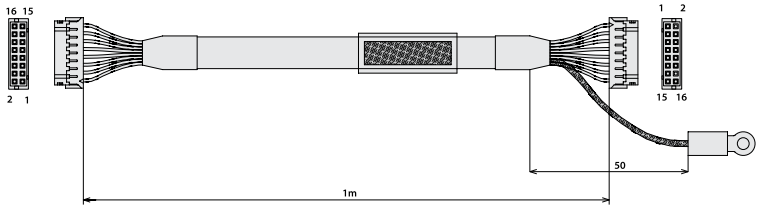
Signal	No.
U	1
V	2
W	3

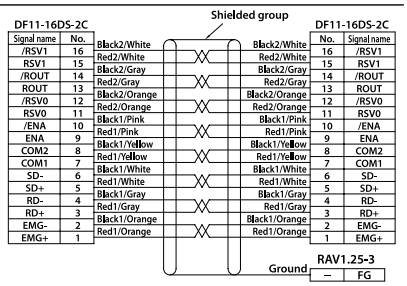
Signal	No.
BK+	16
BK-	15
LS-	18
LS-	17
A+	14
A-	13
B+	12
B-	11
Z+	10
Z-	9
-	8
/PS	7
VCC	6
GND	5
NC	4
FG	1

No.	Signal
A1	U
B1	V
A2	W
B2	NC
A3	NC
B3	NC
A4	BK+
B4	BK-
A5	LS+
B5	LS-
A6	A+
B6	A-
A7	B+
B7	B-
A8	Z+
B8	Z-
A9	-
B9	/PS
A10	VCC
B10	GND
A11	NC
B11	FG

Unit Link Cable for Expansion Unit

Item CB-REXT-SIO010



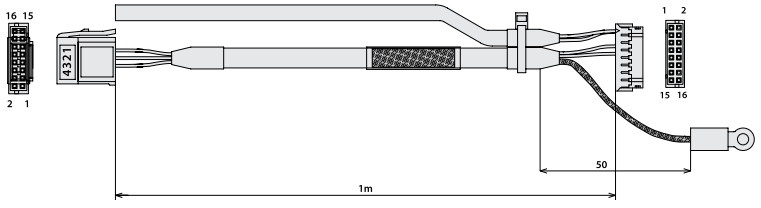


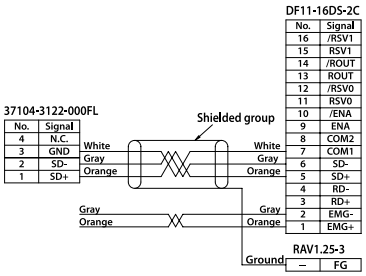
DF11-16DS-2C				DF11-16DS-2C	
Signal name	No.			No.	Signal name
/RSV1	16	Black2/White	Black2/White	16	/RSV1
RSV1	15	Red2/White	Red2/White	15	RSV1
/ROUT	14	Black2/Gray	Black2/Gray	14	/ROUT
ROUT	13	Red2/Gray	Red2/Gray	13	ROUT
/RSV0	12	Black2/Orange	Black2/Orange	12	/RSV0
RSV0	11	Red2/Orange	Red2/Orange	11	RSV0
/ENA	10	Black1/Pink	Black1/Pink	10	/ENA
ENA	9	Red1/Pink	Red1/Pink	9	ENA
COM2	8	Black1/Yellow	Black1/Yellow	8	COM2
COM1	7	Red1/Yellow	Red1/Yellow	7	COM1
SD-	6	Black1/White	Black1/White	6	SD-
SD+	5	Red1/White	Red1/White	5	SD+
RD-	4	Black1/Gray	Black1/Gray	4	RD-
RD+	3	Red1/Gray	Red1/Gray	3	RD+
EMG-	2	Black1/Orange	Black1/Orange	2	EMG-
EMG+	1	Red1/Orange	Red1/Orange	1	EMG+
			Ground	–	FG

Legend of wire color: Dot color and number of dot(s)/insulator color

Controller Connection Cable for Expansion Unit

Item CB-REXT-CTL010





37104-3122-000FL				DF11-16DS-2C	
No.	Signal			No.	Signal
4	N.C.			16	/RSV1
3	GND	White	White	15	RSV1
2	SD-	Gray	Gray	14	/ROUT
1	SD+	Orange	Orange	13	ROUT
				12	/RSV0
				11	RSV0
				10	/ENA
				9	ENA
				8	COM2
				7	COM1
				6	SD-
				5	SD+
				4	RD-
				3	RD+
		Gray	Gray	2	EMG-
		Orange	Orange	1	EMG+
			Ground	–	FG

X-SEL

RCS2-series
program controller

Model List/Pricing

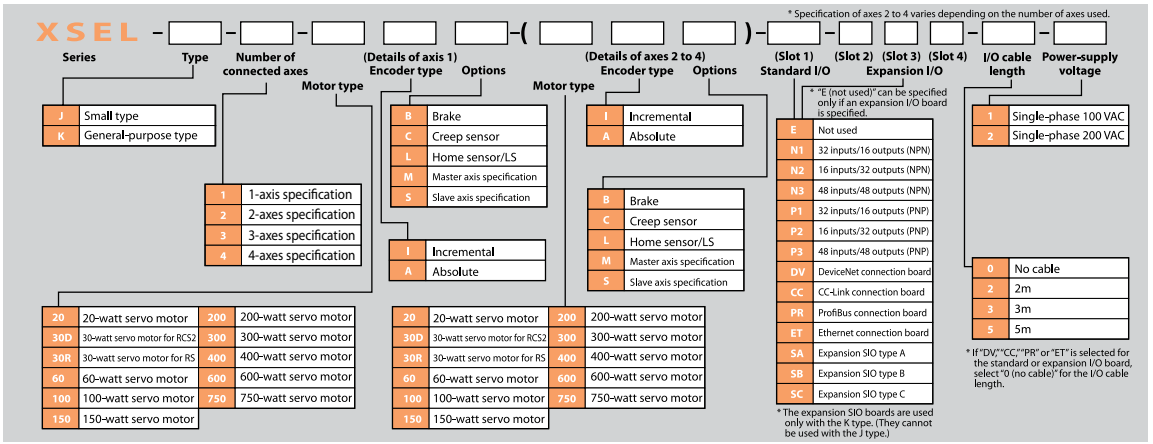
A multi-axis program controller capable of operating RCS2-series actuators. Up to six axes can be controlled simultaneously.

Type	J	K	P	Q
Name	Small type	General-purpose type	Large-capacity type	Large-capacity type (conforming to safety category)
Exterior view				
Description	A small, low-cost type ideal for operating low-output actuators	A standard type offering great expandability	A large-capacity type capable of operating up to six axes or 2400 W	A large-capacity type that can be configured to meet safety category 4
Maximum number of controlled axes	4		6	
Number of positions	3000		4000	
Total wattage of connectable axes	800W	1600W	2400W	
Power supply	Single-phase 100 VAC, Single-phase 200 VAC		Single-phase 200 VAC, Three-phase 200 VAC	
Safety category	B		B	Can be configured to meet category 4.
Safety standard	–	–	CE	CE, ANSI
Standard price	Contact IAI.			

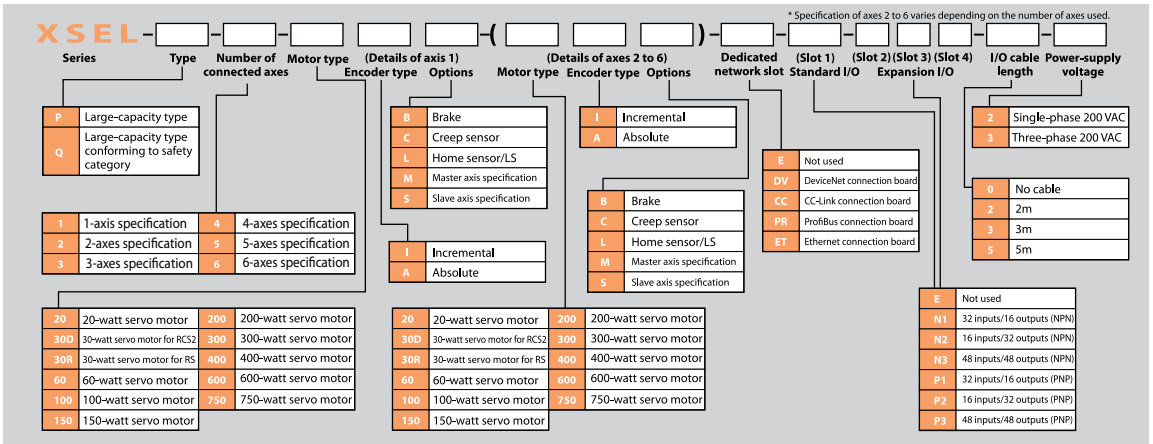
Model

[XSEL-J/K Types]

* If you are selecting multiple options, specify them in an alphabetical order. (Example: Brake + Home sensor ⇨ BL)

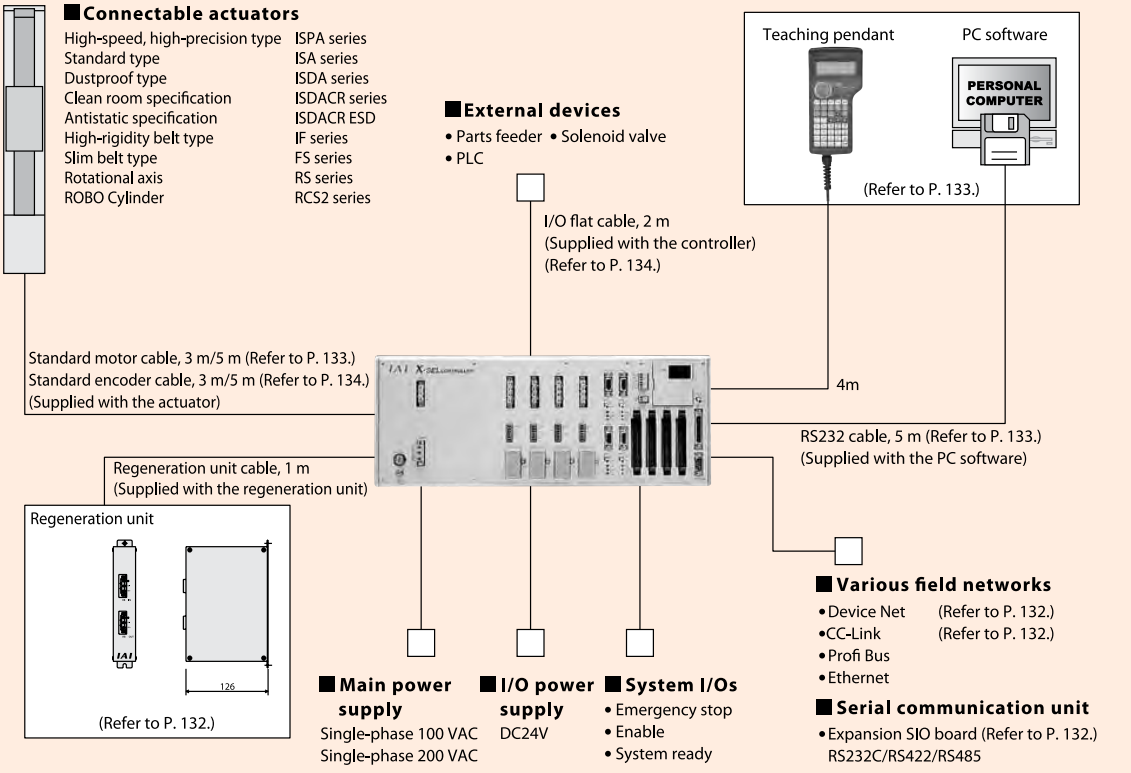


[XSEL-P/QTypes]

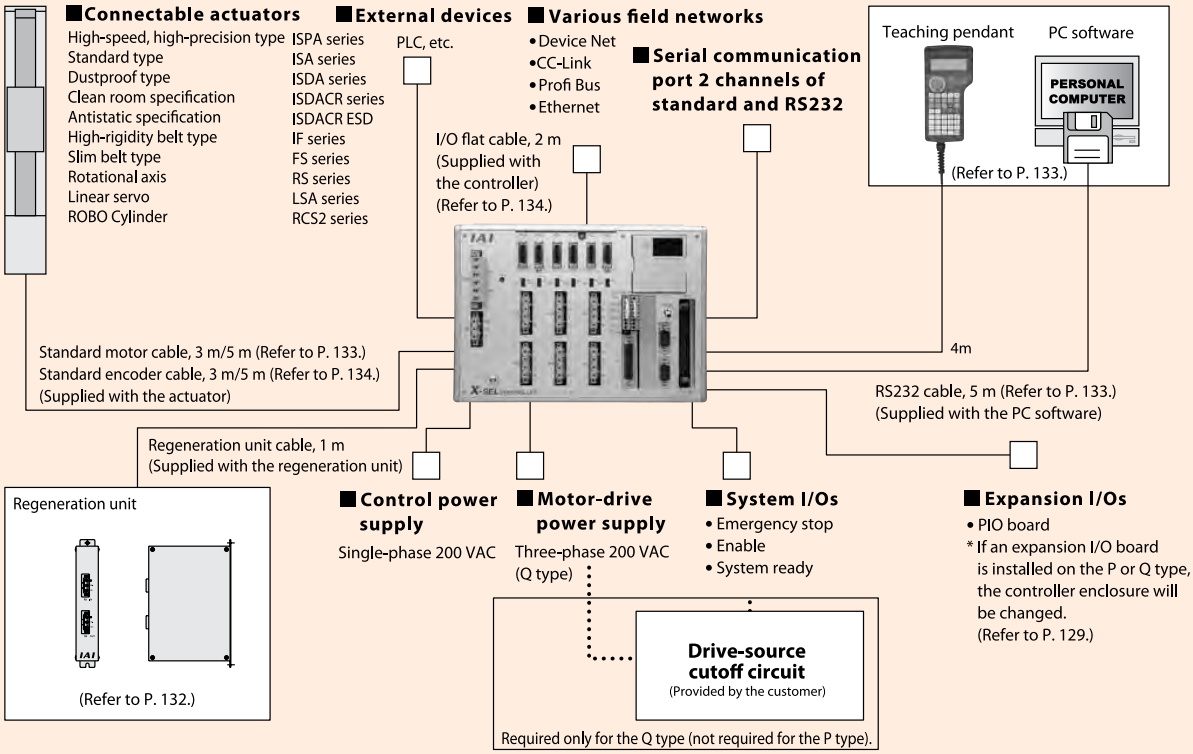


Regenerative resistor unit

J (Small Type)/K (General-purpose Type)/KE (CE Type)



P (Large-capacity Type)/Q (Large-capacity Global Type)

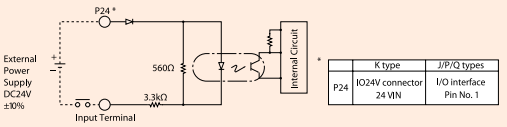


I/O Wiring

Input External input specifications (NPN specification)

Item	Specification
Input voltage	DC24V ±10%
Input current	7 mA per circuit
ON/OFF voltages	ON voltage --- Min. 16.0 VDC / OFF voltage --- Max. 5.0 VDC
Insulation method	Photo-coupler insulation
Externally connected devices	[1] No-voltage contacts (minimum load of approx. 5 VDC/1 mA) [2] Photoelectric/proximity sensors (NPN type) [3] Sequencer transistor outputs (open-collector type) [4] Sequencer contact outputs (minimum load of approx. 5 VDC/1 mA)

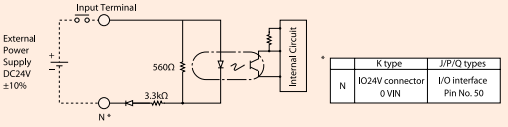
[Input circuit]



Input External input specifications (PNP specification)

Item	Specification
Input voltage	DC24V ±10%
Input current	7 mA per circuit
ON/OFF voltages	ON voltage --- Min. 8.0 VDC / OFF voltage --- Max. 19.0 VDC
Insulation method	Photo-coupler insulation
Externally connected devices	[1] No-voltage contacts (minimum load of approx. 5 VDC/1 mA) [2] Photoelectric/proximity sensors (PNP type) [3] Sequencer transistor outputs (open-collector type) [4] Sequencer contact outputs (minimum load of approx. 5 VDC/1 mA)

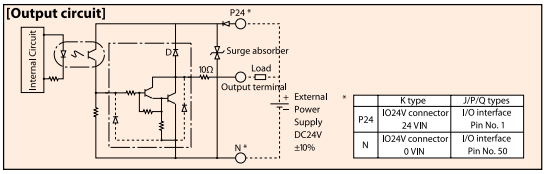
[Input circuit]



Output External output specifications (NPN specification)

Item	Specification	
Load voltage	DC24V	TD62084 (or equivalent) is used.
Maximum load current	100 mA per point, 400 mA peak (total current)	
Leak current (max.)	Max. 0.1 mA per point	
Insulation method	Photo-coupler insulation	
Externally connected devices	[1] Miniature relays [2] Sequence input units	

[Output circuit]

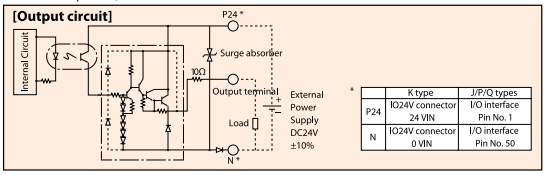


Output External output specifications (NPN specification)

Item	Specification	
Load voltage	DC24V	TD62784 (or equivalent) is used.
Maximum load current	100 mA per point 400 mA per 8 ports Note)	
Leak current (max.)	Max. 0.1 mA per point	
Insulation method	Photo-coupler insulation	
Externally connected devices	[1] Miniature relays [2] Sequence input units	

Note) The maximum total load current for every eight ports from output port No. 300 is 400 mA. (The maximum total load current of output port Nos. 300+n to 300+n+7 is 400 mA, where n is 0 or a multiple of 8.)

[Output circuit]



I/O Signal Tables

Standard I/O Signal Table (When N1 or P1 is selected)

Pin No.	Category	Port No.	Standard setting
1		—	(J/P/Q types: 24-V connection / K type: NC)
2		000	Program start
3		001	General-purpose input
4		002	General-purpose input
5		003	General-purpose input
6		004	General-purpose input
7		005	General-purpose input
8		006	General-purpose input
9		007	Program specification (PRG No. 1)
10		008	Program specification (PRG No. 2)
11		009	Program specification (PRG No. 4)
12		010	Program specification (PRG No. 8)
13		011	Program specification (PRG No. 10)
14		012	Program specification (PRG No. 20)
15		013	Program specification (PRG No. 40)
16		014	General-purpose input
17	Input	015	General-purpose input
18		016	General-purpose input
19		017	General-purpose input
20		018	General-purpose input
21		019	General-purpose input
22		020	General-purpose input
23		021	General-purpose input
24		022	General-purpose input
25		023	General-purpose input
26		024	General-purpose input
27		025	General-purpose input
28		026	General-purpose input
29		027	General-purpose input
30		028	General-purpose input
31		029	General-purpose input
32		030	General-purpose input
33		031	General-purpose input
34		300	Alarm output
35		301	Ready output
36		302	Emergency stop output
37		303	General-purpose output
38		304	General-purpose output
39		305	General-purpose output
40		306	General-purpose output
41		307	General-purpose output
42	Output	308	General-purpose output
43		309	General-purpose output
44		310	General-purpose output
45		311	General-purpose output
46		312	General-purpose output
47		313	General-purpose output
48		314	General-purpose output
49		315	General-purpose output
50		—	(J/P/Q types: 0-V connection / K type: NC)

Expansion I/O Signal Table (When N1 or P1 is selected)

Pin No.	Category	Standard setting
1		(J/P/Q types: 24-V connection / K type: NC)
2		General-purpose input
3		General-purpose input
4		General-purpose input
5		General-purpose input
6		General-purpose input
7		General-purpose input
8		General-purpose input
9		General-purpose input
10		General-purpose input
11		General-purpose input
12		General-purpose input
13		General-purpose input
14		General-purpose input
15		General-purpose input
16		General-purpose input
17	Input	General-purpose input
18		General-purpose input
19		General-purpose input
20		General-purpose input
21		General-purpose input
22		General-purpose input
23		General-purpose input
24		General-purpose input
25		General-purpose input
26		General-purpose input
27		General-purpose input
28		General-purpose input
29		General-purpose input
30		General-purpose input
31		General-purpose input
32		General-purpose input
33		General-purpose input
34		General-purpose output
35		General-purpose output
36		General-purpose output
37		General-purpose output
38		General-purpose output
39		General-purpose output
40		General-purpose output
41		General-purpose output
42	Output	General-purpose output
43		General-purpose output
44		General-purpose output
45		General-purpose output
46		General-purpose output
47		General-purpose output
48		General-purpose output
49		General-purpose output
50		(J/P/Q types: 0-V connection / K type: NC)

Expansion I/O Signal Table (When N2 or P2 is selected)

Pin No.	Category	Standard setting
1		(J/P/Q types: 24-V connection / K type: NC)
2		General-purpose input
3		General-purpose input
4		General-purpose input
5		General-purpose input
6		General-purpose input
7		General-purpose input
8		General-purpose input
9	Input	General-purpose input
10		General-purpose input
11		General-purpose input
12		General-purpose input
13		General-purpose input
14		General-purpose input
15		General-purpose input
16		General-purpose input
17		General-purpose input
18		General-purpose output
19		General-purpose output
20		General-purpose output
21		General-purpose output
22		General-purpose output
23		General-purpose output
24		General-purpose output
25		General-purpose output
26		General-purpose output
27		General-purpose output
28		General-purpose output
29		General-purpose output
30		General-purpose output
31		General-purpose output
32		General-purpose output
33		General-purpose output
34	Output	General-purpose output
35		General-purpose output
36		General-purpose output
37		General-purpose output
38		General-purpose output
39		General-purpose output
40		General-purpose output
41		General-purpose output
42		General-purpose output
43		General-purpose output
44		General-purpose output
45		General-purpose output
46		General-purpose output
47		General-purpose output
48		General-purpose output
49		General-purpose output
50		(J/P/Q types: 0-V connection / K type: NC)

Specification Table

■ J (Small Type)/K (General-purpose Type)

Item	Description							
Controller series/type	J (small type)				K (general-purpose type)/KE (CE type)			
Connected actuators	RCS2/ISA/ISPA/ISP/ISDA/ISDACR/ISPDACR/IF/FS/RS							
Applicable motor output (W)	20/30/60/100/150/200/300/400/600/750							
Number of connected axes	1	2	3	4	1	2	3	4
Maximum output of connected axes (W)	Max 800 (at power-supply voltage of 200 V) Max 400 (at power-supply voltage of 100 V)				Max 800	Max 1600 (at power-supply voltage of 200 V) Max 800 (at power-supply voltage of 200 V)		
Input power supply	100-V specification: Single-phase 100 to 115 VAC 200-V specification: Single-phase 200 to 230 VAC							
Operating power-supply voltage range	±10%							
Power-supply frequency	50Hz/60Hz							
Power-supply capacity	Max 1670VA		Max 1720VA	Max 1810VA	Max 1670VA	Max 3120VA	Max 3220VA	Max 3310VA
Position detection method	Incremental encoder (wire-saving type) Multi-rotation data backup absolute encoder (wire-saving type)							
Speed setting	1 mm/sec ~ (The maximum limit varies depending on the actuator.)							
Acceleration setting	0.01 G ~ (The maximum limit varies depending on the actuator.)							
Program language	Super SEL							
Number of programs	64							
Number of program steps	6,000 (total)							
Number of multi-tasking programs	16							
Number of positions	3,000							
Data storage device	Flash ROM + SRAM backup battery							
Data input method	Teaching pendant or PC software							
Standard I/Os	32 points (total of dedicated inputs + general-purpose inputs)/16 points (total of dedicated outputs + general-purpose outputs)							
Expansion I/Os	None		1 unit, 48 points (1 unit can be added)		1 unit, 48 points (Up to 3 units can be added)			
Serial communication function	Standard RS232 port (D-sub, 25-pin)				Standard RS232 port + Expansion SIO board (optional)			
Other I/Os	System I/Os (emergency stop input, enable input, system ready output)							
Protective functions	Motor overcurrent, overload, motor/driver temperature check, overload check, encoder open detection, soft limit overtravel, system error, battery error, etc.							
Surrounding air temperature/humidity	Temperature 0 to 40°C, humidity 30 to 85%							
Surrounding ambience	Free from corrosive gases or significant dust.							
Weight	2.6kg	3.3kg	5.0kg		6.0kg	7.0kg		
Accessory	I/O flat cable							

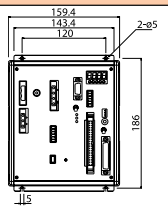
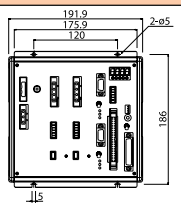
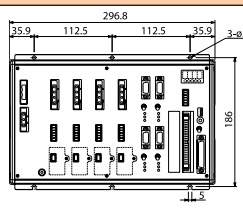
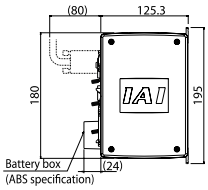
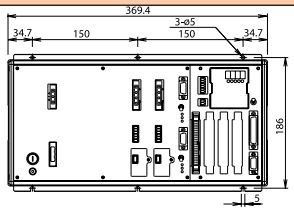
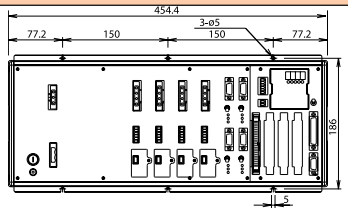
■ P (Large-capacity Type)/Q (Large-capacity Type Conforming to Safety Category)

Item	Description											
Controller series/type	P (standard) type						Q (global) type					
Connected actuators	RCS2/ISA/ISPA/ISP/ISDA/ISDACR/ISPDACR/IF/FS/RS/LSA											
Applicable motor output	20/30/60/100/150/200/300/400/600/750											
Number of controlled axes	1	2	3	4	5	6	1	2	3	4	5	6
Maximum output of connected axes (W)	Max2400W (1600 W for single-phase 200-VAC specification)											
Control power input	AC 200/230, single-phase -15%, +10%						AC 200/230, single-phase -15%, +10%					
Motor power input	AC 200/230, single-phase/three-phase -10%, +10%						AC 200/230, single-phase/three-phase -10%, +10%					
Power-supply frequency	50/60Hz											
Insulation resistance	10MΩ or more (at 500 VDC, between the power-supply terminal and each I/O terminal and between all external terminals and the case)											
Withstand voltage	1500 VAC (1 minute)						1500 VAC (1 minute)					
Power-supply capacity (*1)	Max 1744VA	Max 3266VA	Max 4787VA	Max 4878VA	Max 4931VA	Max 4998VA	Max 1744VA	Max 3266VA	Max 4787VA	Max 4878VA	Max 4931VA	Max 4998VA
Position detection method	Incremental encoder (wire-saving type) Multi-rotation data backup absolute encoder (wire-saving type)											
Safety circuit configuration	Redundancy not supported						Redundancy supported					
Drive-source cutoff method	Internal cutoff relay						External safety circuit					
Enable input	Contact B input (power supplied internally)						Contact B input (power supplied externally, redundant)					
Speed setting	1 mm/sec ~ (The maximum limit varies depending on the actuator.)											
Acceleration setting	0.01 G ~ (The maximum limit varies depending on the actuator.)											
Program language	Super SEL											
Number of programs	64											
Number of program steps	6,000 (total)											
Number of multi-tasking programs	16											
Number of positions	4,000 (total)											
Data storage device	Flash ROM + SRAM backup battery											
Data input method	Teaching pendant or PC											
Standard I/Os	1 of PIO board with 48 I/O points (NPN/PNP) or PIO board with 96 I/O points (NPN/PNP) can be installed.											
Expansion I/Os	Up to 3 of PIO board with 48 I/O points (NPN/PNP) and/or PIO board with 96 I/O points (NPN/PNP) can be installed.											
Serial communication function	Standard teaching port (D-sub, 25-pin) + 2-channel RS232C port (D-sub, 9-pin x 2)											
Protective functions	Motor overcurrnet, overload, motor/driver temperature check, overload check, encoder open detection, soft limit overtravel, system error, battery error											
Surrounding air temperature/humidity, ambience	0 to 40°C, 10 to 95% (non-condensing); free from corrosive gases or significant dust.											
Weight (*2)	5.2kg					5.7kg	4.5kg					5kg
Accessory	I/O flat cable											

*1 When axes corresponding to the maximum wattage are connected.
*2 Including the absolute battery, brake mechanism and expansion I/O box.

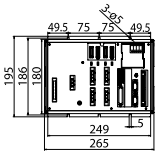
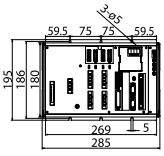
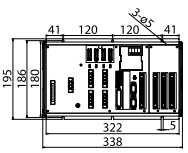
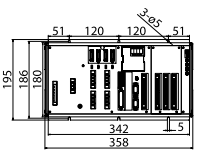
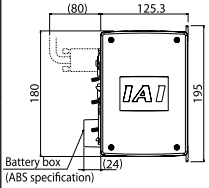
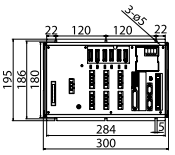
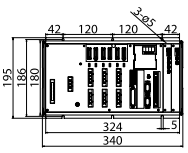
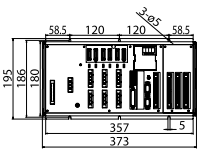
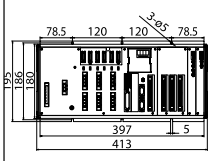
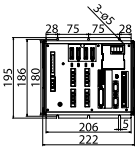
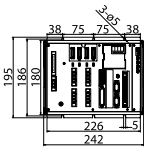
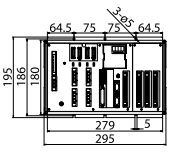
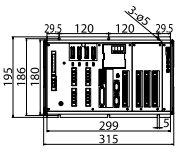
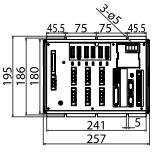
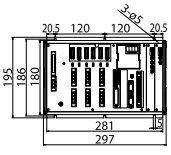
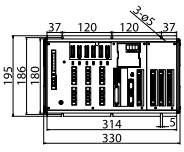
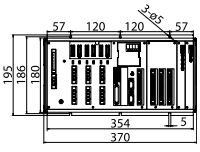
External Dimensions

■ J (Small Type)/K (General-purpose Type)

	1-axis specification	2-axis specification	3/4-axis specification	Side view
J type (Small type)				
	1/2-axis specification		3/4-axis specification	
K type (General-purpose type)				

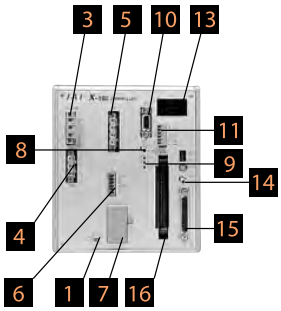
■ P (Large-capacity Standard Type)/Q (Large-capacity Global Type)

The shapes and dimensions of SEL-P/Q types vary depending on the controller specifications (encoder type, with/without brake, and with/without I/O expansion).
The following four shapes are available. Check the applicable dimensions based on the desired type and number of axes to be connected.

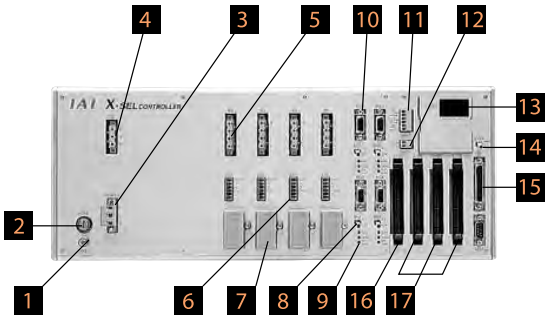
		Base shape (incremental specification)	With brake/absolute unit	With I/O expansion base	With brake/absolute unit + I/O expansion base	Side view
Controller specification	Encoder	Incremental	Absolute	Incremental	Absolute	
	Brake	Not equipped	Equipped	Not equipped	Equipped	
	I/O	Standard only	Standard only	Standard + Expansion	Standard + Expansion	
P type (Large-capacity)	1 to 4-axis specification					
	5 to 6-axis specification					
Q type (Large capacity conforming to safety standard) * The dimensions of single-phase 200-VAC controllers conform to those of the P type.	1 to 4-axis specification					
	5 to 6-axis specification					

Name of Each Part

J Type (Small)



K Type (General-purpose)



1 FG connection terminal

A connection edge to connect the FG terminal of the enclosure.
This terminal is connected to the PE terminal of the AC input part internally through the controller.

2 Fuse holder (K type only)

A half-cut fuse holder for protecting the AC input part from overcurrent.

3 Main-power input connector

A connector for 100/200-VAC single-phase input.
(This connector comes with a cable-end plug. Refer to the right page.)

4 Regenerative-resistor unit connector

This connector is used to connect the regenerative resistor unit (optional: REU-1) that may be required if the built-in regenerative connector is not enough due to high acceleration, high load, etc.

5 Motor cable connector

A connector for the motor power cable of the actuator motor.

6 Actuator-sensor input connector

A connector for the LS, CREEP, OT and other axis sensors.

7 Absolute-data backup battery

A battery unit for backing up the absolute encoder if used.
This battery is not connected to non-absolute axes.

8 Brake release switch (brake specification only)

An alternate switch with lock for releasing the axis brake. To operate this switch, pull the switch toward you and then tilt it to a desired position. Tilt the switch to the top (RLS) position to forcibly release the brake, or tilt it to the bottom (NOM) position to let the controller control the brake automatically.

9 Axis-driver status LEDs

These LEDs are used to monitor the operating status of the driver CPU that controls the motor drive.
The following three LEDs are provided.

Name	Color	Meaning when the LED is lit
ALM	Orange	The driver has detected an error.
SVON	Green	The servo is ON and the motor is being driven.
BATT ALM	Orange	The absolute battery voltage is low.

10 Encoder cable connector

This 15-pin, D-sub connector is used to connect the encoder cable of the actuator.

11 System IO connector

This connector has a total of three I/Os including two inputs for controlling the controller operation and one output regarding the system status.
(This connector comes with a cable-end plug. Refer to the right page.)

Name		
EMG	Emergency stop input	Operation is enabled when this signal is ON. An emergency stop is actuated when the signal turns OFF.
ENB	Safety gate input	Operation is enabled when this signal is ON. The servo turns OFF when the signal turns OFF.
RDY	System ready relay output	The controller status is output. Cascade connection is supported. The controller is ready when the output contacts are shorted and not ready when the contacts are open.

12 IO24V power connector (K type only)

If DI/DOs are installed in the IO slots 16, 17, this connector is used to supply the I/O power to the insulated part externally.

13 Panel window

The 4-digit 7-segment LED display and five LED lamps indicating the system status can be visually checked.

14 Mode switch

An alternate switch with lock for specifying the operation mode of the controller. To operate this switch, pull the switch toward you and then tilt it to a desired position. The top position indicates the MANU (manual operation) mode, while the bottom position indicates the AUTO (auto operation) mode. Teaching operation can only be performed in the MANU mode, and auto operation using external IOs cannot be performed in the MANU mode.

15 Teaching connector

This D-sub, 25-pin connector is used to connect a teaching pendant or PC to input program positions.

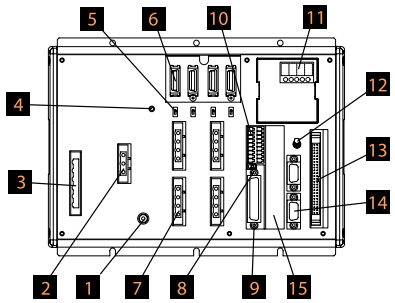
16 Standard I/O slot (slot 1)

The standard PIO board with 32 input points and 16 output points is installed in this slot.

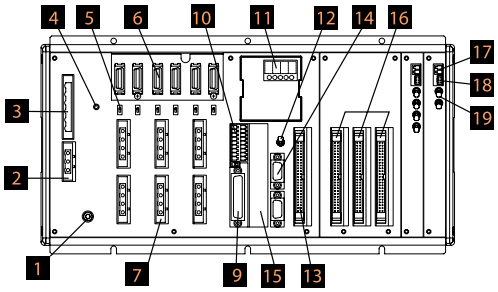
17 Expansion I/O slots (slot 2, slot 3, slot 4)

An expansion IO board (optional) can be installed in each of these slots.

P type (standard, 4-axis)



Q type (with absolute brake unit + expansion base, 6-axis)



1 FG connection terminal

A connection edge to connect the FG terminal of the enclosure. This terminal is connected to the PE terminal of the AC input part internally through the controller.

2 External regeneration unit connector

This connector is used to connect an additional regenerative resistor when the built-in regenerative resistor is not enough due to high acceleration, high load, etc. Whether or not an external regenerative resistor is needed depends on the specifics of the application, such as the axis configuration.

3 AC-power input connector

A connector for 200-VAC three-phase input. This connector consists of six terminals including the motor power-supply, control power-supply and PE terminals.
The standard specification only comes with a terminal block.
Caution To prevent electric shock, do not touch this connector while the power is supplied.

4 Control power-supply monitor LED

A green light is lit while the control power supply is generating the internal controller power properly.

5 Absolute-battery enable/disable switch

This switch is used to enable or disable the encoder backup operation using the absolute battery. The factory setting is to disable the backup. Connect the encoder and axes-sensor cables, turn on the power, and then set this switch to the top position.

6 Encoder/axis-sensor connector

A connector for the actuator encoder and axis sensors such as LS, CREEP and OT.
*: LS, CREEP and OT sensors are optional.

7 Motor connector

A connector for driving the motor in the actuator.

8 Teaching-pendant type selector switch

This switch is used to change the type of the teaching pendant connected to the teaching connector 9. You can switch between IAI's standard teaching pendant and ANSI teaching pendant. Set the switch provided on the front side of the board according to the teaching pendant to be used.

9 Teaching connector

This teaching interface is used to connect IAI's teaching pendant or PC (PC software) to operate, set or otherwise manipulate the system.

10 System I/O connector

This I/O connector controls the safety operations of the controller. With the global specification, this connector can be used, together with an external safety circuit, to configure a safety circuit meeting up to category 4.

11 Panel window

The panel window consists of the 4-digit, 7-segment LED display and five LED lamps indicating the status of the system.

Meanings of 5 LEDs

Name	Condition when the LED is lit
RDY	The CPU is ready (to perform program operation).
ALM	A CPU alarm (system-shutdown level error) or CPU hardware error is present.
EMG	An emergency stop is actuated or CPU hardware error or power-supply hardware error is present.
PSE	A power-supply hardware error is present.
CLK	The system clock is abnormal.

12 Mode switch

An alternate switch with lock for specifying the operation mode of the controller. To operate this switch, pull the switch toward you and then tilt it to a desired position. The top position indicates the MANU (manual operation) mode, while the bottom position indicates the AUTO (auto operation) mode. Teaching operation can only be performed in the MANU mode, and auto operation using external IOs cannot be performed in the MANU mode.

13 Standard I/O connector

Overview of standard IO interface specifications

Item	Photo-coupler
Connector name	I/O
Applicable connector	Flat connector, 50-pins
Power supply	Power is supplied from connector pin Nos. 1 and 50.
Inputs	32 points (including general-purpose and dedicated inputs)
Outputs	16 points (including general-purpose and dedicated outputs)
Connected to	External PLC, sensor, etc.

14 General-purpose RS232C port connector

This port is used to connect general-purpose RS232C devices. (Two channels are provided.)

15 Field-network board slot

A fieldbus interface module is installed in this slot.

16 Expansion I/O boards (optional)

Optional expansion boards are installed in theses slots.

17 Brake-power input connector

A power input connector for driving the brake of the actuator. 24 VDC must be supplied externally. If the specified power is not supplied, the actuator brake cannot be released. Be sure to supply this power to axes with brake. For the brake power cable, use a shielded cable and connect the shield on the 24-V power supply side.

18 Brake-release switch connector

This connector is used to connect a switch that releases the actuator brake from outside the controller. The brake is released when the COM and BKMRL* terminals of this connector are shorted. Use this connector if you want to manually operate the actuator when the controller power is cut off or other abnormality is present.

19 Brake switch

An alternate switch with lock for releasing the axis brake. To operate this switch, pull the switch toward you and then tilt it to a desired position. Tilt the switch to the top (RLS) position to forcibly release the brake, or tilt it to the bottom (NOM) position to let the controller control the brake automatically.

Options

■ Regenerative Resistor Unit

Model **REU-1**

Description

This unit converts to heat the regenerative current produced when the motor decelerates. Although the controller has a built-in regenerative resistor, a regeneration unit or units may be required if its capacity is not enough for the vertical axis load. (Refer to the table on the right.)

Specification

Item	Specification
Dimensions	W34mm×H195mm×D126mm
Weight	0.9kg
Built-in regenerative resistor	220Ω 80W
Accessory	Controller connection cable (model: CB-ST-REU101), 1 m

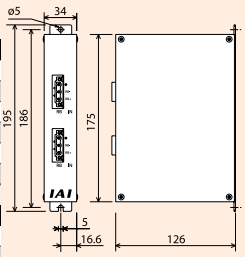
Installation Standards Determine the required number of unit(s) according to the total motor capacity of the connected vertical axes.

Horizontal application

Motor wattage	P/Q type	J type	K type
~200W	Not required	Not required	Not required
~800W	1 unit	Not required	Not required
~1000W	1 unit	–	Not required
~1500W	2 units	–	Not required
~2000W	3 units	–	–
~2400W	4 units	–	–

Vertical application

Motor wattage	P/Q type	J type	K type
~100W	Not required	Not required	Not required
~200W	1 unit	Not required	Not required
~400W	1 unit	1 unit	Not required
~600W	1 unit	1 unit	1 unit
~800W	1 unit	2 units	1 unit
~1200W	2 units	–	2 units
~1600W	3 units	–	Consult IAI.
~2000W	4 units	–	–
~2400W	5 units	–	–



■ Absolute-data Backup Battery (for XSEL-J/K/KE/KT/KET)

Model **IA-XAB-BT**

Features A data backup battery for absolute axes. Replace the battery as soon as the controller generates a battery alarm.

Packing specification

Individually packed. (One battery is required for one axis. Specify an appropriate quantity according to the number of axes to be used.)

■ Absolute-data Backup Battery

Model **AB-5**

Features This absolute-data backup battery is used when absolute actuators are operated.

■ Expansion PIO Board

Description

This optional board is used to add I/Os (inputs/outputs).
On the general-purpose and large-capacity types, up to three expansion PIO boards can be installed in the expansion slots.
(On the small type, only one expansion PIO board can be installed in the expansion slot, provided that the controller is of 3 or 4-axis type.)

■ Expansion SIO Board (for General-purpose Type Only)

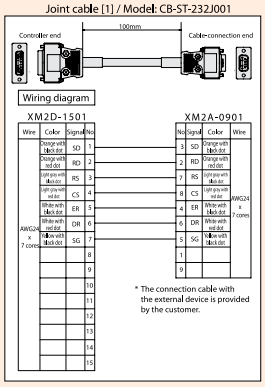
ModelSpecification

IA-105-X-MW-A (for RS232C connection) (board + joint cable [1] x 2)
IA-105-X-MW-B (for RS422 connection) (board + joint cable [2] x 1)
IA-105-X-MW-C (for RS485 connection) (board + joint cable [2] x 1)

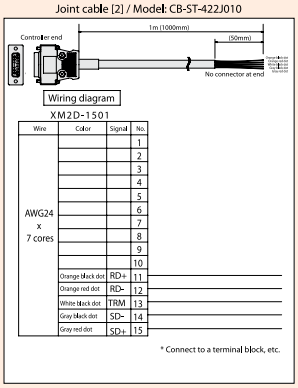
Description

This board is used to perform serial communication with external devices.
The 2-channel port supports three communication patterns according to the supplied joint cable.

Joint cable [1] / Model: CB-ST-232J001



Joint cable [2] / Model: CB-ST-422J010



■ DeviceNet Connection Board

This board is used to connect the XSEL controller to DeviceNet.

Item	Specification			
Number of I/O points	256 input points/256 output points per board * Only one board can be installed.			
Communication protocol	Certified DeviceNet 2.0 interface module (Certification pending)			
	Group 2 only server			
	Insulation node of network-power operation type			
Communication specification	Master-slave connection	Bit strobe		
		Polling		
		Cyclic		
Baud rate	500k/250k/125kbps (Switchable via DIP switches)			
Communication cable length	Baud rate	Maximum network length	Maximum branch length	Total branch length
	500kbps	100m	6m	39m
	250kbps	250m		78m
	125kbps	500m		156m
	Note) When a thick DeviceNet cable is used.			
Communication power supply	24 VDC (supplied from DeviceNet)			
Current consumption of communication power supply	60 mA or more			
Number of occupied stations	1 node			
Connector	MSTBA2.5/5-G.08AUM by Phoenix Contact (*1)			

(*1) The cable-end connector (SMSTB2.5/5-ST-5.08AU by Phoenix Contact) is a standard accessory.

■ CC-Link Connection Board

This board is used to connect the XSEL controller to CC-Link.

Item	Specification					
Number of I/O points	256 input points/256 output points per board * Only one board can be installed.					
Communication protocol	CC-Link Ver1.10 (Certified)					
Baud rate	10M/5M/2.5M/625k/156kbps (switchable via a rotary switch)					
Communication method	Broadcast polling method					
Synchronization method	Frame synchronization method					
Encoding method	NRZI					
Transmission path format	Bus format (conforming to EIA RS485)					
Transmission format	Conforming to HDLC					
Error control method	CRC($X^{16}+X^{12}+X^{5}+X1$)					
Number of occupied stations	1 to 3 stations (remote device stations)					
Communication cable length	Baud rate (bps)	10M	5M	2.5M	625k	156k
	Cable length (m)	100	160	400	900	1200
Connector (controller end)	MSTBA2.5/5-G.08AUM by Phoenix Contact (*1)					

(*1) The cable-end connector (SMSTB2.5/5-ST-5.08AU by Phoenix Contact) is a standard accessory.

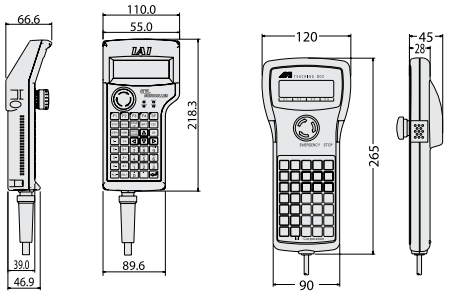
Options

Teaching Pendant

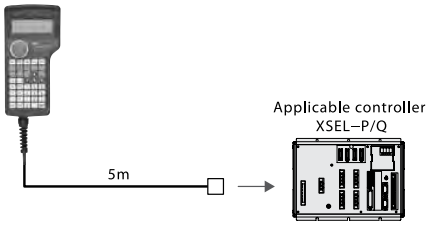
Features A teaching device offering functions for program/position input, test operation, monitoring, and more.

Model/Price

Model	Description
SEL–T	Standard type with connector conversion cable
SEL–TD	Deadman switch type with connector conversion cable



Configuration

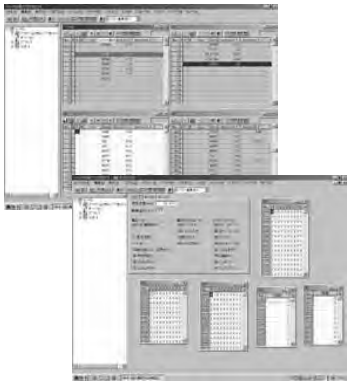


Specification

Item	SEL–T–J	SEL–TD–J
3-position enable switch	Not equipped	Equipped
ANSI/UL standard	Not compliant	Compliant
CE mark	Compliant	
Display	20 characters x 4 lines	
Surrounding air temperature/humidity	0–40°C 10–90%RH (non-condensing)	
Protection structure	IP54	
Weight	Approx. 0.4 kg (excluding cables)	

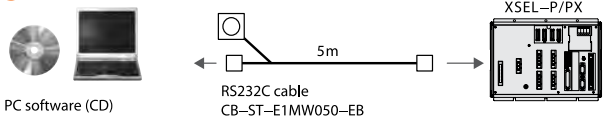
PC Software (Windows only)

Features A software program that assists the initial startup of your system, offering functions for program/position input, test operation, monitoring, and more. The enhanced debugging functions help reduce the startup time.



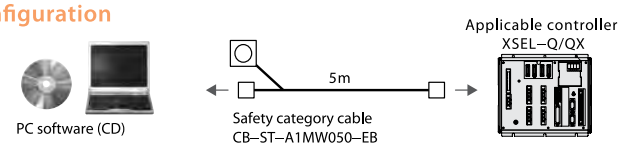
Model **IA–101–X–MW** (with RS232C cable)

Configuration



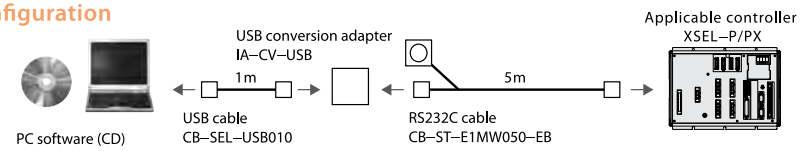
Model **IA–101–XA–MW** (with safety category 4 cable)

Configuration



Model **IA–101–X–USBMW** (with USB conversion adapter + cable)

Configuration



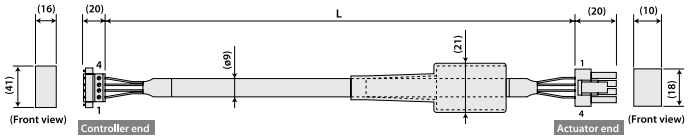
Replacement Parts

If you must order a replacement cable, etc., after the initial purchase of your product, specify the correct model by referring to the information below.

Motor Cable/Robot Motor Cable

Item CB-RCC-MA□□□ / CB-RCC-MA□□□-RB

* □□□ indicates the cable length (L). A desired length up to 20 m can be specified. Example) 080 = 8 m



	Signal	No.
0.75sq	PE	1
	U	2
	V	3
	W	4

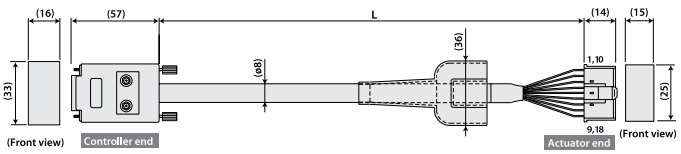
No.	Signal	Wire
1	U	0.75sq (crimped)
2	V	
3	W	
4	PE	

Replacement Parts

Encoder Cable/Robot Encoder Cable (for XSEL-J/K types)

Item CB-RCBC-PA□□□ / CB-RCBC-PA□□□-RB

* □□□ indicates the cable length (L). A desired length up to 15 m can be specified. Example) 080 = 8 m



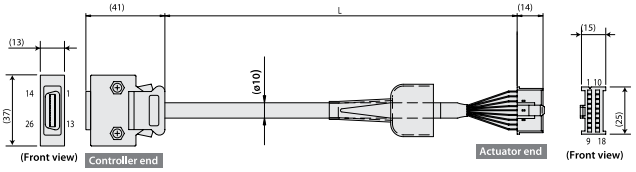
Wire	Signal	No.
0.15sq (Crimped)	A/U	1
	A/U	2
	B/V	3
	B/V	4
	Z/W	5
	Z/W	6
	SD	7
	SD	8
	BAT+	9
	BAT–	10
	VCC	11
	GND	12
	BK–	13
	BK+	14
	—	15
Clamp the shield to the hood.		
Ground wire and shielded braided wires		

No.	Signal	Wire
1	A/U	0.15sq (Crimped)
2	A/U	
3	B/V	
4	B/V	
5	Z/W	
6	Z/W	
7	—	
8	—	
9	FG	
10	SD	
11	SD	
12	BAT+	
13	BAT–	
14	VCC	
15	GND	
16	—	
17	BK–	
18	BK+	

Encoder Cable/Robot Encoder Cable (for XSEL-P/Q types)

Item CB-RCS2-PA□□□ / CB-X3-PA□□□

* □□□ indicates the cable length (L). A desired length up to 20 m can be specified. Example) 080 = 8 m



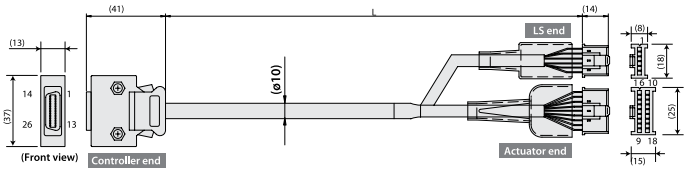
Wire	Color	Signal	No.
AWG26 (soldered)	–	–	10
	–	–	11
	–	E24V	12
	Gray/White	0V	13
	Brown/White	LS	26
	–	CREEP	25
	–	OT	24
	–	RSV	23
	–	–	9
	–	–	18
	–	–	19
	Pink	A+	1
	Purple	A–	2
	White	B+	3
	Blue/Red	B–	4
	Orange/White	Z+	5
	Green/White	Z–	6
	Blue	SRD+	7
	Orange	SRD–	8
	Black	BAT+	14
	Yellow	BAT–	15
	Green	VCC	16
	Brown	GND	17
	Gray	BKR+	20
	Red	BKR–	21
	–	–	22
Connect the shield to the hood via a clamp.			
Ground wire and braided shield wire.			

No.	Signal	Color	Wire
1	A	Pink	AWG26 (Crimped)
2	Ā	Purple	
3	B	White	
4	B̄	Blue/Red	
5	Z	Orange/White	
6	Z	Green/White	
7	LS+	Brown/White	
8	–	–	
9	FG	Ground	
10	SD	Blue	
11	SD	Orange	
12	BAT+	Black	
13	BAT–	Yellow	
14	VCC	Green	
15	GND	Brown	
16	LS–	Gray/White	
17	BK–	Gray	
18	BK+	Red	

Dedicated Encoder Cable/Robot Encoder Cable for Rotary Robots

Item CB-RCS2-PLA□□□ / CB-X2-PLA□□□

* □□□ indicates the cable length (L). A desired length up to 30 m can be specified. Example) 080 = 8 m



Wire	Color	Signal	No.
AWG26 soldered)	–	–	10
	–	–	11
	White/Orange	E24V	12
	White/Green	0V	13
	Brown/Blue	LS	26
	Brown/Yellow	CREEP	25
	Brown/Red	OT	24
	Brown/Black	RSV	23
	–	–	9
	–	–	18
	–	–	19
	White/Blue	A+	1
	White/Yellow	A–	2
	White/Red	B+	3
	White/Black	B–	4
	White/Purple	Z+	5
	White/Gray	Z–	6
	Orange	SRD+	7
	Green	SRD–	8
	Purple	BAT+	14
	Gray	BAT-	15
	Red	VCC	16
	Black	GND	17
	Blue	BKR–	20
	Yellow	BKR+	21
	–	–	22
Connect the shield to the hood via a clamp.			
Ground wire and braided shield wire.			

("White/Blue" and other designations under "Wire color" indicate the band color/insulator color.

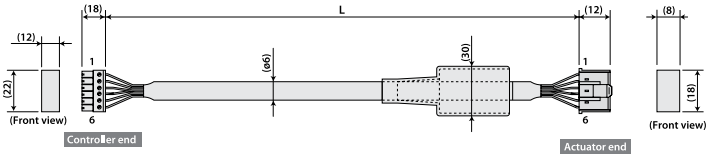
No.	Signal	Color	Wire
1	E24V	White/Blue	AWG26 (Crimped)
2	0V	White/Yellow	
3	LS	White/Red	
4	CREEP	White/Black	
5	OT	White/Purple	
6	RSV	White/Gray	

No.	Signal	Color	Wire
1	A	White/Blue	AWG26 (Crimped)
2	Ā	White/Yellow	
3	B	White/Red	
4	B̄	White/Black	
5	Z	White/Purple	
6	Z̄	White/Gray	
7	–	–	
8	–	–	
9	FG	Drain	
10	SD	Orange	
11	SD	Green	
12	BAT+	Purple	
13	BAT-	Gray	
14	VCC	Red	
15	GND	Black	
16	–	–	
17	BK–	Blue	
18	BK+	Yellow	

Limit Switch Cable (for X-SEL-J/K types)

Item CB-X-LC□□□

* □□□ indicates the cable length (L). A desired length up to 20 m can be specified. Example) 080 = 8 m



Wire	Color	Signal	No.
AWG24	Light blue	24VOUT	6
	Pink	N	5
	Light green	LS	4
	Orange	CREEP	3
	Gray	OT	2
	1B/light blue	RSV	1

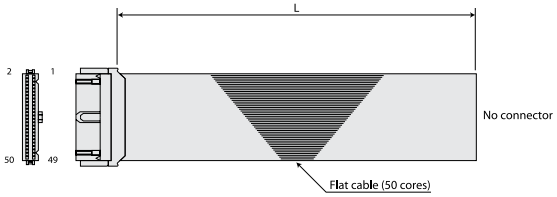
No.	Signal	Color	Wire
1	24VOUT	Light blue	AWG24 (Crimped)
2	N	Pink	
3	LS	Light green	
4	CREEP	Orange	
5	OT	Gray	
6	RSV	1B/light blue	

Note) "1B" indicates one black dot.

I/O Flat Cable (XSEL-J/K/P/Q types)

Item CB-X-PIO□□□

* □□□ indicates the cable length (L). A desired length up to 10 m can be specified. Example) 080 = 8 m



No.	Color	Wire	No.	Color	Wire	No.	Color	Wire
1	Brown 1	Flat cable pressure-welded	18	Gray 2	Flat cable pressure-welded	35	Green 4	Flat cable pressure-welded
2	Red 1		19	White 2		36	Blue 4	
3	Orange 1		20	Black 2		37	Purple 4	
4	Yellow 1		21	Brown-3		38	Gray 4	
5	Green 1		22	Red 3		39	White 4	
6	Blue 1		23	Orange 3		40	Black 4	
7	Purple 1		24	Yellow 3		41	Brown-5	
8	Gray 1		25	Green 3		42	Red 5	
9	White 1		26	Blue 3		43	Orange 5	
10	Black 1		27	Purple 3		44	Yellow 5	
11	Brown-2		28	Gray 3		45	Green 5	
12	Red 2		29	White 3		46	Blue 5	
13	Orange 2		30	Black 3		47	Purple 5	
14	Yellow 2		31	Brown-4		48	Gray 5	
15	Green 2		32	Red 4		49	White 5	
16	Blue 2		33	Orange 4		50	Black 5	
17	Purple 2		34	Yellow 4				

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